



# Neutron reconstruction at tau-charm facilities with Deep Learning

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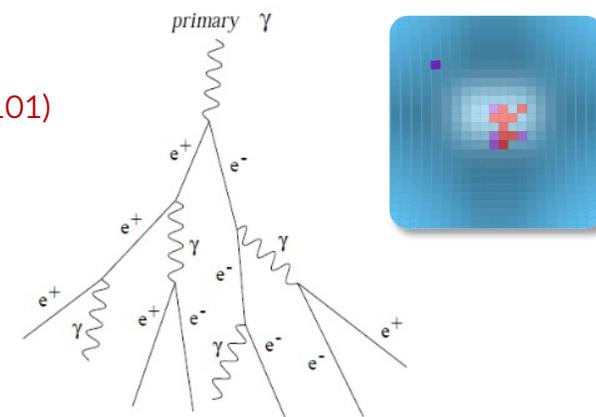
FTCF 2024, Guangzhou

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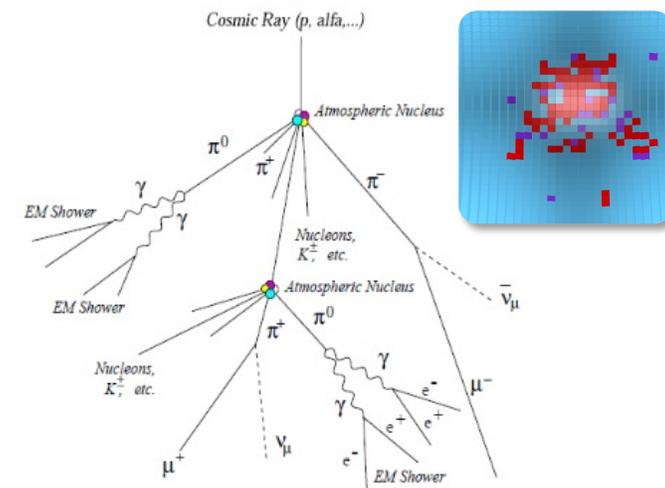


# Introduction

- **Long-lived neutral hadrons ( $n$ ,  $K_L^0$ ) are important probes for physics at  $\tau$ -charm region**
  - e.g., about 1/3 of  $\bar{\Lambda}_c^-$  decays contain  $\bar{n}$  where 20% of them are still unknown (PRD **108**, L031101)
- **However,  $\tau$ -charm facilities have no dedicated hadronic calorimeter**
  - Detection relies on electromagnetic calorimeter (ECAL, EMC)
  - Its size & material prevent full deposition of hadronic showers
- **Direct reconstruction of neutral hadron is very challenging**
  - **Momentum** is unknown
    - Sizable energy leakage
  - **Position** isn't always known
    - Clusters are less centralized than photons
  - **Identification** is not perfect
    - Can be confused with photon / beam background / detector noises
  - **MC simulation** is imprecise
    - Up to ~10% discrepancy from data (NIMA **1033**, 166672)

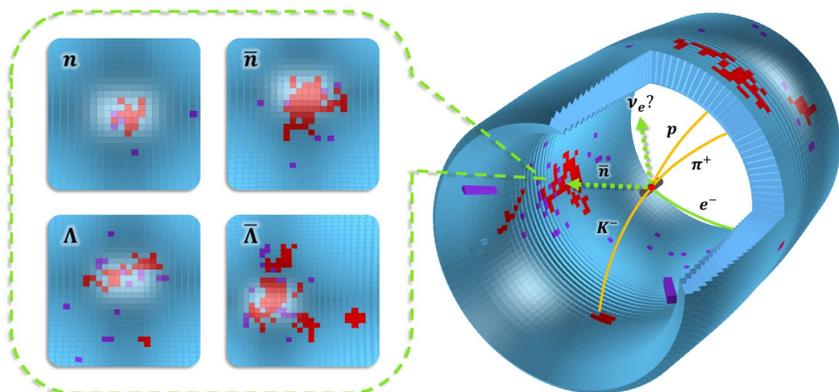


EM shower ( $\uparrow$ ) vs. hadronic shower ( $\downarrow$ )



## Observation of a rare beta decay of the charmed baryon with a Graph Neural Network

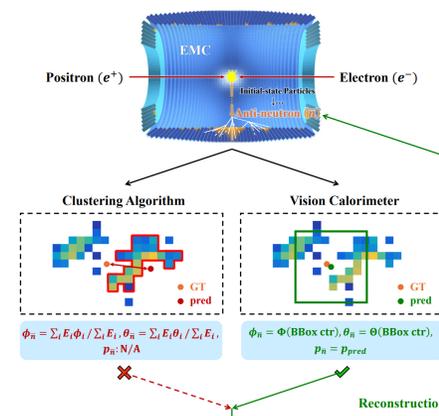
arXiv: [2410.13515](https://arxiv.org/abs/2410.13515), accepted by Nature Commun.



- Practical solution for **neutron identification**
- Enables an important charm study at BESIII

## Vision Calorimeter for Anti-neutron Reconstruction: A Baseline

arXiv: [2408.10599](https://arxiv.org/abs/2408.10599), submitted to AAAI 2025 Conference



- Precise **anti-neutron position measurement**
- First realization of **momentum prediction ability**

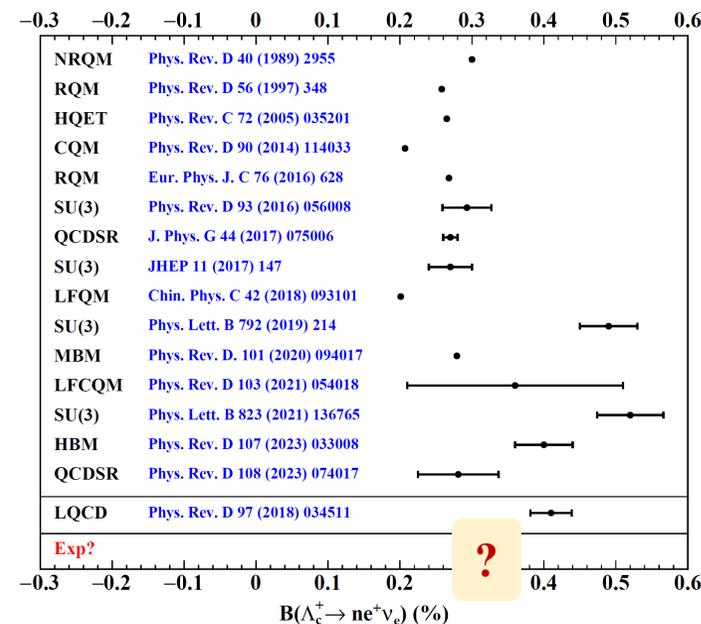
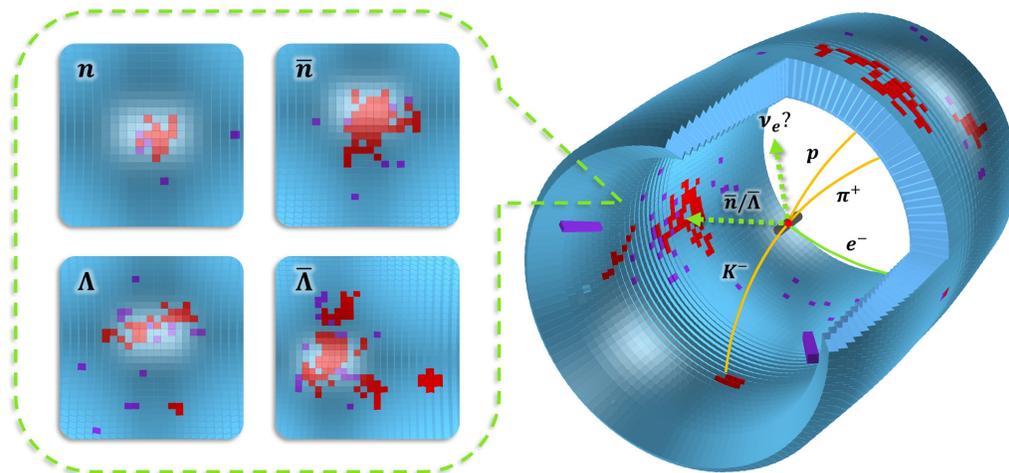
The studies are based on BESIII data, but are also applicable to STCF with similar EMC designs.



# Neutron identification via Graph Neural Network

# Task overview

- The physics goal:** measure  $\Lambda_c^+ \rightarrow ne^+\nu_e$ 
  - The second-most-dominant  $\Lambda_c^+$  semi-leptonic decay is still unobserved
  - Tons of theoretical predictions wait to be confirmed & calibrated
- Experimental challenge**
  - Simultaneous existence of neutron & neutrino
  - Dominant background from  $\Lambda_c^+ \rightarrow \Lambda(n\pi^0)e^+\nu_e$ , yield  $\sim 10\times$  signal
  - Need very powerful tool to identify neutron from photon & noises



Distinction in  $n/\Lambda$  EMC patterns can be seen from eyes.

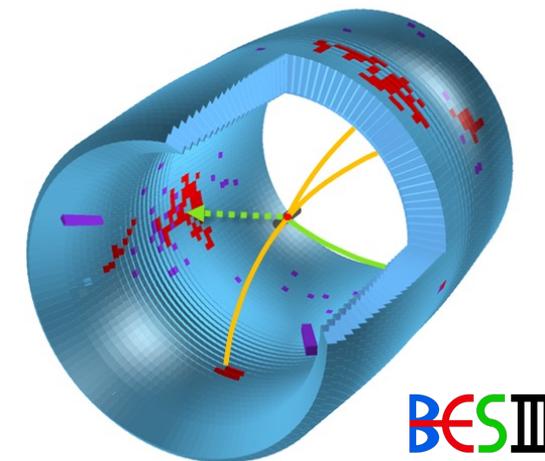
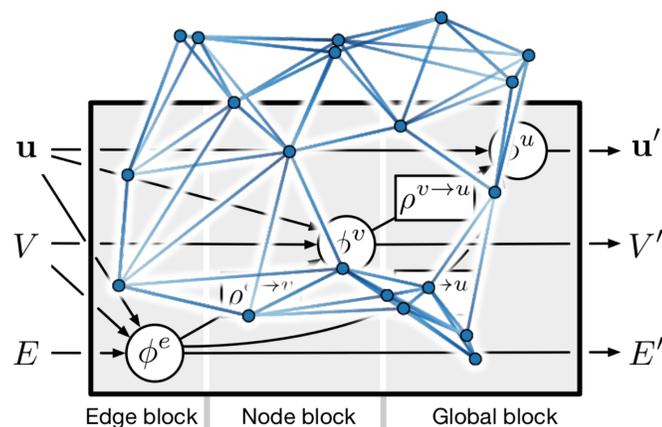
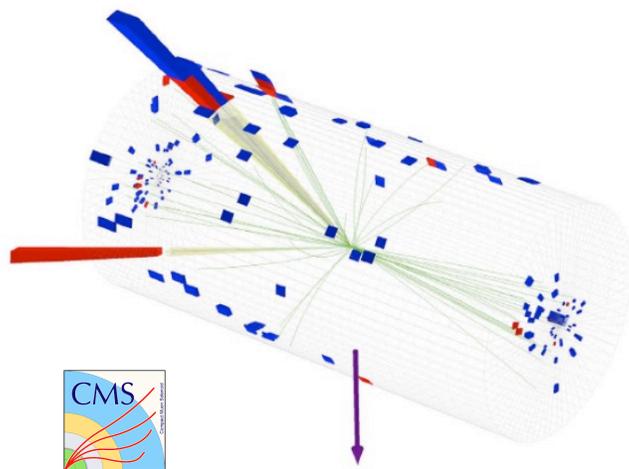
Deep learning may recognize such distinctions in a **smart & flexible way**.



# Why Graph Neural Network (GNN)

● Our task parallels **jet tagging** in LHC experiments at a new energy scale

- EMC cells are in regular grids, but users can only access **reconstructed shower objects**
- The graph-based model **ParticleNet** beats image/sequence-based ones in jet tagging (PRD **101**, 056019)
- GNN can represent more arbitrary relations between data objects as nodes & edges in a graph

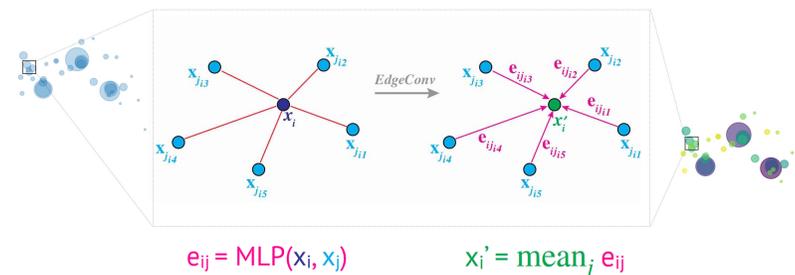


arXiv: 2007.13681

# Our GNN toolkit

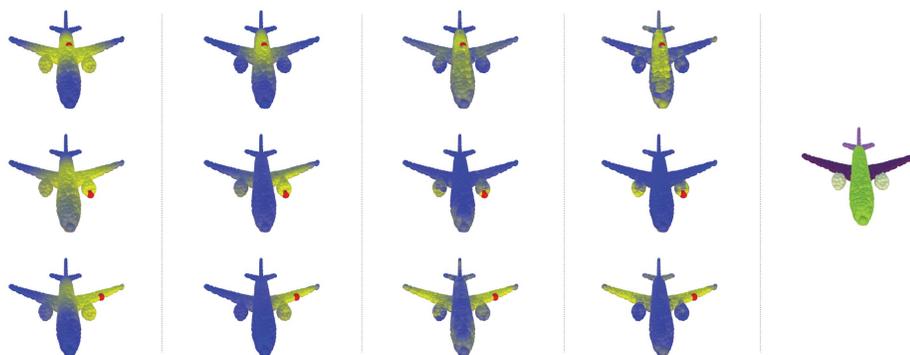
## Event representation – point cloud

- Unordered, permutation-invariant set of particle showers
- Each shower carries spatial coordinates + additional features
  - Energy, time, number of hits, cluster expansion moments...
- Symmetry-preserving, high expressiveness, low computational cost

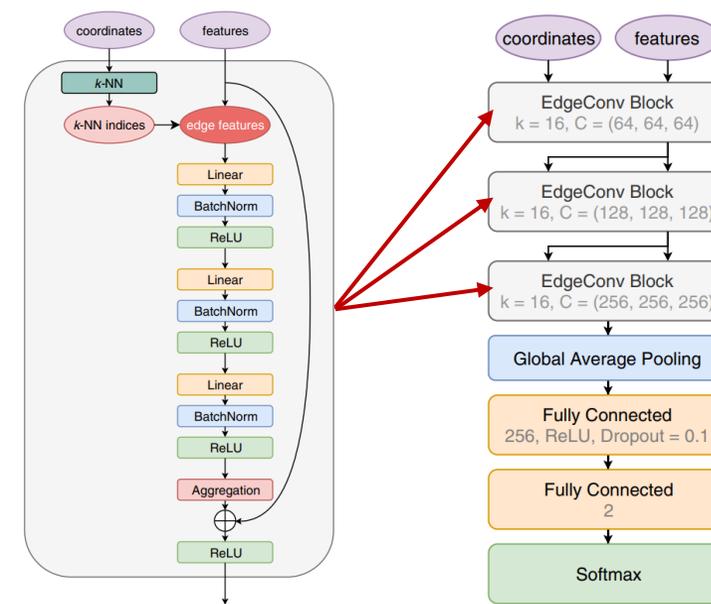


## Model structure – Dynamic Graph CNN (arXiv: 2007.13681)

- Build “edge features” between  $k$ -nearest neighboring points
- Design a symmetric “convolution” function on edges
- Dynamically update the graph after each convolution block



Neighboring in feature space → Neighboring in semantics



# Data-driven analysis pipeline

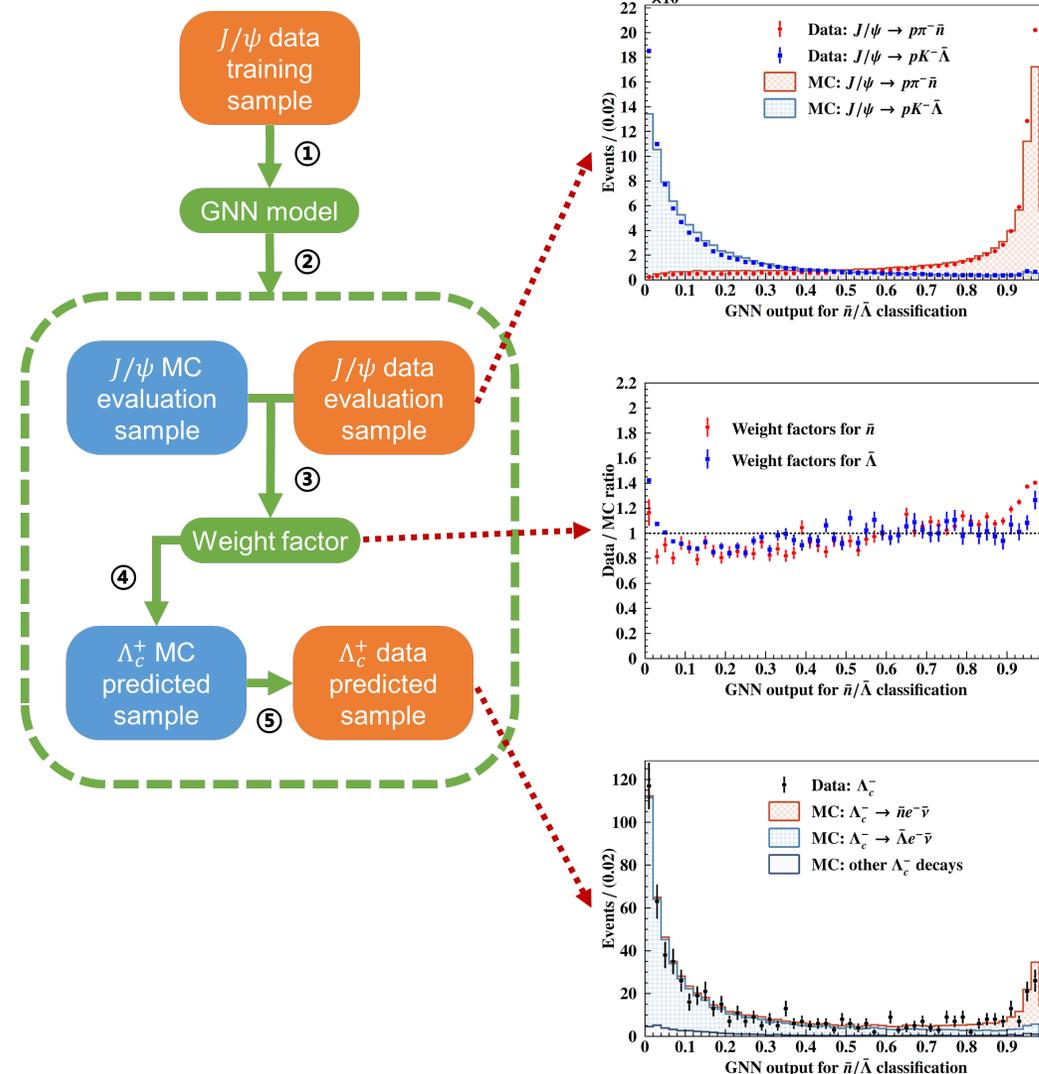
- It's easy to train  $n/\bar{\Lambda}$  classifier with MC samples and apply to data

- But the MC simulation is imprecise!

- Utilize control samples from 10 billion  $J/\psi$  events at BESIII

- Train GNN model with  $J/\psi \rightarrow \bar{p}n\pi^+$  vs.  $\bar{p}\bar{\Lambda}K^+$  events from **real data**
- Use the model to predict  $J/\psi$  data,  $J/\psi$  MC,  $\Lambda_c^+$  data and  $\Lambda_c^+$  MC samples
- Weight the GNN responses** between  $J/\psi$  data & MC
- Correct  $\Lambda_c^+$  MC shape** using bin-by-bin weight factors
- Fit to  $\Lambda_c^+$  data with  $\Lambda_c^+$  MC shapes

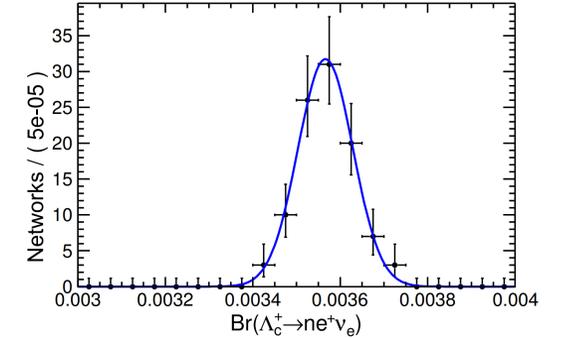
Conjugate channels are treated separately, as anti-neutron may annihilate with EMC while neutron won't



# Quantify ML-related systematic uncertainties

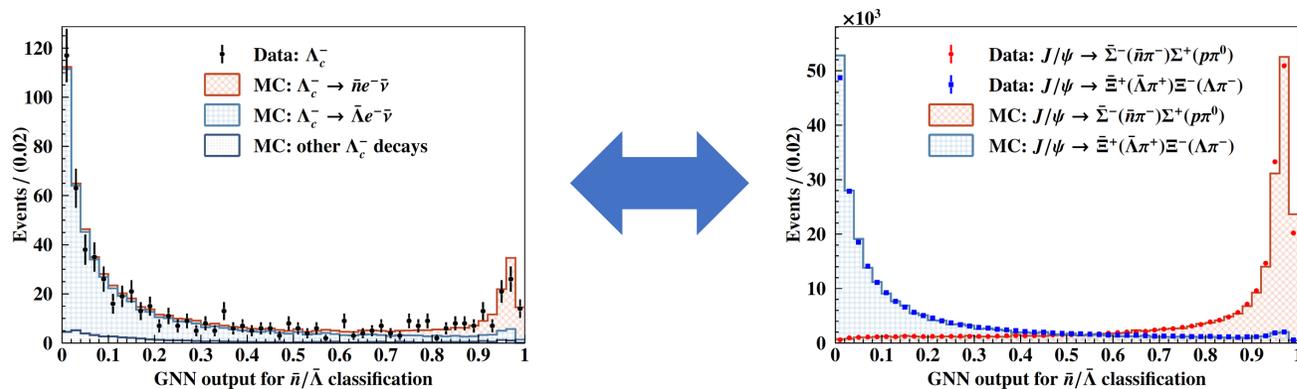
## Model uncertainty

- Lack of knowledge about best model configurations
- Incorporate randomness in training
  - Data processing sequence, network initialization, dropout...
- Ensemble different models in prediction
  - Physics results form a Gaussian distribution

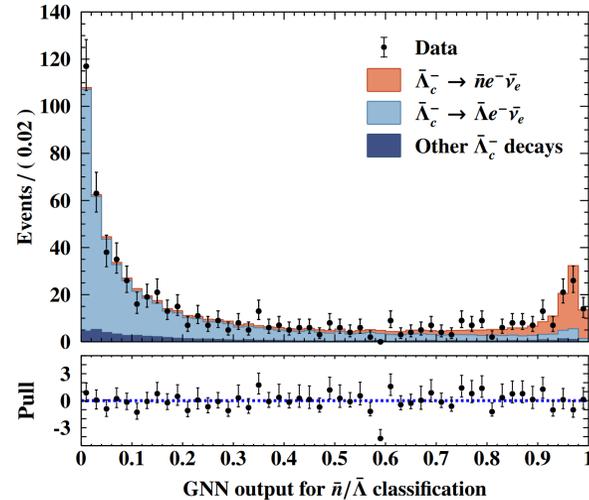
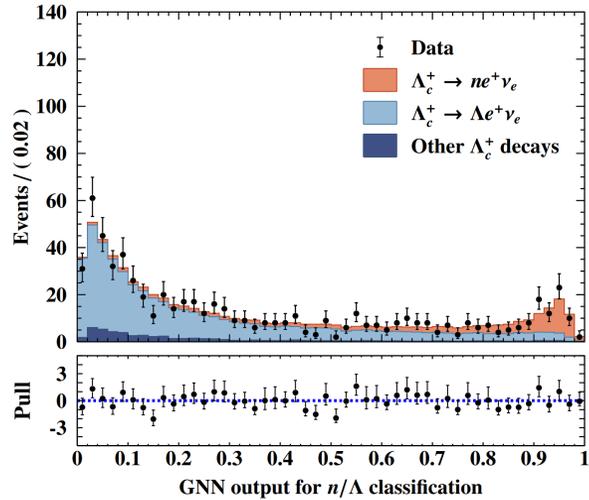


## Domain shift

- Residual diffs between  $J/\psi$  &  $\Lambda_c^+$  datasets (kinematics, BKG environment...)
- Replace  $\Lambda_c^+$  datasets with **another independent control sample**:  $J/\psi \rightarrow \Sigma^+(\mathbf{n}\pi^+)\bar{\Sigma}^-(\bar{p}\pi^0)$  vs.  $J/\psi \rightarrow \Xi^-(\Lambda\pi^-)\bar{\Xi}^+(\bar{\Lambda}\pi^+)$
- Data & MC still well consistent in large statistics after correction



# Physics outcomes



● **First observation of  $\Lambda_c^+ \rightarrow ne^+\nu_e$  with over  $10\sigma$  significance**

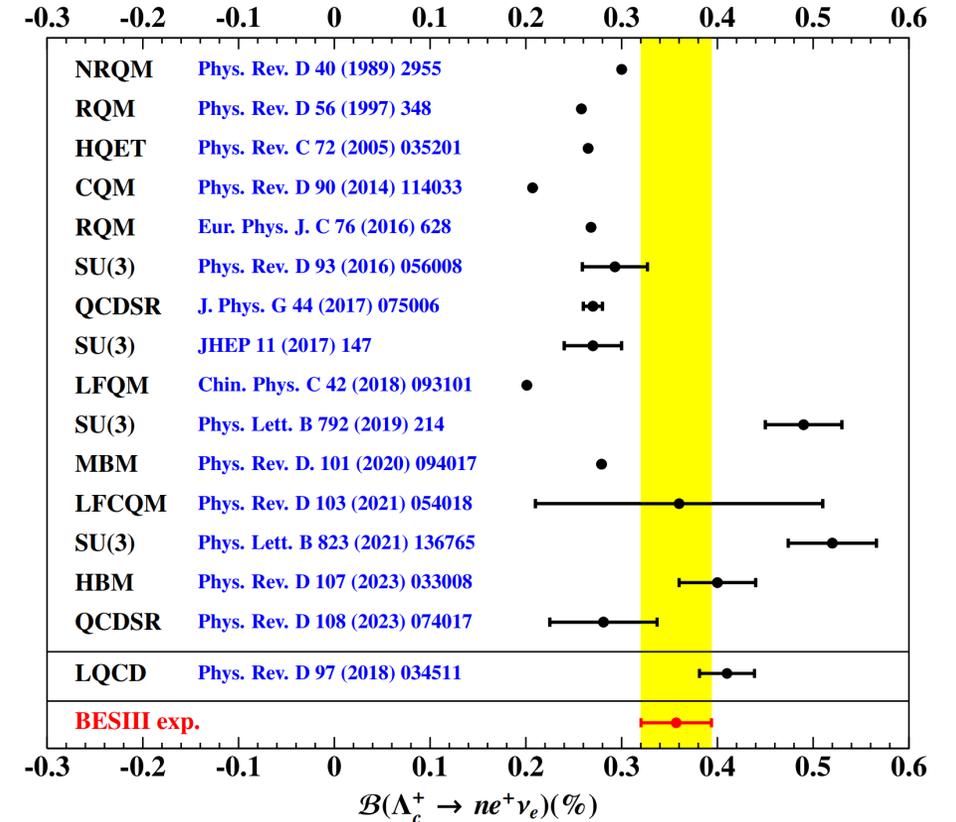
- $B(\Lambda_c^+ \rightarrow ne^+\nu_e) = (0.357 \pm 0.034_{\text{stat.}} \pm 0.014_{\text{syst.}})\%$

● **First measurement of  $|V_{cd}|$  from charmed baryon decays**

- $|V_{cd}| = 0.208 \pm 0.011_{\text{exp.}} \pm 0.007_{\text{LQCD}} \pm 0.001_{\tau(\Lambda_c^+)}$

The study is based on  $4.5 \text{ fb}^{-1}$  data at BESIII.

One-year run at STCF can improve BR and  $|V_{cd}|$  precisions to  $\sim 3\%$  (systematics dominant)



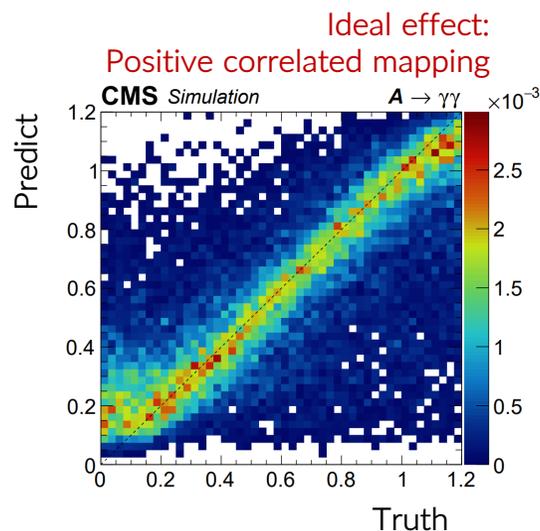
# One step forward

- **Full neutron reconstruction beyond identification is desired.**
  - More meaningful physics results (e.g., form factors) require knowing the neutron momentum
- **We tried predicting neutron momentum with GNN, but failed**
  - A **regression task** that doesn't perfectly fit our toolkit

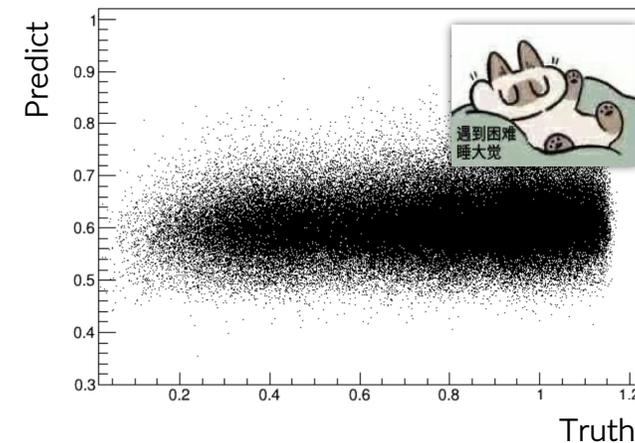


Does the limitation come from detector, or our deep learning technique?

We should **seek help from ML experts.**



Our result:  
Assign all outputs near average  
to yield local minimum for loss function





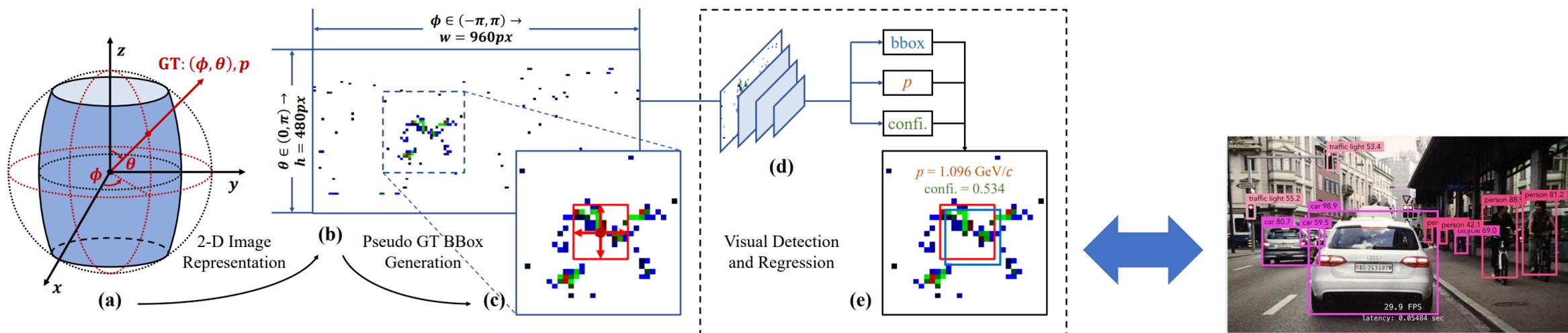
# Anti-neutron reconstruction via *Visual Object Detector*

# Vision Calorimeter (ViC)

## ● An **object detection** approach

- Represent EMC hits on a 2D image
- Find the position of  $\bar{n}$  within a **binding box**
- Determine its confidence score, class and incident momentum

A comprehensive reconstruction with **particle type, position and momentum** measurements.



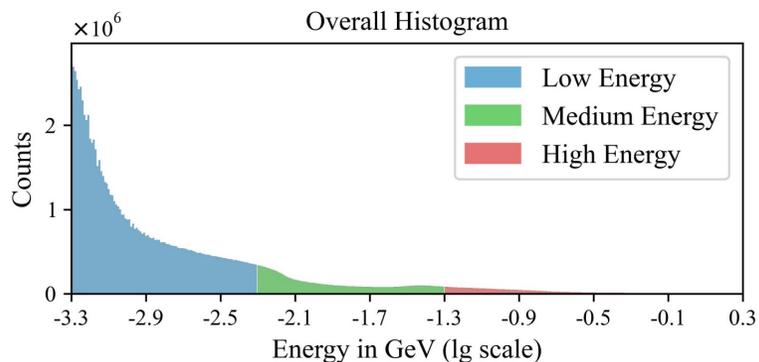
# Image quantification

## ● Pixels

- BESIII barrel EMC has 44 rings × 120 cells, end-cap EMC has 6 rings × [96, 96, 80, 80, 64, 64] cells
- Set image size with 960 × 480 pixels
  - 960 is the least common multiple of (120, 96, 80, 64)
- Define position-varied cell height according to their center positions

## ● Colors

- EMC deposited energy range is 0.5 MeV ~ 2 GeV
- Take log scale:  $[10^{-3.3}, 10^{0.3}]$
- Divide low, medium and high measures to fill blue, green and red channels
- Add a -30db Gaussian noise due to the sparsity of on-fire EMC cells



layers	cells	w (pixels)	h (pixels)	note
2	-	30	8	
2	-	24	8	empty
3	-	20	7	
2	64	15	6	
2	80	12	6	end-cap
2	96	10	5	
1	-	10	5	empty
5	120	8	5	
4	120	8	6	
5	120	8	7	
16	120	8	8	
5	120	8	7	barrel
4	120	8	6	
5	120	8	5	
1	-	10	5	empty
2	96	10	5	
2	80	12	6	end-cap
2	64	15	6	
3	-	20	7	
2	-	24	8	empty
2	-	30	8	

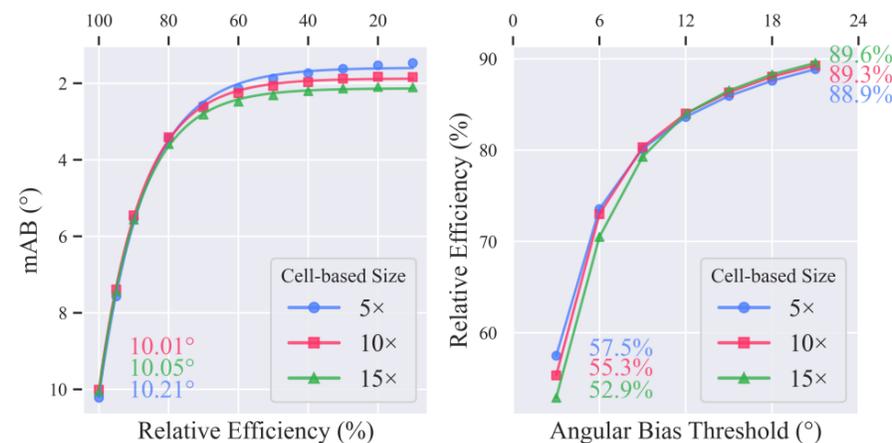
# Bounding box generation

## Why not just make point-wise position prediction?

- Bounding box (BBox) prediction can better exploit contextual information
- Superior performance in afterward tests
- Need to **generate pseudo BBox** around  $\bar{n}$  incident position

## Choice of BBox width

- Smaller size  $\rightarrow$  higher precision upper limit
- Larger size  $\rightarrow$  more available contextual information
- Best performance at **10x cell-based size**



The performance of incident position prediction with different pseudo GT BBox sizes. **Left:** mAB at different relative efficiency levels; **Right:** relative efficiency with different angular bias thresholds.

# Network configuration

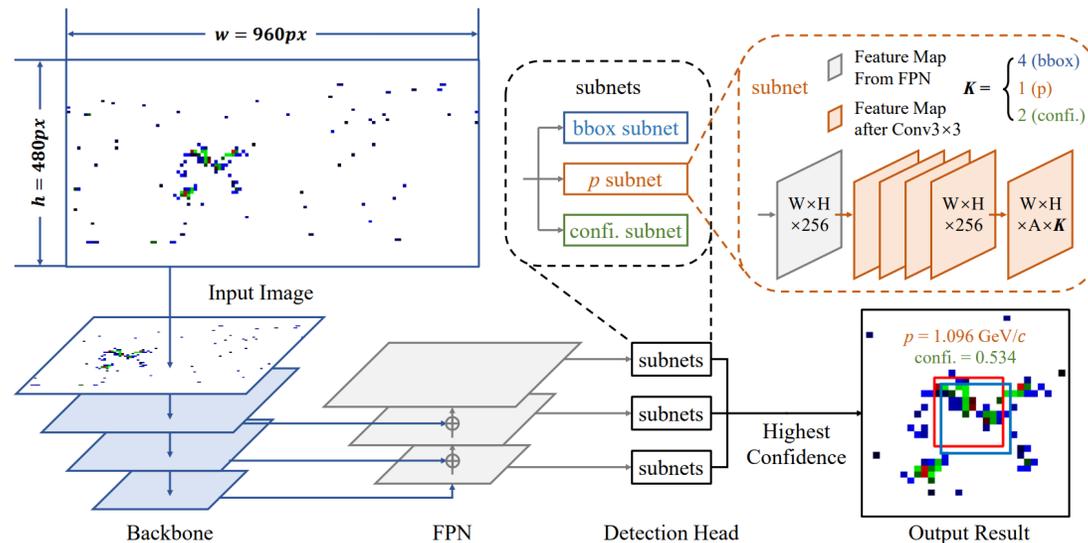
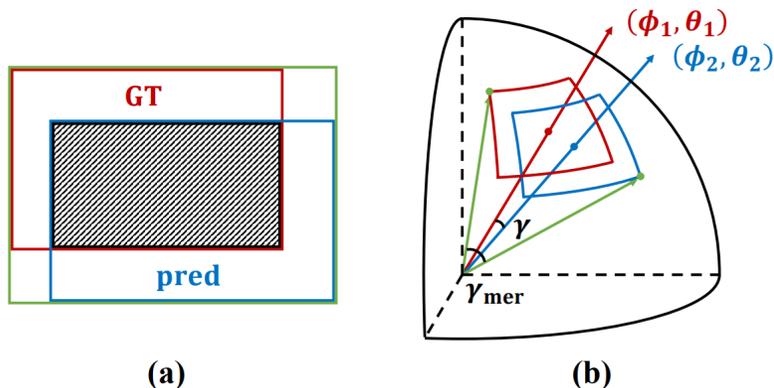
## Architecture

- Backbone: [Swin-Transformer](#) pre-trained on ImageNet
- Detection head: [RetinaNet](#)

## Loss function

- Conventional choice in object detection is **IOU**
  - $IOU = S(GT \cap Pred) / S(GT \cup Pred)$
- We design a more **center-oriented** version

$$\mathcal{L}_{CO} = 1 - IoU + \alpha \cdot \frac{(\cos \gamma - 1)^2}{(\cos \gamma_{mer} - 1)^2}$$



# Performance of ViC (I)

## Dataset

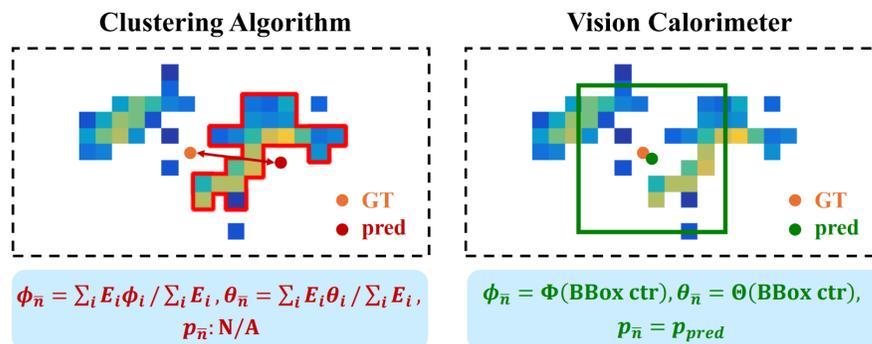
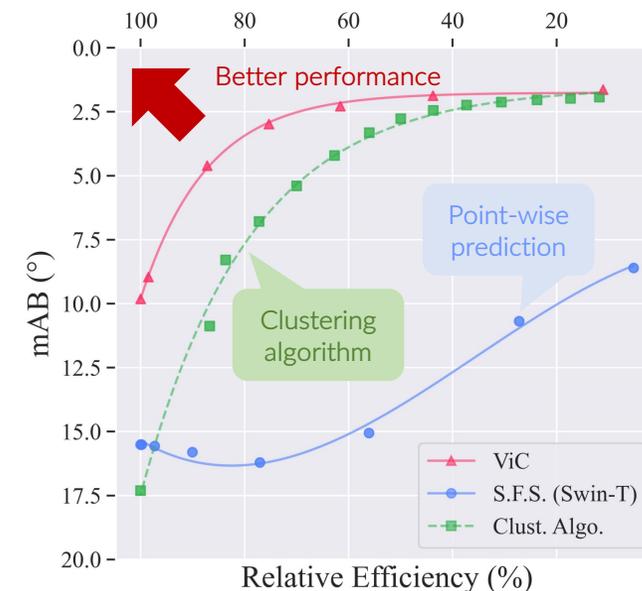
- 1 million  $J/\psi \rightarrow p\bar{n}\pi^-$  events taken from BESIII data
- Plan to extend to 10 million events

## In position measurement

- Compared with conventional clustering algorithm, ViC **improves the precision by 75%** at full efficiency
  - From  $17.4^\circ$  to  $9.9^\circ$
- ViC can **double this precision at 90% efficiency**
  - A near-practical performance of  $5^\circ$

## How comes the improvement?

- Conventional clustering algorithm would **split** a discontinues hadronic shower
  - Usually caused by multiple scattering
  - Only the most energetic one is considered
- ViC can better handle such scenarios



# Performance of ViC (II)

## ● In momentum measurement

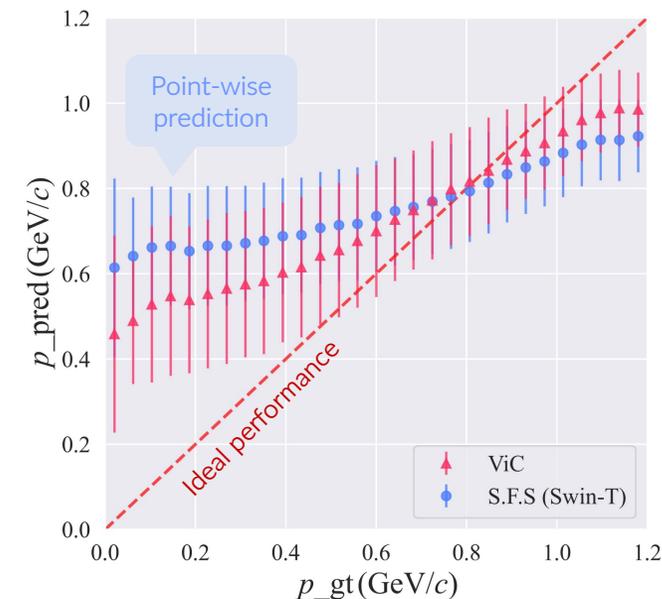
- No conventional methods so far
- ViC firstly realize such capability in EMC
- **Resolution ~25% in sub-GeV region**
  - Even better than dedicated HCALs in this region ( $\sim 80\%/\sqrt{E}$ ) ?!

## ● In classification

- ViC is capable to identify  $\bar{n}$  &  $\bar{\Lambda}$  (though not optimized)
- Position & momentum measurements also **compatible for  $\bar{\Lambda}$  case**

Reconstruction performance of  $\bar{n}$  and  $\bar{\Lambda}$ . † indicates that the corresponding correlation value is not an average but is recalculated across all testing samples.

		↓ mAB (°)	↓ mAE (GeV/c)	↓ mRE (%)	↑ Corr.	↑ Acc. (%)
S.F.S.	$\bar{n}$	16.34	0.1546	28.17	0.5733	95.38
	$\bar{\Lambda}$	20.15	0.1421	36.93	0.5389	54.04
	avg.	18.24	0.1483	32.55	0.6390†	74.71
ViC	$\bar{n}$	10.16	0.1414	25.52	0.6365	93.14
	$\bar{\Lambda}$	15.10	0.1285	33.60	0.5469	73.82
	avg.	<b>12.63</b>	<b>0.1349</b>	<b>29.56</b>	<b>0.6785†</b>	<b>83.48</b>



ViC shows potential to develop an **universal** neutral hadron reconstruction algorithm!



# Summary & outlook

- **Neutral hadron reconstruction is challenging at  $\tau$ -charm facilities.**
  - Information recorded in detector is rare & sparse
- **Deep learning could be a key to fully exploit such information.**
  - A practical solution for neutron identification with Graph Neural Network
  - A baseline model for anti-neutron reconstruction with Visual Object Detector
- **Prospects in STCF**
  - EMC maintains BESIII spec but with faster time response
    - Allow identification & momentum measurement via **time-of-flight method**
      - **300 ps time resolution can offer  $3\sigma$   $n/\gamma$  separation & 8% momentum precision for a neutron @ 1 GeV/c**
  - MUD serves as auxiliary detector for neutral hadron

More data & more information is always welcomed for deep learning.

**Thanks for your attention!**