



SHANDONG
UNIVERSITY



前沿交叉科学青岛研究院
INSTITUTE OF FRONTIER AND INTERDISCIPLINARY SCIENCE

MDC track reconstruction algorithm based on machine learning

Xiaoqian Jia¹, Xiaoshuai Qin¹, Teng Li¹, Xingtao Huang¹,
Xueyao Zhang¹, Yao Zhang² and Ye Yuan²

1. Shandong University, Qingdao

2. Institute of High Energy Physics, Beijing

FTCF, 2024, Guangzhou





Outline

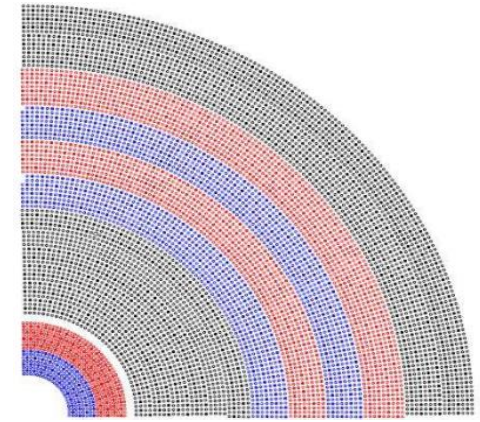
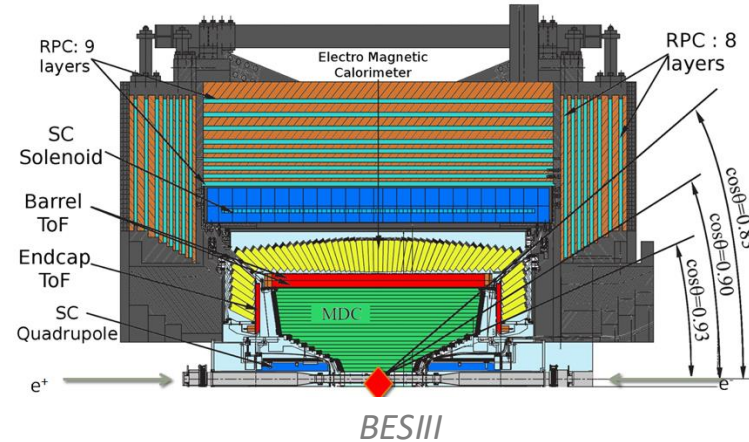
- BESIII and STCF
- Methodology
 - Filtering Noise via GNN
 - Clustering of Tracks Based on DBSCAN and RANSAC
- Preliminary Results
- Summary

Beijing electron-positron collider (BEPCII)

- Peak luminosity : $10^{33} \text{ cm}^{-2} \text{ s}^{-1}$
- CMS: 2.0 - 4.95 GeV, τ -charm region
- World's largest J/ψ dataset : 10 billion

◆ Main Drift Chamber (MDC) at BESIII

- 43 sense wire layers
- 5 axial wire super-layers, 6 stereo wire super-layers
- dE/dx resolution : 6%
- Momentum resolution : 0.5% @ 1 GeV/c



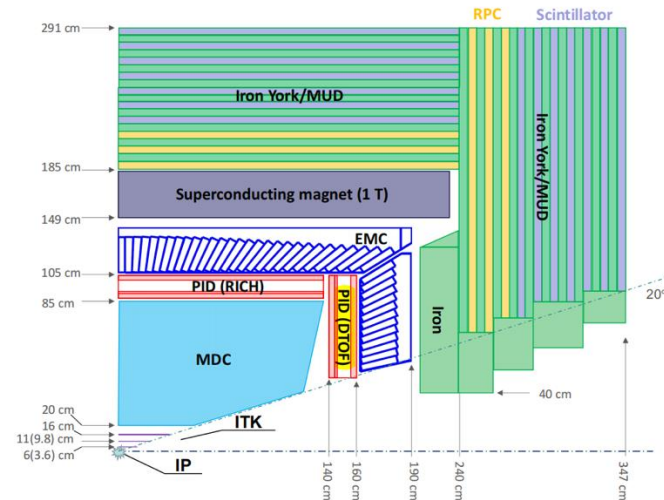
BESIII MDC

Super Tau-Charm Facility (STCF)

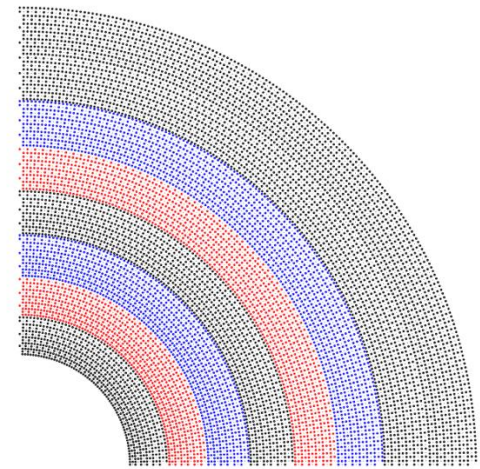
- High Luminosity: $> 0.5 \times 10^{35} \text{ cm}^{-2} \text{ s}^{-1}$ @ 4 GeV
- CMS: 2.0 - 7 GeV

◆ Main Drift Chamber (MDC) at STCF

- 48 sense wire layers
- 4 axial wire super-layers, 4 stereo wire super-layers
- dE/dx resolution : ~6%
- Momentum resolution : 0.5% @ 1 GeV/c



STCF



STCF MDC

Tracking at BESIII and STCF



◆ Track finding

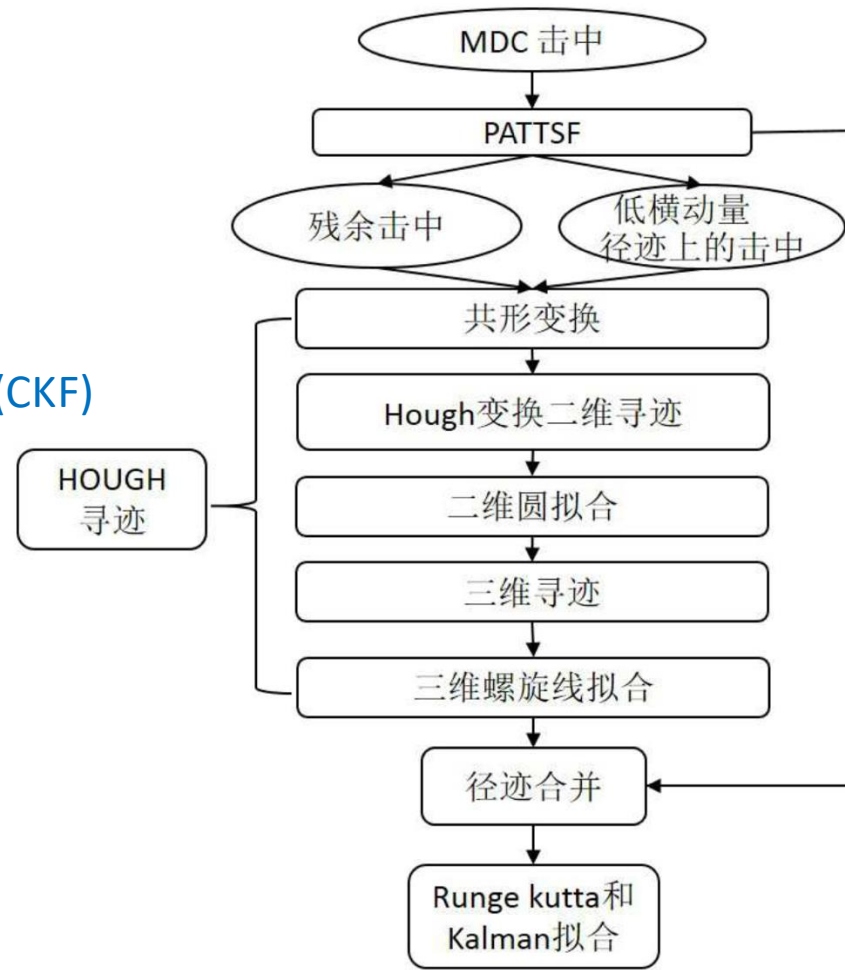
- Global approach : Hough Transform (HOUGH)
- Local approach : Pattern Matching (PAT)

Track Segment Finding (TSF)

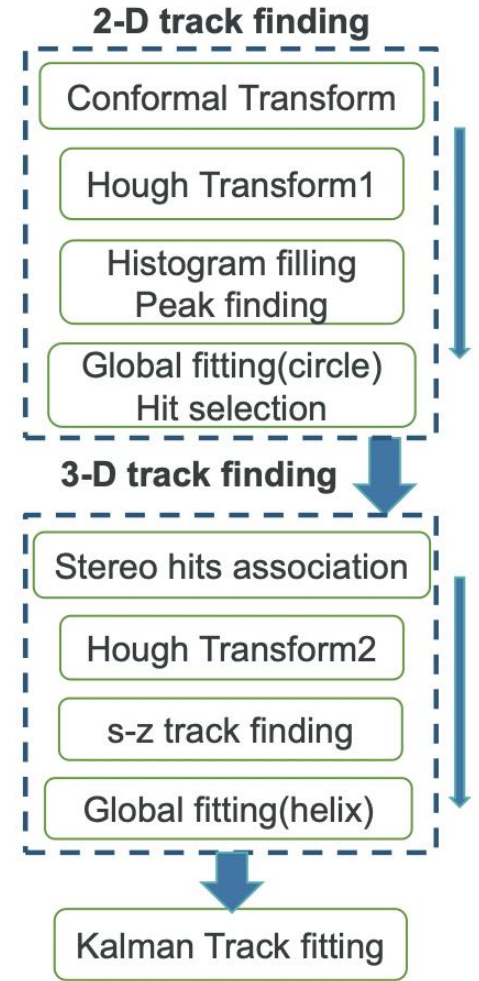
Combinatorial Kalman Filter (CKF)

◆ Track fitting

- Global fit : Least Square Method
Runge-Kutta Method
- Recursive fit : Kalman filter

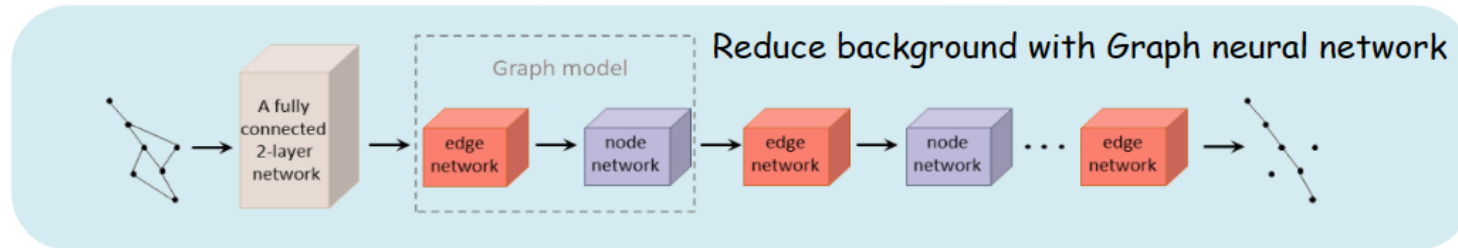
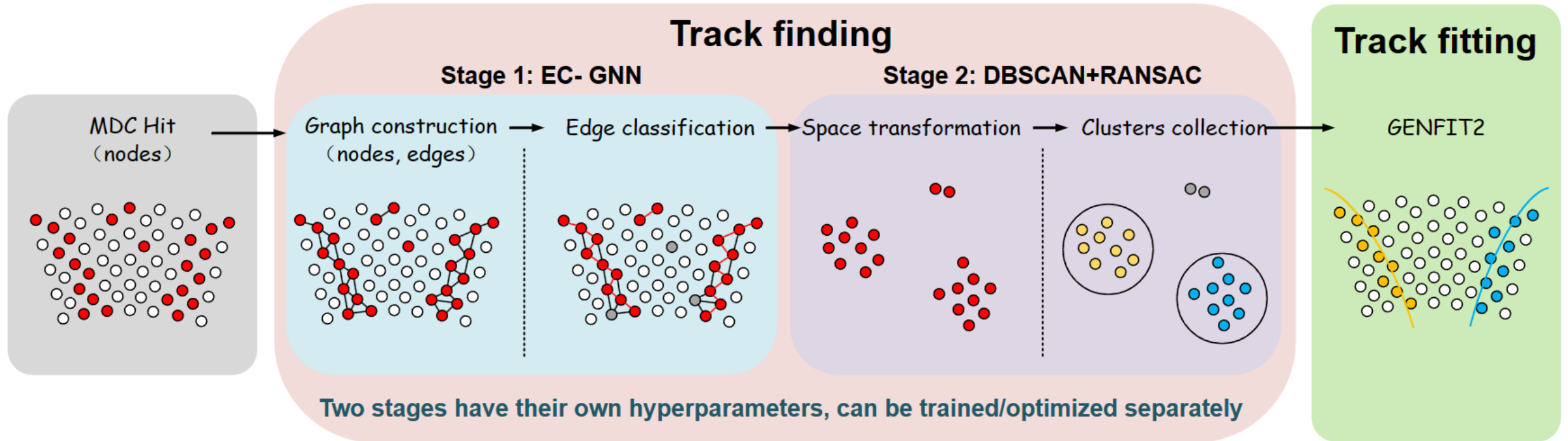


BESIII Tracking



STCF Tracking

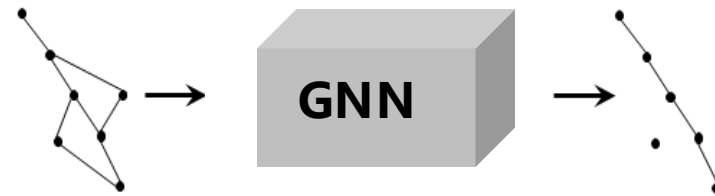
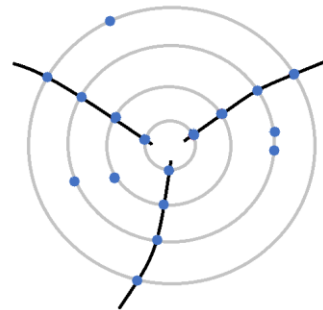
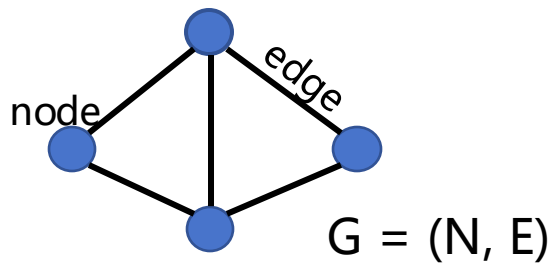
Methodology: GNN based tracking pipeline



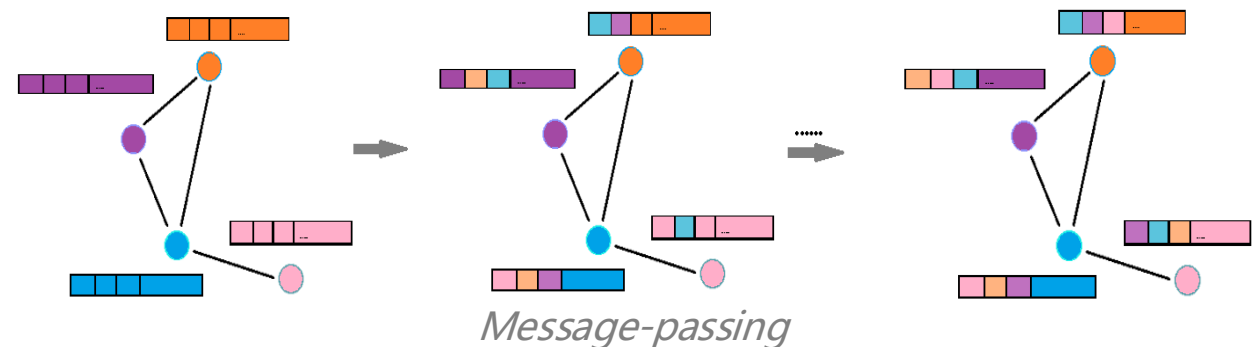
Graph and Graph Neural Network



- ◆ A type of neural network that are specifically designed to operate on graph-structured data
- ◆ Graph: nodes, edges
- ◆ Graph \rightarrow Track
 - Nodes \rightarrow Hits
 - edges \rightarrow track segments
- ◆ GNN key idea: propagate information across the graph using a set of learnable functions that operate on node and edge features



- ◆ Graph Neural Network edge classifier
 - High classification score
 \rightarrow *the edge belongs to a true particle track*
 - Low classification score
 \rightarrow *it is a spurious or noise edge*



To reduce the number of fake edges during graph construction

Pattern Map based on MC simulation at BESIII

◆ Definition of valid neighbors

- Hits on the same layer
 - Two adjacent sense wires on the left and right
- Hits on the next layer

The collection of sense wires that could potentially represent **two successive hits on a track**

◆ MC sample used to build pattern map

- Two million single tracks produced with BESIII offline software (BOSS)
- 5 types of charged particles (e^\pm , K^\pm , μ^\pm , p^\pm , π^\pm)
- $0.05 \text{ GeV}/c < P < 3 \text{ GeV}/c$

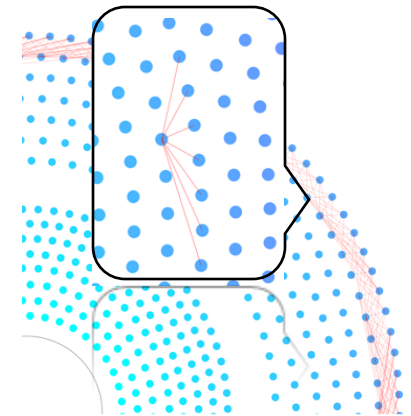
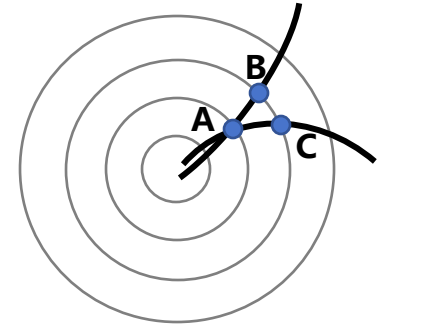
◆ Edge assignment based on Pattern Map

- Hit with its neighbors on the **same layer** and **next layer**
- Hit with its neighbors' neighbors on **one layer apart**

◆ To reduce the size of the graphs, the Pattern Map is further reduced based on **a probability cut**

◆ Graph representation

- Node features (raw time, position coordinates r , ϕ of the sense wires), adjacency matrices, edge labels



A wire on layer13 and its neighbors on layer14

Geometric cut at STCF

◆ Edge assignment

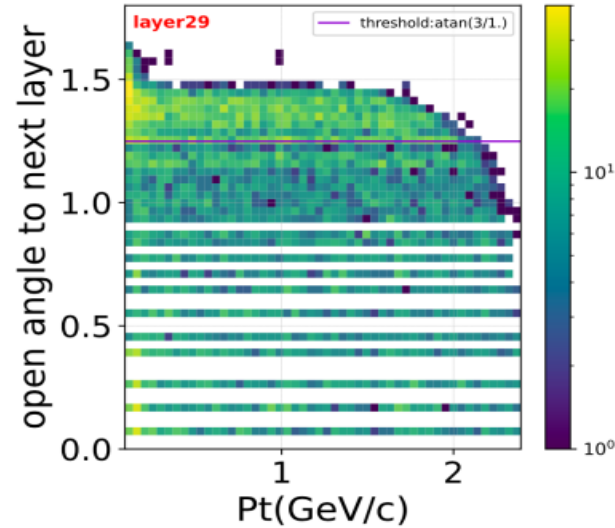
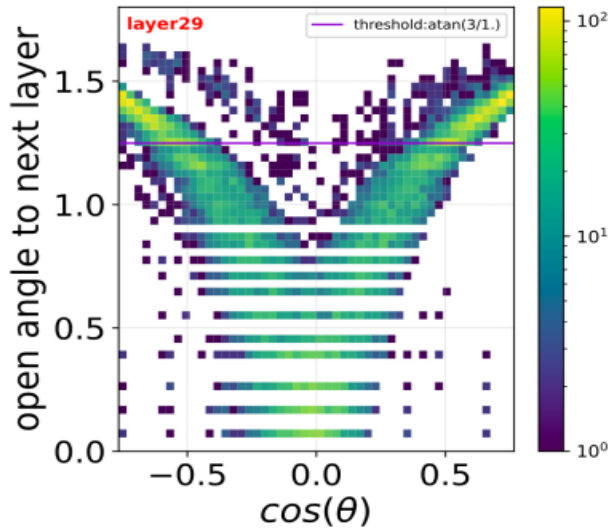
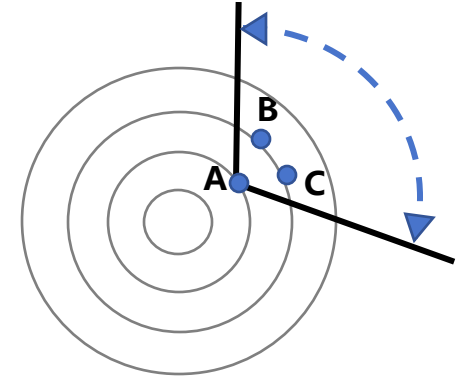
- Hit and two adjacent hits on the left and right sides (same layer)
- Within a certain opening angle (the next layer and one layer apart)

◆ Angle range

- No sense wire efficiency
- The junction of U-V superlayers (layers 11 and 29) appropriately amplify the threshold

◆ Graph representation

- Node features (raw time, position coordinates r , ϕ of the sense wires), adjacency matrices, edge labels



GNN edge classifier based on PyTorch



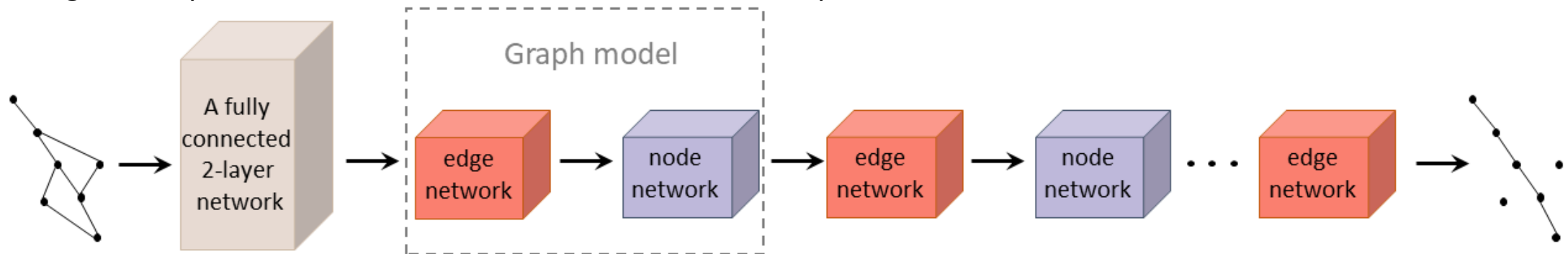
◆ Input network

- Node features embedded in latent space

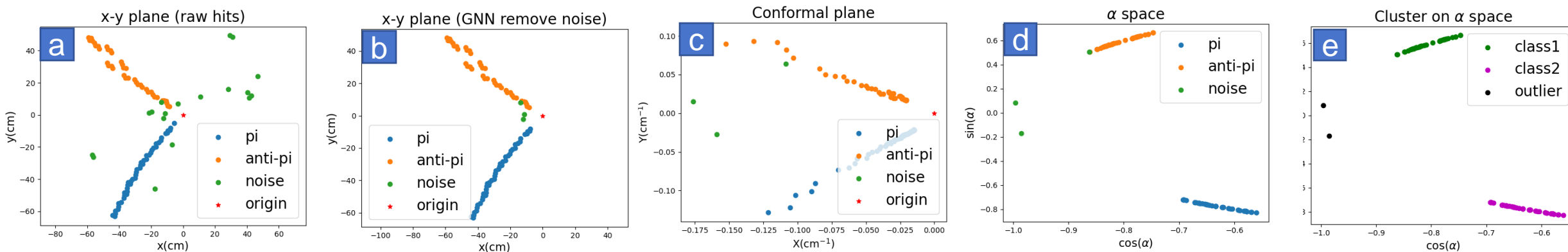
◆ Graph model

- Edge network computes **weights for edges** using the features of the start and end nodes
- Node network computes **new node features** using the edge weight aggregated features s of the connected nodes and the nodes' current features
- MLPs
- 8 graph iterations

◆ Strengthen important connections and weaken useless or spurious ones



Clustering based on DBSCAN



a) Original MC data sample

- $J/\psi \rightarrow \rho^0 \pi^0 \rightarrow \gamma \gamma \pi^+ \pi^-$
- π^+, π^- : Pt (0.2GeV - 1.4GeV)

b) Remove noise via GNN

c) Transform to Conformal plane

- $X = \frac{2x}{x^2+y^2} \quad Y = \frac{2y}{x^2+y^2}$
- Circle passing the origin transform into a straight line

d) Transform to ' α ' parameter plane

- Hits connected in the X-Y plane in a straight line
- α as the angle between the straight line and X axis
- The parameter space as $\cos\alpha$ and $\sin\alpha$

e) DBSCAN clustering in ' α ' parameter plane

- Density-Based Spatial Clustering of Application with Noise
- Hits in a cluster are considered to be in the same track

Clustering salvage algorithm RANSAC

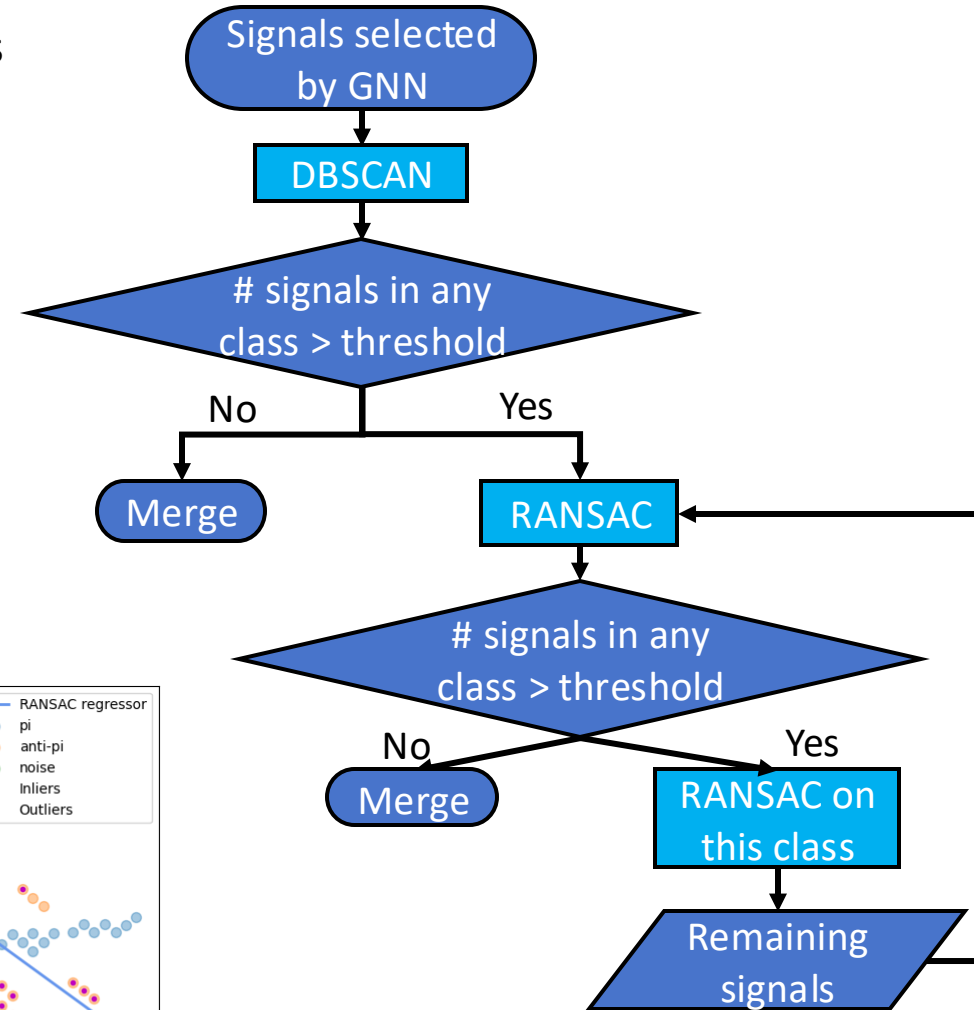
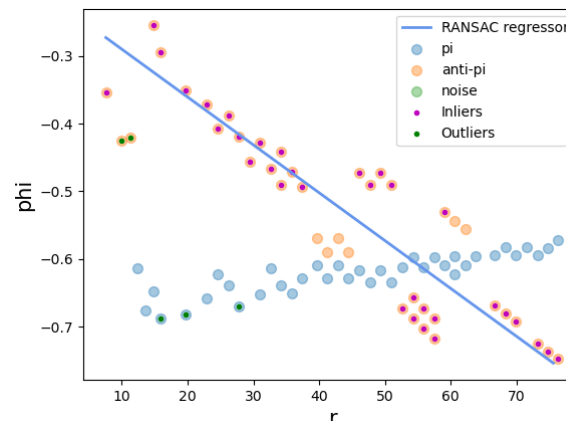
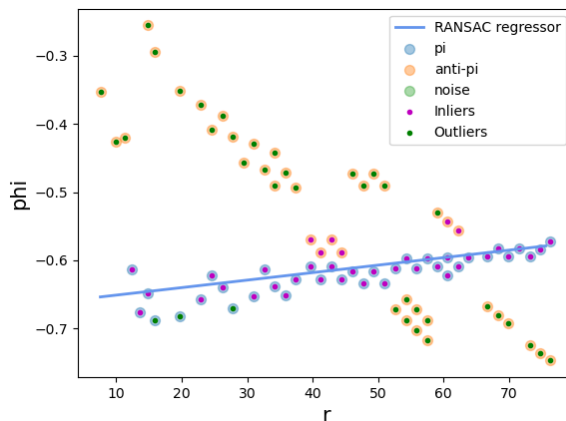


◆ Random sample consensus (RANSAC)

- Estimate a mathematical model from the data that contains outliers
- Its good robustness to noise and outliers
- Model can be specified

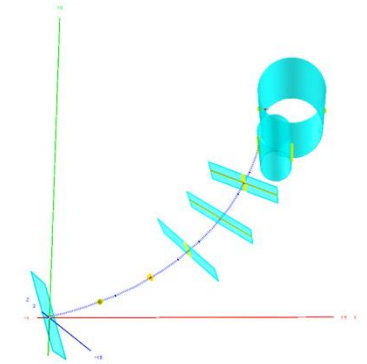
◆ RANSAC is triggered by the events that DBSCAN processing fails

- Polar coordinate space
- linear model
- Inliers \rightarrow a track , outliers \rightarrow other tracks
- Stop condition: outliers $<$ threshold



Genfit2

- A Generic Track-Fitting Toolkit
 - Experiment-independent framework
 - PANDA, Belle II, FOPI and other experiments
 - Deterministic annealing filter (DAF) to resolving the left-right ambiguities of wire measurements
- ◆ Configuration: Detector geometry and materials
 - ◆ Input : Signal wire position, initial values of position and momentum, particle hypothesis for e , μ , π , k , p
 - ◆ Fitting procedure:
 - Start 1st try: drift distance roughly estimated from TDC、ADC of sense wires
 - Iteration to update information of drift distance, left-right assignment, hit position on z direction and entrancing angle in the cell et al.



Performance of filtering noise at BESIII



◆ Dataset

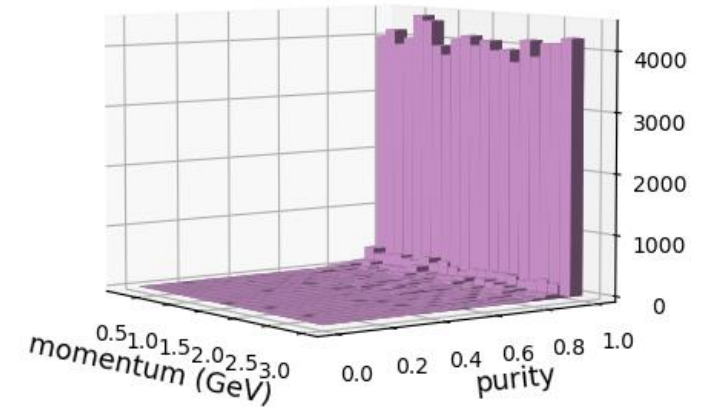
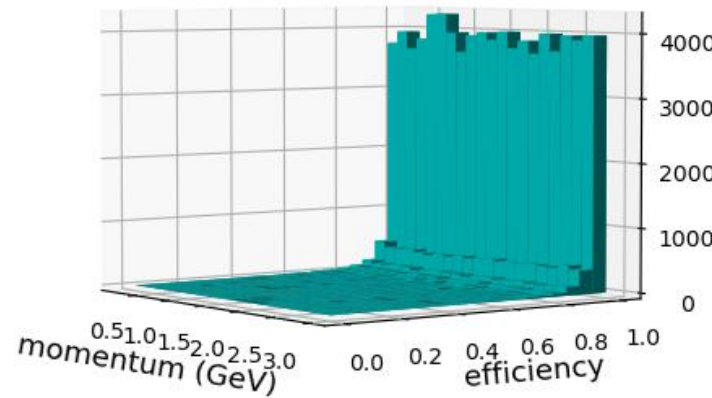
- Single-particle (e^\pm , K^\pm , μ^\pm , p^\pm , π^\pm) MC sample
- $0.2 \text{ GeV}/c < P < 3.0 \text{ GeV}/c$
- Mixed with BESIII random trigger data as background ($\sim 45\%$ hits)
- Train: Validation: Test = 4: 1: 1

◆ Hit selection performance

- The preliminary results show that GNN provides high efficiency and purity of hits selection

- *Hit selection Efficiency* : $\frac{N_{signal}^{predicted}}{N_{signal}^{real}} 98.7\%$

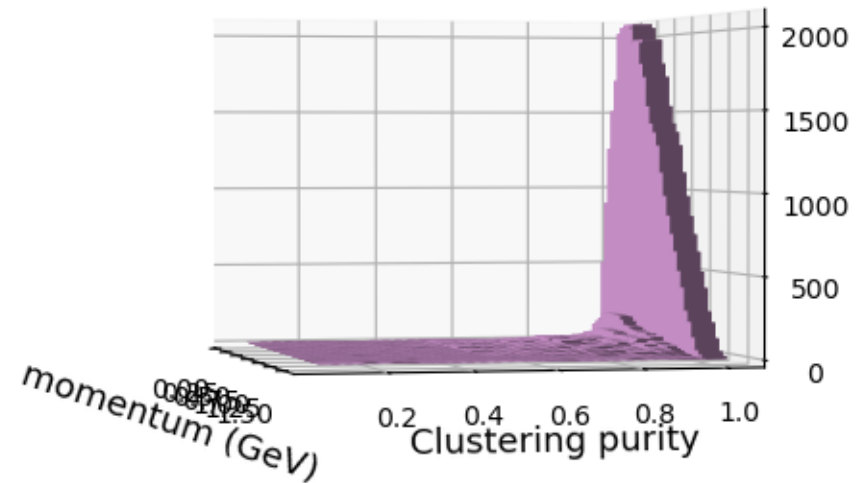
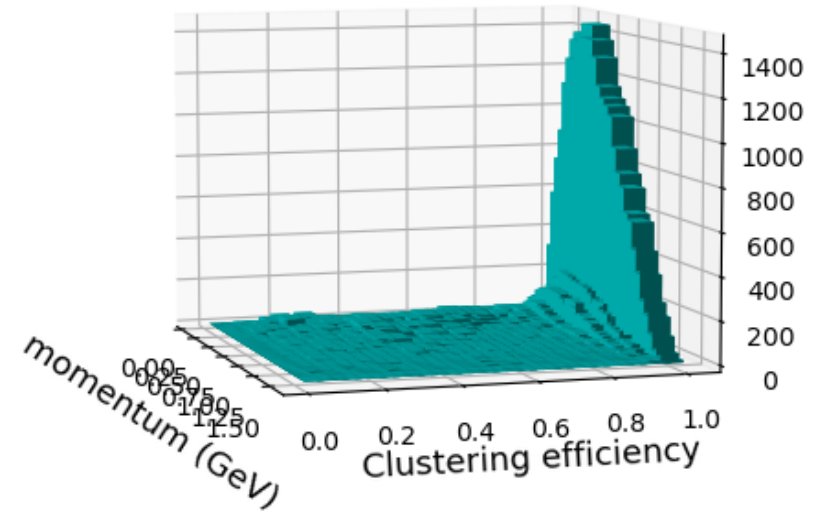
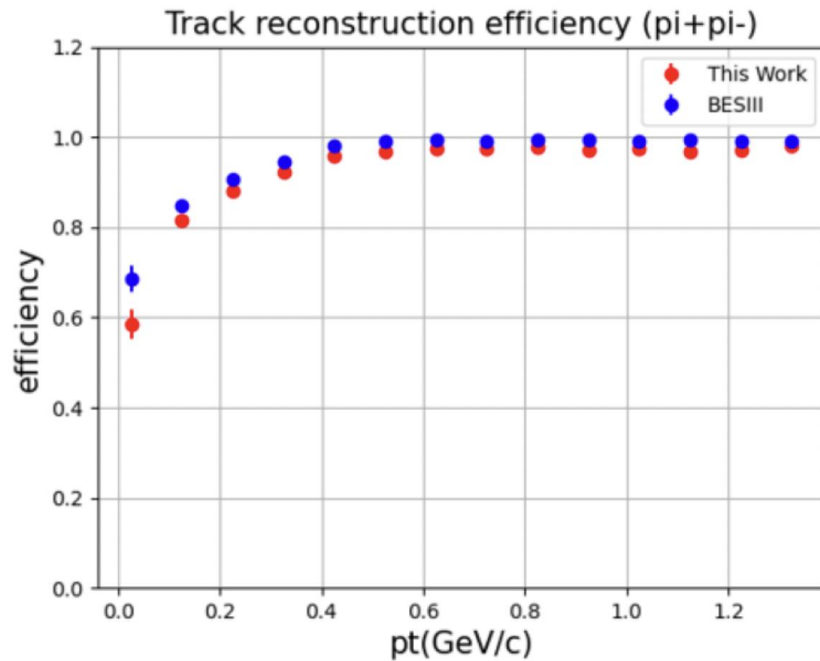
- *Hit selection Purity* : $\frac{N_{signal}^{predicted}}{N_{all}^{predicted}} 96.5\%$



Efficiency and purity can be balanced by adjusting the model parameter

◆ Particle reconstructed performance

- $J/\psi \rightarrow \rho^0 \pi^0 \rightarrow \gamma \gamma \pi^+ \pi^-$ from MC simulation
- $track\ eff = \frac{N_{rec\ tracks}}{N_{total\ tracks}}$
- The preliminary results presents promising performance



Performance of filtering noise at STCF



◆ Dataset

- $J/\psi \rightarrow \rho^0 \pi^0 \rightarrow \gamma \gamma \pi^+ \pi^-$ from MC simulation
- Mixing background (Luminosity-related, Beam-gas effect, Touschek effect) within the framework

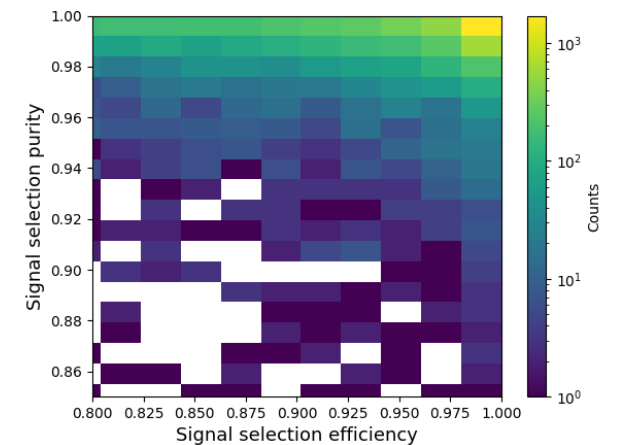
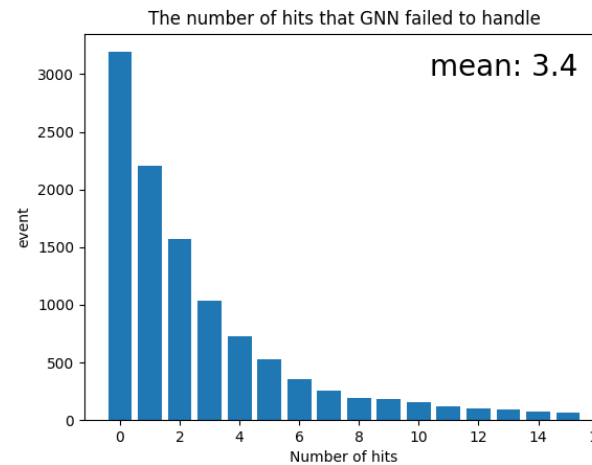
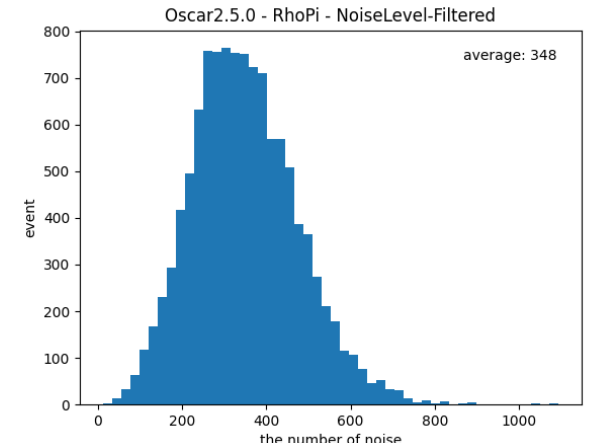
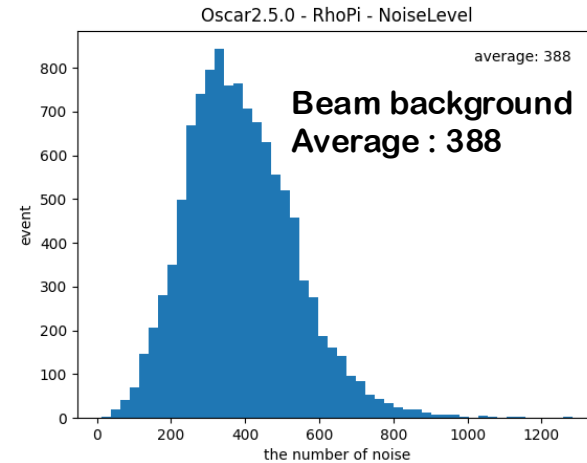
◆ Hit selection performance

- The background includes 'track' background, after removal, the noise level is 348

- *Hit selection Efficiency* : $\frac{N_{signal}^{predicted}}{N_{signal}^{real}}$ 91.7%

- *Hit selection Purity* : $\frac{N_{signal}^{predicted}}{N_{all}^{predicted}}$ 97.0%

- *Remove noises rate* : $\frac{N_{noise}^{predicted}}{N_{noise}^{real}}$ 99.0%



Performance of filtering noise at STCF

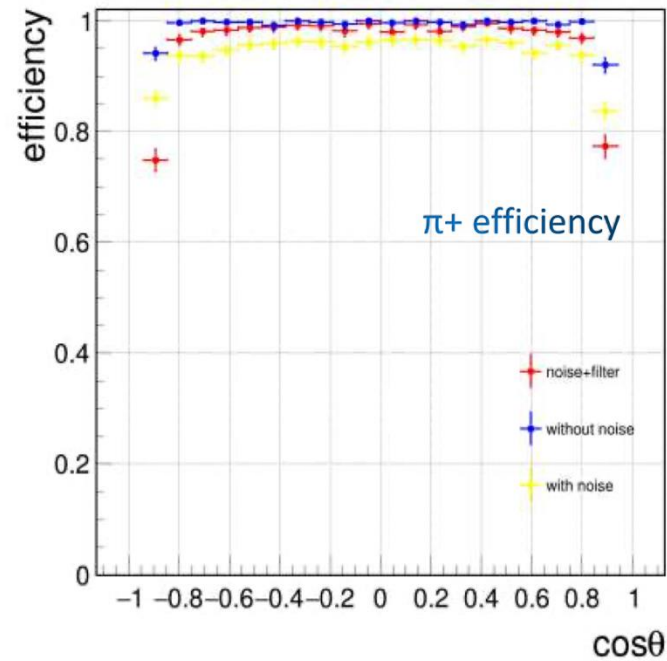
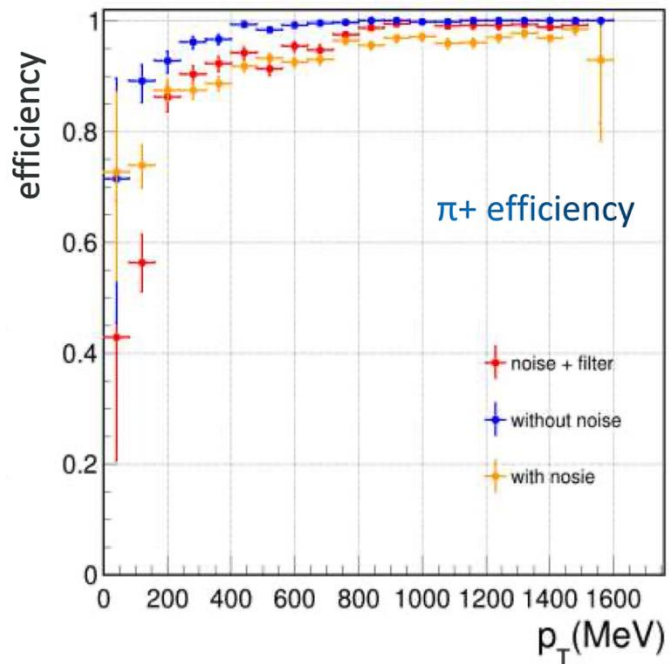


◆ Dataset

- $J/\psi \rightarrow \rho^0 \pi^0 \rightarrow \gamma \gamma \pi^+ \pi^-$ from MC simulation
- Mixing background (Luminosity-related, Beam-gas effect, Touschek effect) within the framework

◆ The reconstruction efficiency after GNN filtering noise is significantly improved

◆ At large $|\cos\theta|$, the tracking efficiency decreases due to **fewer signal and more noises**

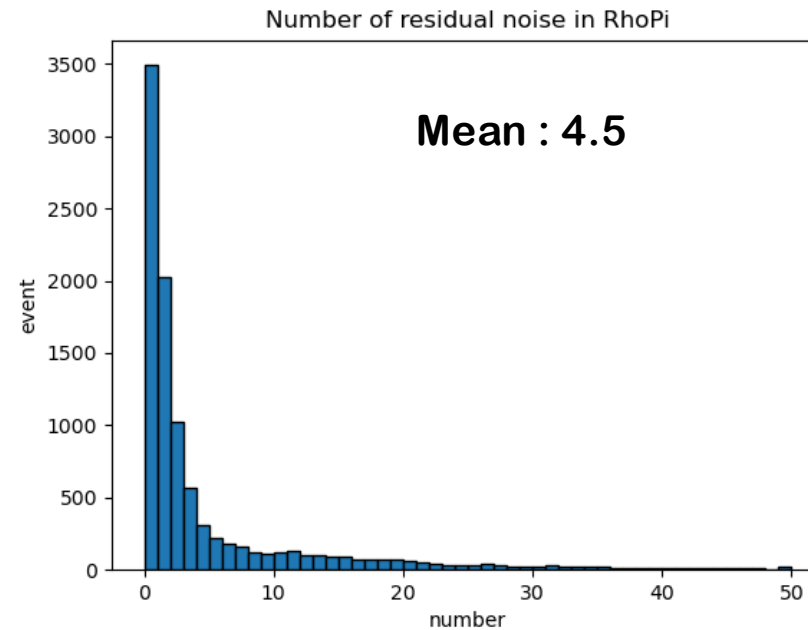
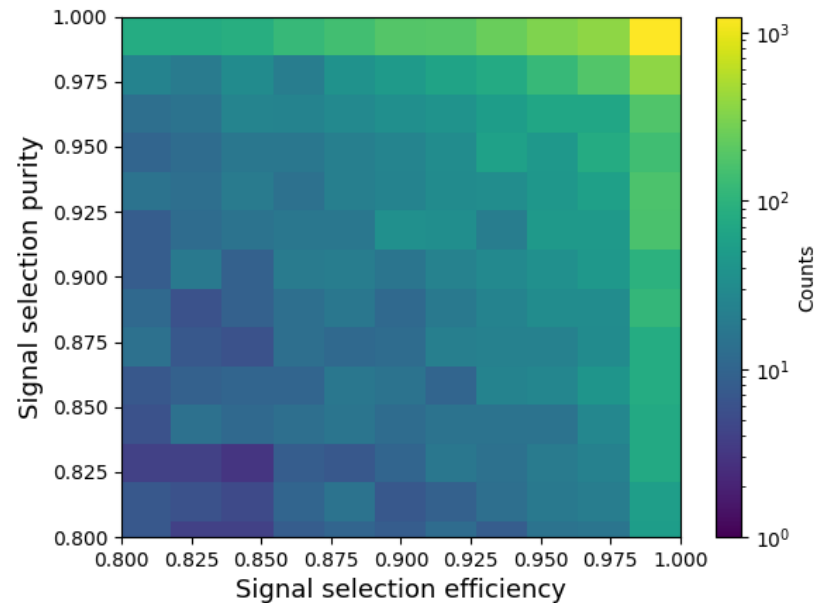


◆ Dataset

- $J/\psi \rightarrow \rho^0 \pi^0 \rightarrow \gamma \gamma \pi^+ \pi^-$ from MC simulation
- Mixed with 600 random trigger noises

◆ Hit selection performance

- Preliminary results shows promising performance



- ◆ A novel tracking algorithm prototype based on machine learning method at BESIII and STCF is under development
 - GNN to distinguish the hit-on-track from noise hits.
 - Clustering method based on DBSCAN and RANSAC to cluster hits from multiple tracks
- ◆ Preliminary results on MC data shows promising performance

Outlook

- ◆ Further optimization of the cluster model is needed
- ◆ Performance verification concerning events with more tracks and long lived particle
- ◆ Check the reconstruction time



THANK YOU