Particle Physics

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Content (and Disclaimer)

This lecture will give an overview of how to assemble detectors into experiments at Colliders.

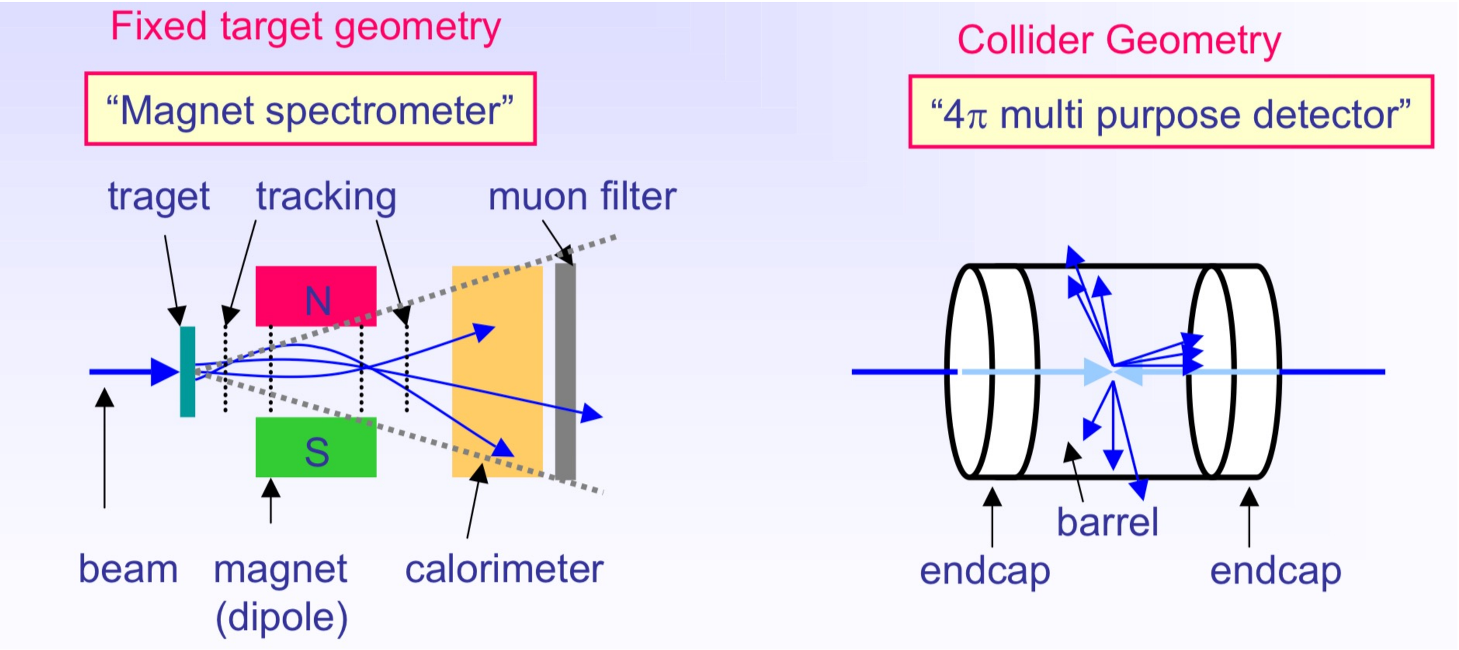
- Experiments of the recent past and
- present experiments

Experiment: assembly of detectors

Goal of Ideal experiments: measure

- Characteristics of *ALL* charged and neutral articles
- Characteristics of a full Event (topology & much more)

This cannot be done by a single detector
→ integrate several detectors
→ experiments



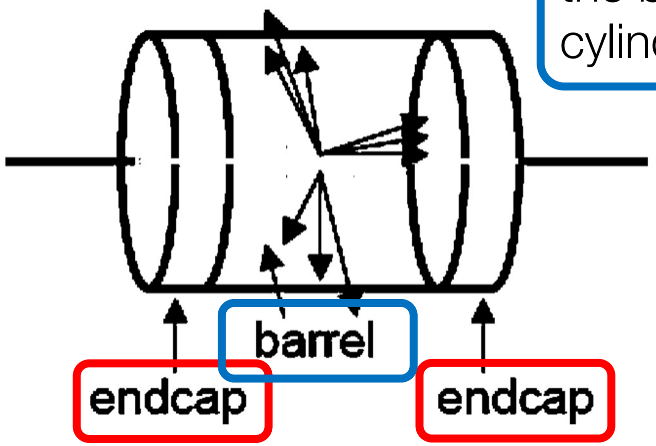
Limited dΩ + easy access

~Full dΩ + ~no access

Designing a 4π Collider Experiment

the end-cap (forward / backward part), it consists of disks that are perpendicular to the beam line.

the barrel (large angle / large p_T / large η) cylindrical and co-axial with the beam axis

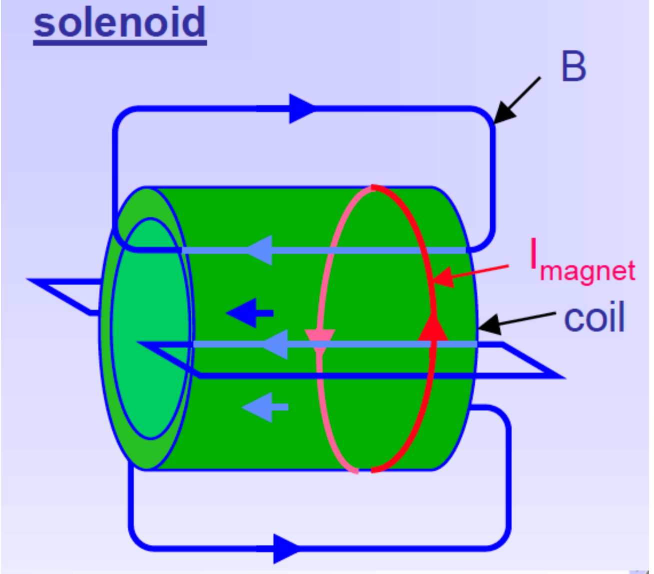


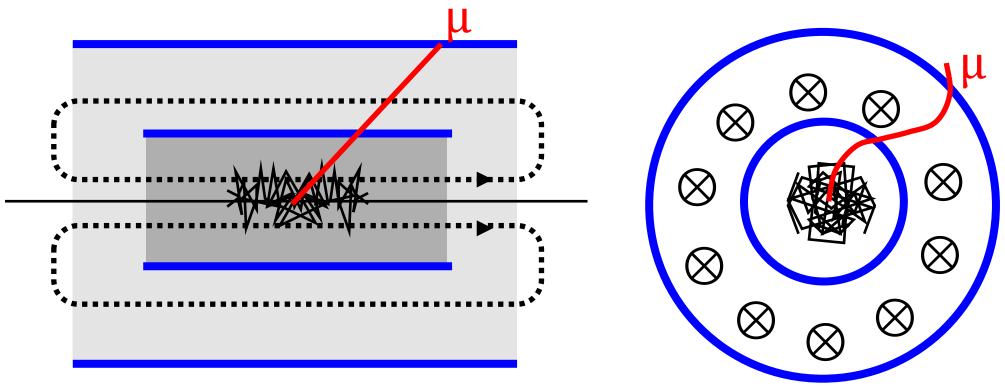
The experiment (== assembly of many detectors) 'should':

- *Be capable of measuring known physics processes but also unexpected new physics*;
- Be as hermetic as possible;
- Measure momentum of all charged particles → B field
- Measure energy of all hadrons and electrons;
- Filter muons using a large amount of material and measure its momentum;
- Be capable of identifying particles (mass and charge)
- Reconstruct primary and secondary vertices
- Have excellent triggering performance and sustain the rate of interactions;
- The position of all the different detectors should be known with high accuracy.

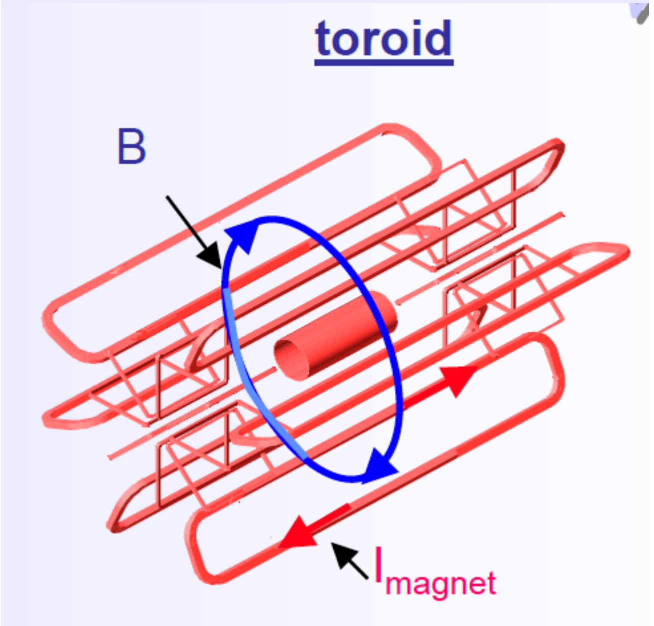
Is this possible at all? Yes but with caveats and limitations.

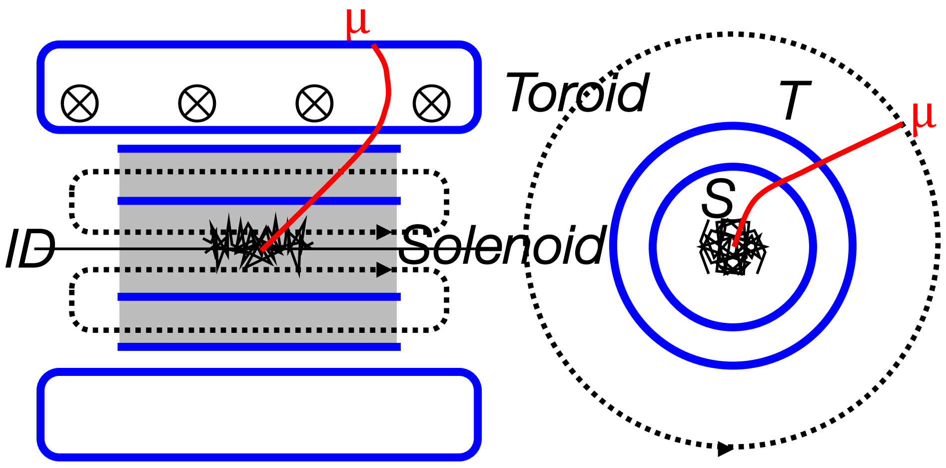
Choosing a B-Field Configuration





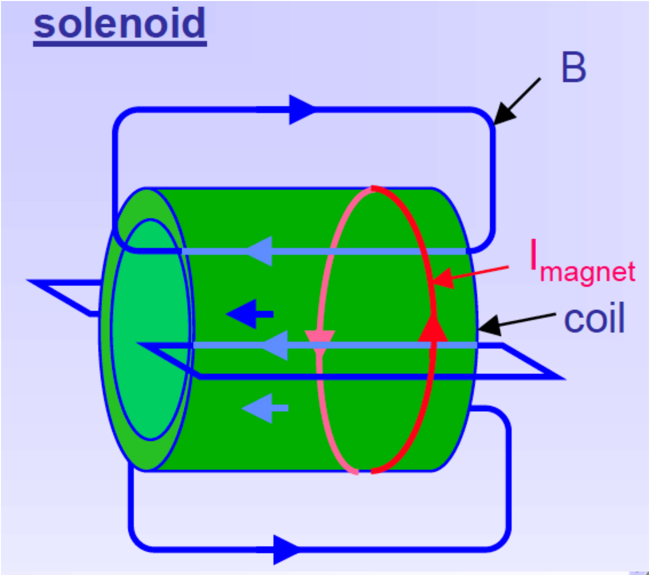
- *Bending in the transverse plane*
- Large homogenous field inside coil
- weak opposite field in return yoke
- Size limited (cost)
- rel. high material budget





- *Bending in the longitudinal plane*
- Rel. large fields over large volume
- Rel. low material budget (air toroid)
- non-uniform field → measure!
- complex structure

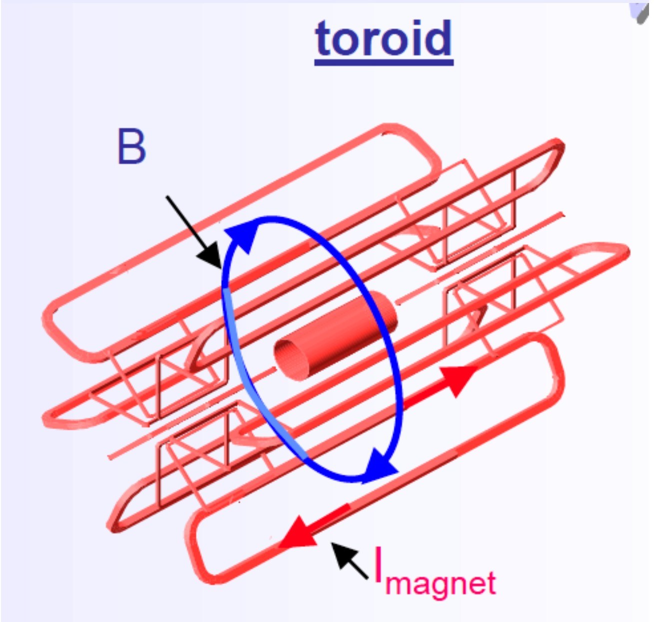
Solenoids Vs Toroids



- Large homogenous field inside coil
- weak opposite field in return yoke

- Size limited (cost)
- rel. high material budget

Type	Experiment	B-Field (T)	Cold/ Warm	Diameter (m)	Length (m)
S	DELPHI	1.2	C	5.2	7.4
S	L3	0.5	W	11.9	11.9
S	CMS	4.0	C	5.9	12.5
S	ATLAS (ID)	2.0	C	2.5	5.8
T	ATLAS (μ, barrel)	0.5	C	9.4/20	24.3
T	ATLAS (μ, end-cap)	1.0	C	1.7/10.7	5



- Rel. large fields over large volume
- Rel. low material budget

- non-uniform field
- complex structure

Time Laps of Physics

A modern experiment should be "capable of … unexpected new physics (generally indicated with NP)"

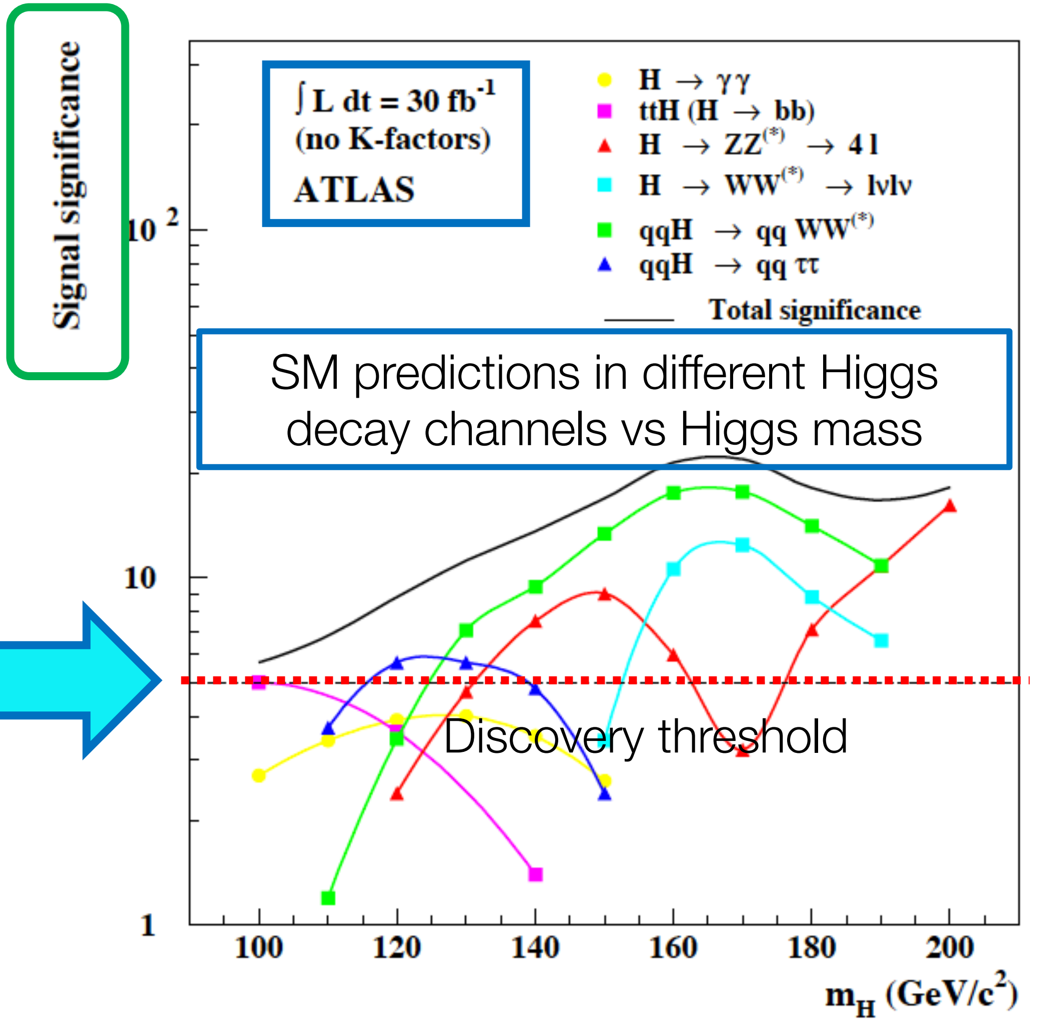
The *Higgs case* @ LHC experiments.

Higgs = "New Physics < 2012"

- SM: couplings versus (unknown) mass known → cross section and decay rates known
- Higgs events for different mass simulated
- LHC Experiments designed to detect Higgs decays 'all masses'

A good / excellent discovery potential for some models beyond SM (SUSY).

Where is the problem?



Time Laps of Physics - continued

A modern experiment at a collider should be "capable of measuring known physics processes but also unexpected new physics (generally indicated with NP)".

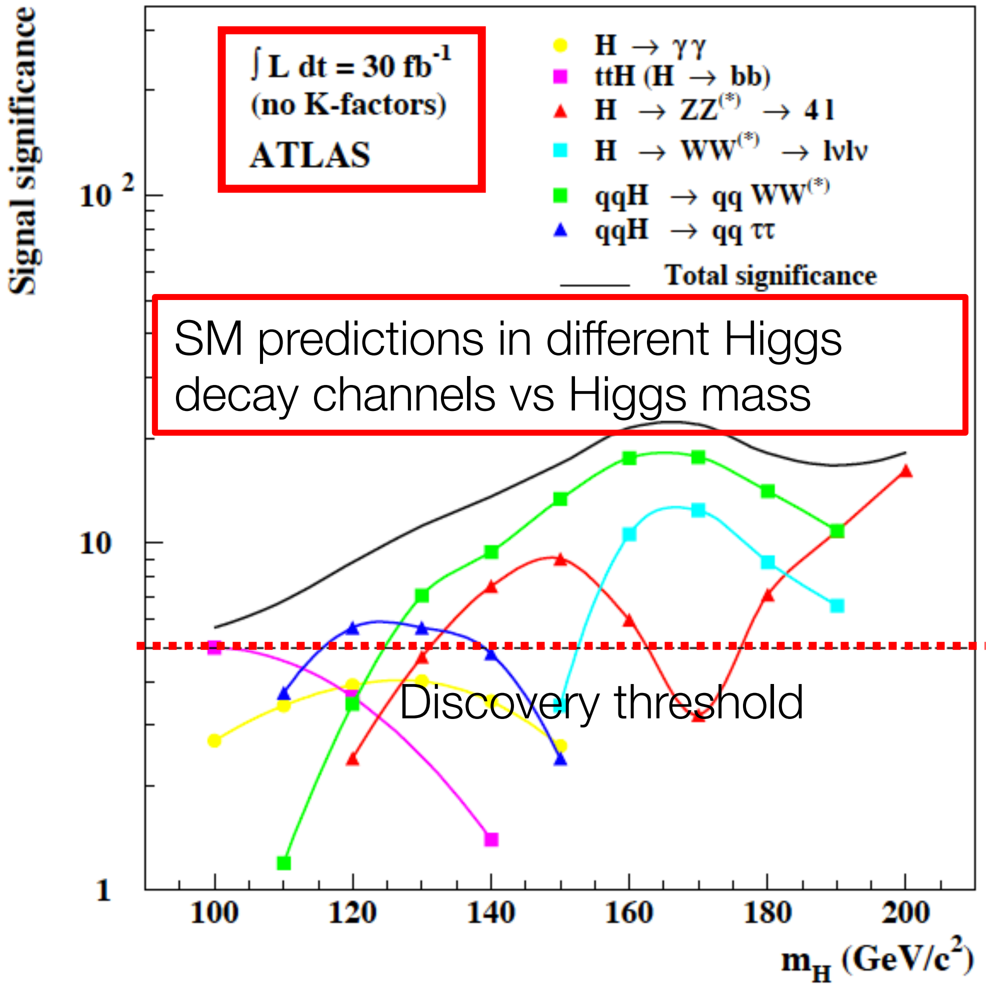
~20 years between the conception / design and operation
(~10 years of project ~10 years of construction) *(Find the money!)*

What if after the 'no-return point' some new discovery or theory development changes the landscape?

The design cannot change much
→ risk of a 'poor' experiment.

However:
- Modern experiments extremely versatile + very large detection potential
- past indicates that New Physics ~means 'large masses'
- Look for high energy leptons, jets, missing energies

Pre-LHC situation : simulation



Time Laps of Technology (1990 – 2000)

Table 1. Typical detector characteristics.

Detector Type	Accuracy (rms)	Resolution Time	Dead Time
Bubble chamber	10 to 150 μm	1 ms	50 ms[a]
Streamer chamber	300 μm	2 μs	100 ms
Proportional chamber	$\geq$ 300 μm[b,c]	50 ns	200 ns
Drift chamber	50 to 300 μm	2 ns[d]	100 ns
Scintillator	–	150 ps	10 ns
Emulsion	1 μm		
Silicon strip	2.5 μm	[e]	[e]

PDG. 1990 edition

Table 28.1: Typical resolutions and deadtimes of common detectors. Revised September 2009.

Detector Type	Accuracy (rms)	Resolution Time	Dead Time
Bubble chamber	10–150 μm	1 ms	50 ms[a]
Streamer chamber	300 μm	2 μs	100 ms
Proportional chamber	50–100 μm[b,c]	2 ns	200 ns
Drift chamber	50–100 μm	2 ns[d]	100 ns
Scintillator	—	100 ps/n[e]	10 ns
Emulsion	1 μm	—	—
Liquid argon drift [7]	~175–450 μm	~ 200 ns	~ 2 μs
Micro-pattern gas detectors [8]	30–40 μm	< 10 ns	20 ns
Resistive plate chamber [9]	$\lesssim$10 μm	1–2 ns	—
Silicon strip	pitch/(3 to 7)[f]	[g]	[g]
Silicon pixel	2 μm[h]	[g]	[g]

PDG. ~2010 edition

Comparison between typical detectors characteristics in 1990 and 2010

Accuracy (μm) Time Resolution					
Year	Streamer chamber	Proportional chamber	Drift chamber	RPC	Micro-pattern gas detectors
1990	300	>300 50 ns	50-300	-	-
2010	300	50-100 2 ns	50-100	10 μm <10ns	30-40 10 ns

~20 years

Detectors designed ~ 10y < data taking

- Detectors at the frontier of technology or (more often) detectors in R&D phase → optimise while constructing
- Expected duration of future experiments > 30 years!
- Long term planning for ***upgrade*** and / or replacement of technologies (increase of luminosity, radiation damage)

And of SC Magnets used in Experiments

Table 34.10: Progress of superconducting magnets for particle physics detectors.

Experiment	Laboratory	B [T]	Radius [m]	Length [m]	Energy [MJ]	X/X_0	E/M [kJ/kg]	
TOPAZ*	KEK	1.2	1.45	5.4	20	0.70	4.3	1987 - 2011
CDF*	Tsukuba/Fermi	1.5	1.5	5.07	30	0.84	5.4	
VENUS*	KEK	0.75	1.75	5.64	12	0.52	2.8	
AMY*	KEK	3	1.29	3	40	†		
CLEO-II*	Cornell	1.5	1.55	3.8	25	2.5	3.7	
ALEPH*	Saclay/CERN	1.5	2.75	7.0	130	2.0	5.5	1989 - 2000
DELPHI*	RAL/CERN	1.2	2.8	7.4	109	1.7	4.2	
ZEUS*	INFN/DESY	1.8	1.5	2.85	11	0.9	5.5	1992 - 2007
H1*	RAL/DESY	1.2	2.8	5.75	120	1.8	4.8	
BaBar*	INFN/SLAC	1.5	1.5	3.46	27	†	3.6	
D0*	Fermi	2.0	0.6	2.73	5.6	0.9	3.7	
BELLE*	KEK	1.5	1.8	4	42	†	5.3	
BES-III	IHEP	1.0	1.475	3.5	9.5	†	2.6	
ATLAS-CS	ATLAS/CERN	2.0	1.25	5.3	38	0.66	7.0	
ATLAS-BT	ATLAS/CERN	1	4.7–9.75	26	1080	(Toroid)†		
ATLAS-ET	ATLAS/CERN	1	0.825–5.35	5	2×250	(Toroid)†		
CMS	CMS/CERN	4	6	12.5	2600	†	12	
SiD**	ILC	5	2.9	5.6	1560	†	12	> 2035
ILD**	ILC	4	3.8	7.5	2300	†	13	
SiD**	CLIC	5	2.8	6.2	2300	†	14	
ILD**	CLIC	4	3.8	7.9	2300	†		
FCC**		6	6	23	54000	†	12	

* No longer in service
**Conceptual design in future
† EM calorimeter is inside solenoid, so small X/X_0 is not a goal

Radius of curvature of a charged particle in a B field → *p*

Super-conducting magnets are used for the momentum measurement of charged tracks (curvature):

$$\frac{\sigma(p_T)}{p_T} \propto \frac{1}{B}$$

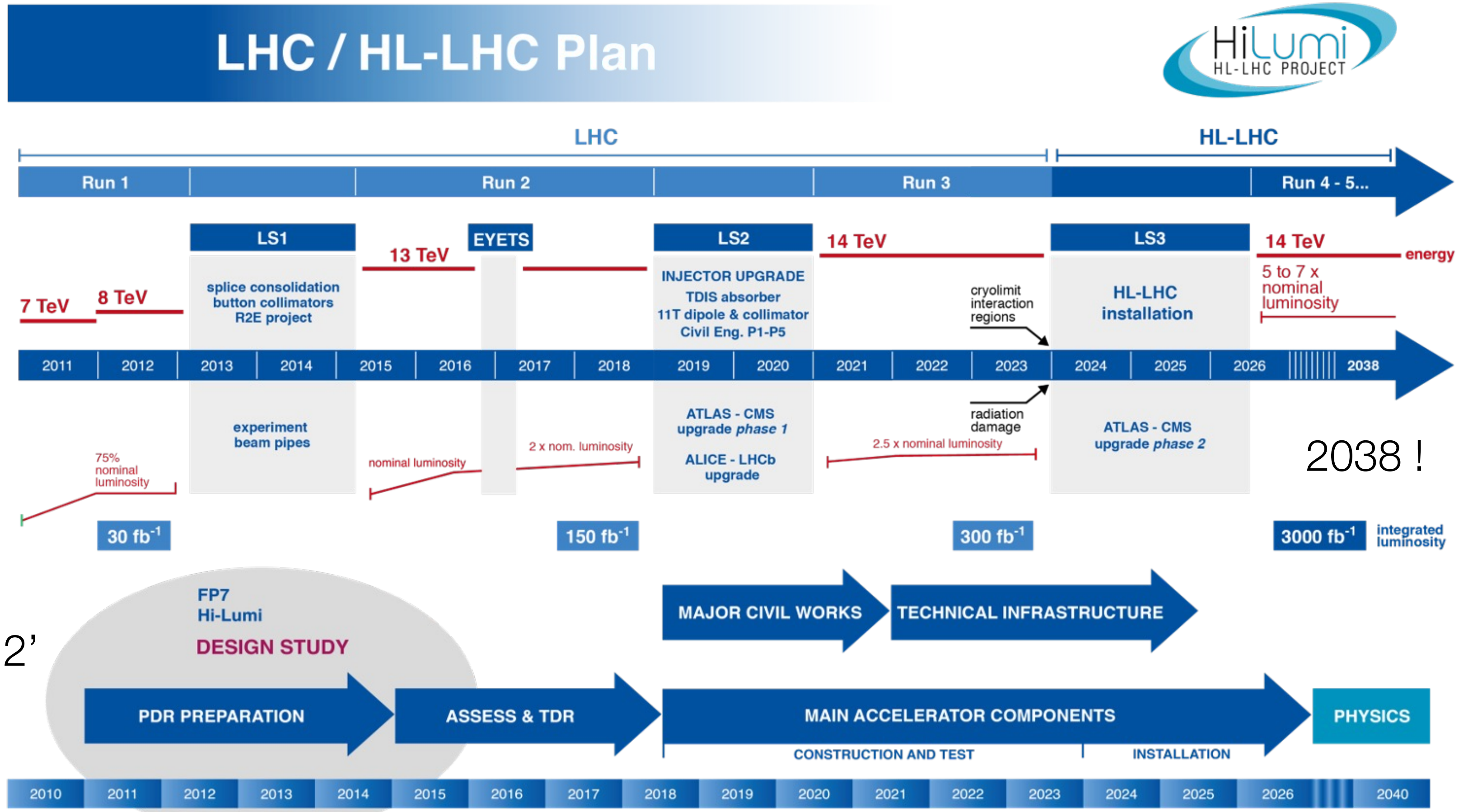
- 4 x B → 4 x resolution in p_T
- Magnets are the largest structure of an experiment

- You may replace (part of the) detectors
- Magnets in experiments have to last for ~30 to 40 y

A 4π Collider Experiment: the Real Life

A 4π hermetic experiment is inaccessible, like a ship in a bottle.

Interventions at the LHC are planned since the construction and opening / intervening / closing back takes ~ 2 y and the coordinated work of a large number of engineers and technicians. The periods of stop are called 'LS', Long Shutdowns.

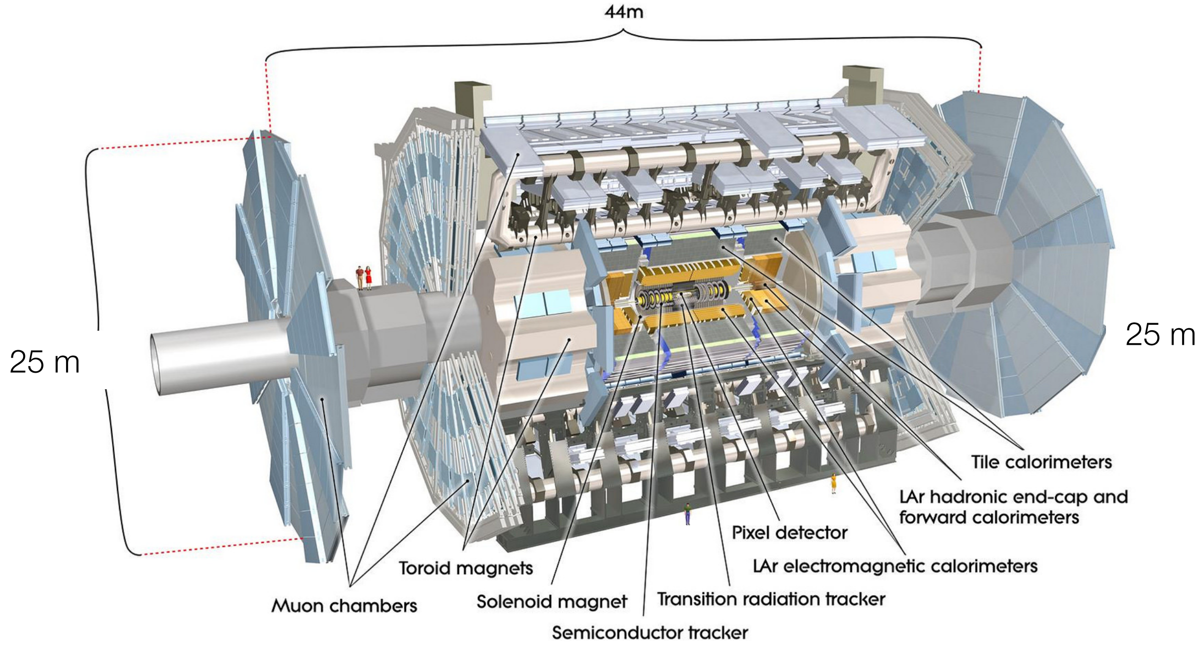


2038 !

LS Long Shutdowns :

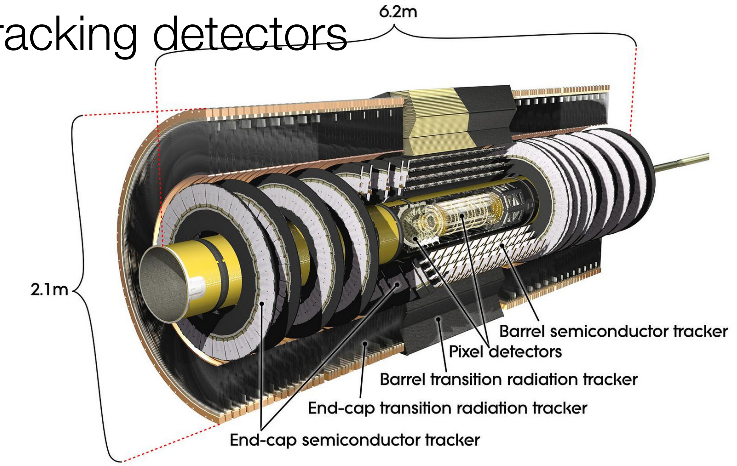
LS2 2019+2020 'Upgrade Phase 1'
LS3 2024 → ½ 2026 'Upgrade Phase 2'
….. COVID delays!!
Expected data taking end ~ 2040

General Overview

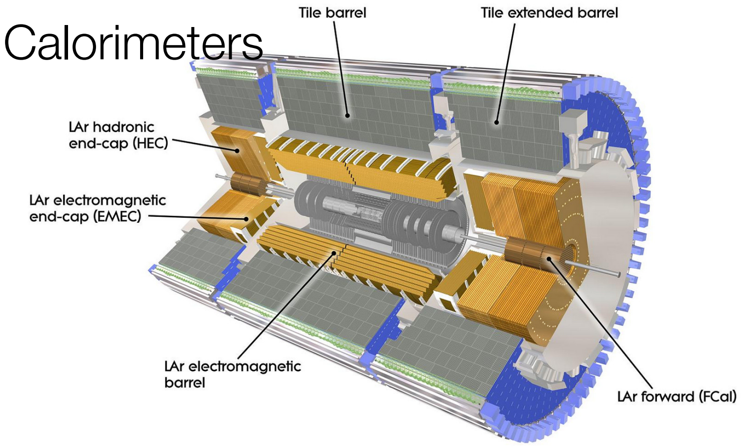


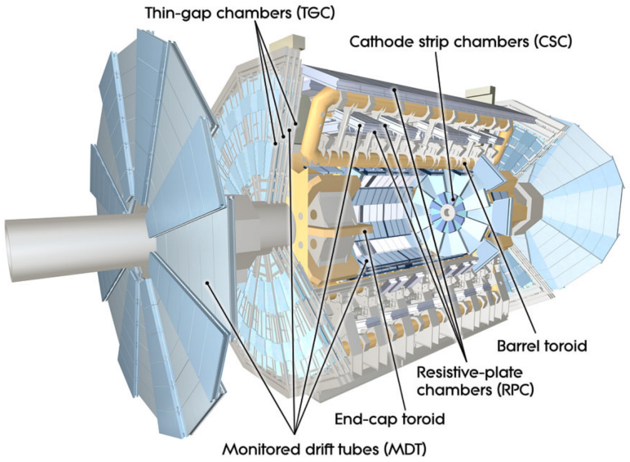
From Inside → Out

Inside → Tracking detectors



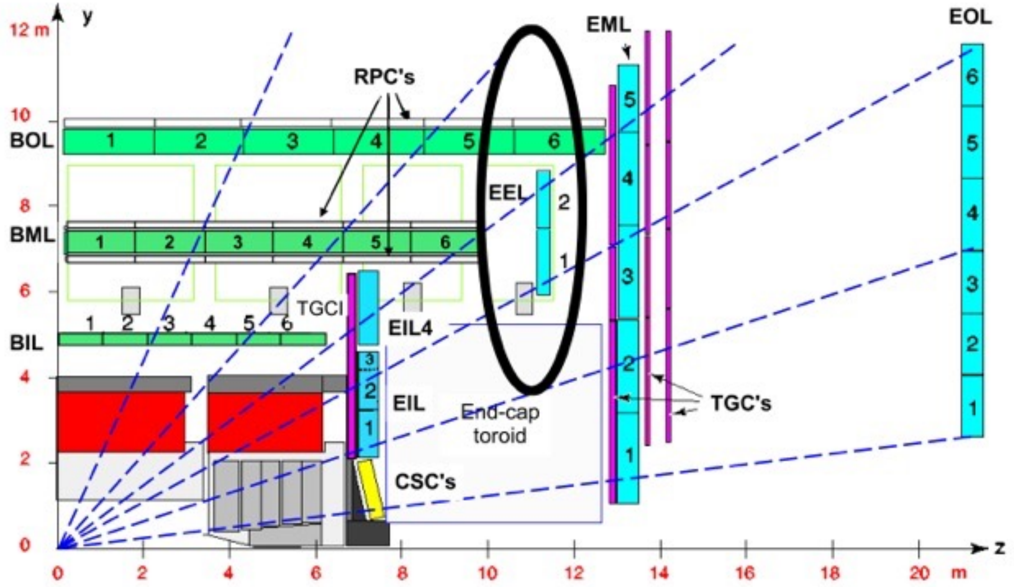
Middle → Calorimeters

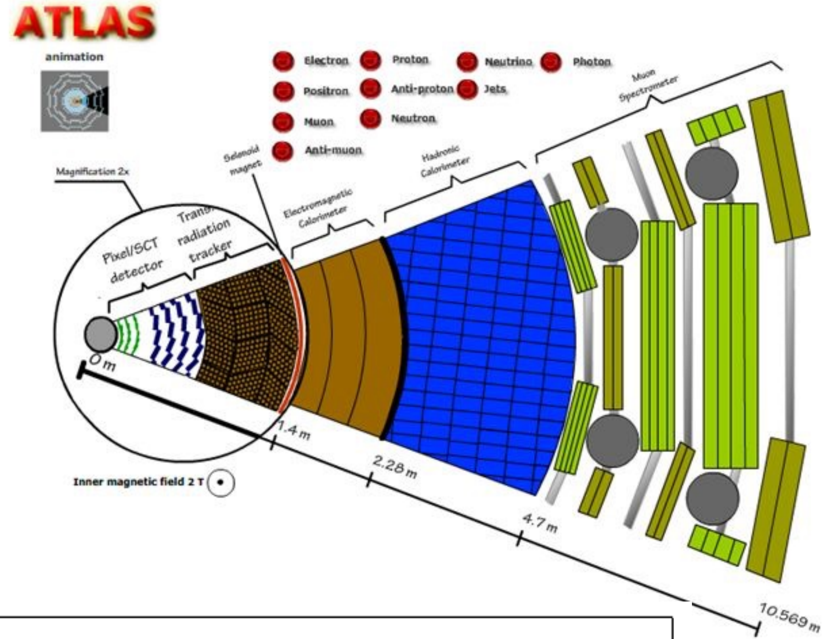




Outside → Muon Spectrometer

General Overview





Detector component	Required resolution	η coverage	
		Measurement	Trigger
Tracking	$\sigma_{p_T}/p_T = 0.05\%\ p_T \oplus 1\%$	± 2.5	
EM calorimetry	$\sigma_E/E = 10\%/\sqrt{E} \oplus 0.7\%$	± 3.2	± 2.5
Hadronic calorimetry (jets)			
barrel and end-cap	$\sigma_E/E = 50\%/\sqrt{E} \oplus 3\%$	± 3.2	± 3.2
forward	$\sigma_E/E = 100\%/\sqrt{E} \oplus 10\%$	$3.1 < \lvert\eta\rvert < 4.9$	$3.1 < \lvert\eta\rvert < 4.9$
Muon spectrometer	$\sigma_{p_T}/p_T = 10\%$ at $p_T = 1$ TeV	± 2.7	± 2.4

Non destructive measurements

Destructive measurements

~ mixed measurements

General Overview

Position	*Name*	*Purpouse*
Innermost	Vertex Detector	charged tracks close to beam pipe; primary (+ secondary ***vertices*** of decaying particles) (small ΔRadius → no momentum!)
Inner	Tracking Detectors	***charged tracks*** with a large ΔRadius
Middle	EM Calorimeters	Measure the energy of ***electrons and photons***
Middle	Hadron Calorimeters	Measure the energy of ***hadronic particles***
Outer	Muon Spectrometer	Measure the momentum of penetrating particles → ***muons***

Position	*Name*	*Hadrons$^{\pm}$*	*Hadrons^{0}*	*Photons*	*$e^{\pm}$*	*$\mu^{\pm}$*
Innermost	Vertex Detector	✅			✅	✅
Inner	Tracking Detectors	✅			✅	✅
Middle	EM Calorimeters	✅	✅	✅	✅	✅
Middle	Hadron Calorimeters	✅	✅			✅
Outer	Muon Spectrometer					✅

Penetration limit

Basic Measurements: Summary

Type of Measurement	Quantity measured	Detector	Position in Experiment
Non destructive (~light detectors in ~vacuum or in gas)	Trajectory of charged particles close to interaction point	Vertex detectors, Si detectors (excellent spatial resolution & rad-hard)	Cylinders with radii ~ 10/20 cm
	Radius of curvature of charged particles in magnetic field	Inner Detectors, typically Si or gaseous detectors	Cylinders in barrel, disks in end-caps. Radially out of Vertex Detectors
Destructive (detectors made of heavy materials)	Energy of em particles (electrons & photons)	EM calorimeters ~ Lead sandwiched with energy detectors	Cylinders in barrel, disks in end-caps. Radially out of Inner Detectors
	Energy of hadronic particles (charged & neutral)	Hadron Calorimeters: Fe/Cu sandwiched with energy detectors	Cylinders in barrel, disks in end-caps. Radially out of Inner Detectors
Mixed	Radius of curvature of charged particles emerging from EM & HCAL calorimeters	Muon detectors: tracking detectors, typically gaseous detectors	Cylinders in barrel, disks in end-caps. At the outmost position

Glossary

	Definition	Measurement	Comment
Efficiency	probability that a detector gives a signal when a particle traverses it	measured using a beam of known particles or using simulation	
Response time	time that the detector takes to form an electronic signal after the arrival of the particle	Test beams	during this time, a second event may not be recorded
Dead time	time between the passage of a particle and the moment at which the detector is ready to record the passage of the next particle	Test beams	The length of the signal, the electronics used, and the recovery time of the detector influence the dead time
Spatial resolution	precision with which the passage of a charged particle is located in space	Test beams	
Energy resolution	possibility of a detector to distinguish two close energies	"test beam" with particles of known energy	The energy resolution is the half-width of the energy distribution

Charged Particles Detectors

Particle Data Group: https://pdg.lbl.gov/2020/reviews/contents_sports.html

Table 34.1: Typical resolutions and deadtimes of common charged particle detectors. Revised November 2011.

Detector Type	Intrinsinc Spatial Resolution (rms)	Time Resolution	Dead Time
Resistive plate chamber	$\lesssim 10$ mm	1 ns (50 ps^a)	—
Streamer chamber	300 μm^b	2 μs	100 ms
Liquid argon drift [7]	$\sim$175–450 μm	$\sim$ 200 ns	$\sim$ 2 μs
Scintillation tracker	$\sim$100 μm	100 ps/n^c	10 ns
Bubble chamber	10–150 μm	1 ms	50 ms^d
Proportional chamber	50–100 μm^e	2 ns	20-200 ns
Drift chamber	50–100 μm	2 ns^f	20-100 ns
Micro-pattern gas detectors	30–40 μm	$<$ 10 ns	10-100 ns
Silicon strip	pitch/(3 to 7)^g	few ns^h	$\lesssim 50$ ns^h
Silicon pixel	$\lesssim 10$ μm	few ns^h	$\lesssim 50$ ns^h
Emulsion	1 μm	—	—

[a] For multiple-gap RPCs.
[b] 300 µm is for 1 mm pitch (wirespacing/√12).
[c] n = index of refraction.
[d] Multiple pulsing time.
[e] Delay line cathode readout can give Å}150 µm parallel to anode wire.
[f] For two chambers.
[g] The highest resolution (“7”) is obtained for small-pitch detectors (.25 µm) with pulse-height-weighted center finding.
[h] Limited by the readout electronics [8].

Typical detectors in modern colliders

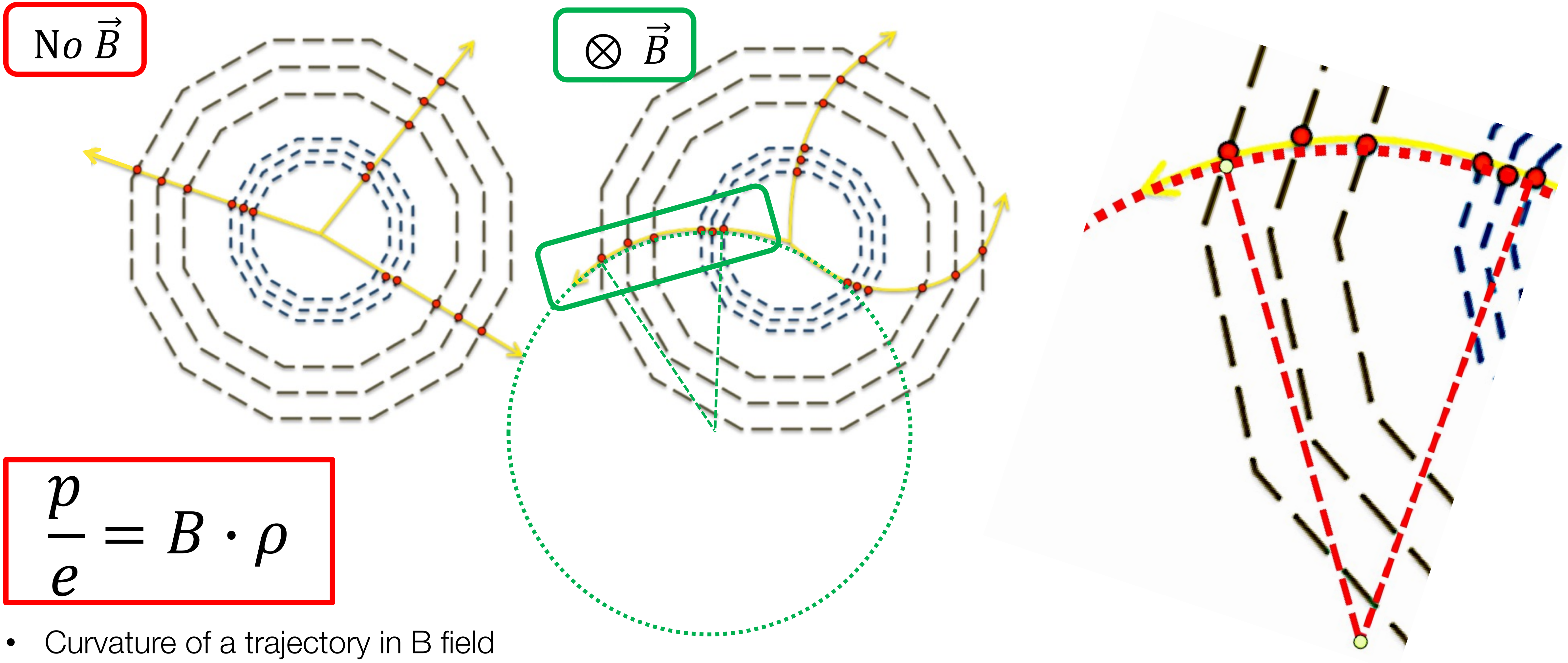
Combined Measurements

Complex observables need the combination of different detectors

- E_{tot},=Total event energy, p_{tot} = event momentum balance;
  - (E_{CM} – E_{tot}) = energy carried by invisible particles
  - $(\vec{0} - \overrightarrow{p_{tot}})$ gives the direction of invisible particles
  - Total momentum only in the transverse plane (E_{CM} is not known in hadronic colliders)
- Muons (Inner Detector + Muon Spectrometer)
- EM and Hadron calorimeters to distinguish hadrons from electrons and photons
- Associate showers with charged tracks extrapolated to the entrance of calorimeters
- showers not associated to any charged particle (→ neutral EM or hadronic particle)
- Reconstruct jets

	p of charged tracks	*Energy of all particles*	*Identify photons electrons*	*Identify muons*	*Associate tracks & showers*	*Jets*	*E_{tot} & p_{tot}*
ID	✅		✅	✅	✅	✅	✅
EM-calo		✅	✅	✅	✅	✅	✅
H-Calo		✅		✅	✅	✅	✅
μ-spec	✅			✅			✅

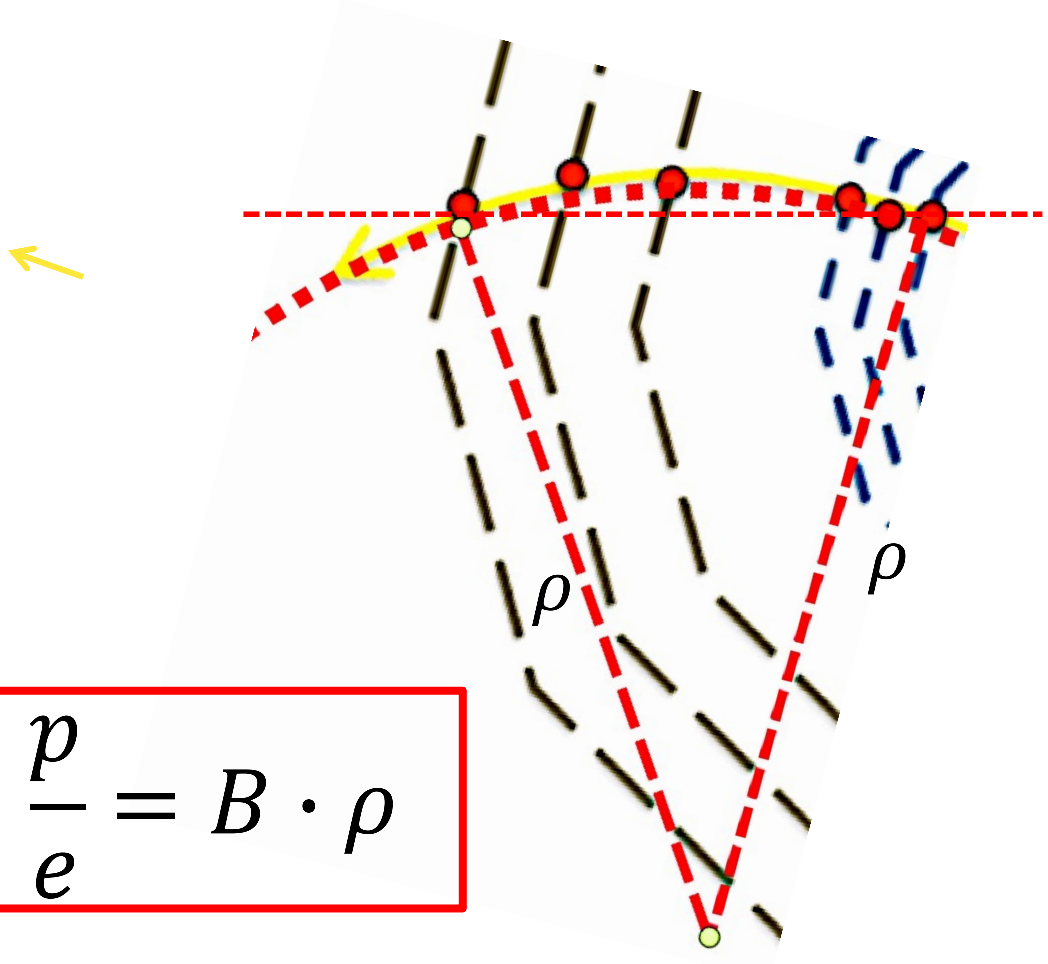
Measurement of Momentum p in a B Field



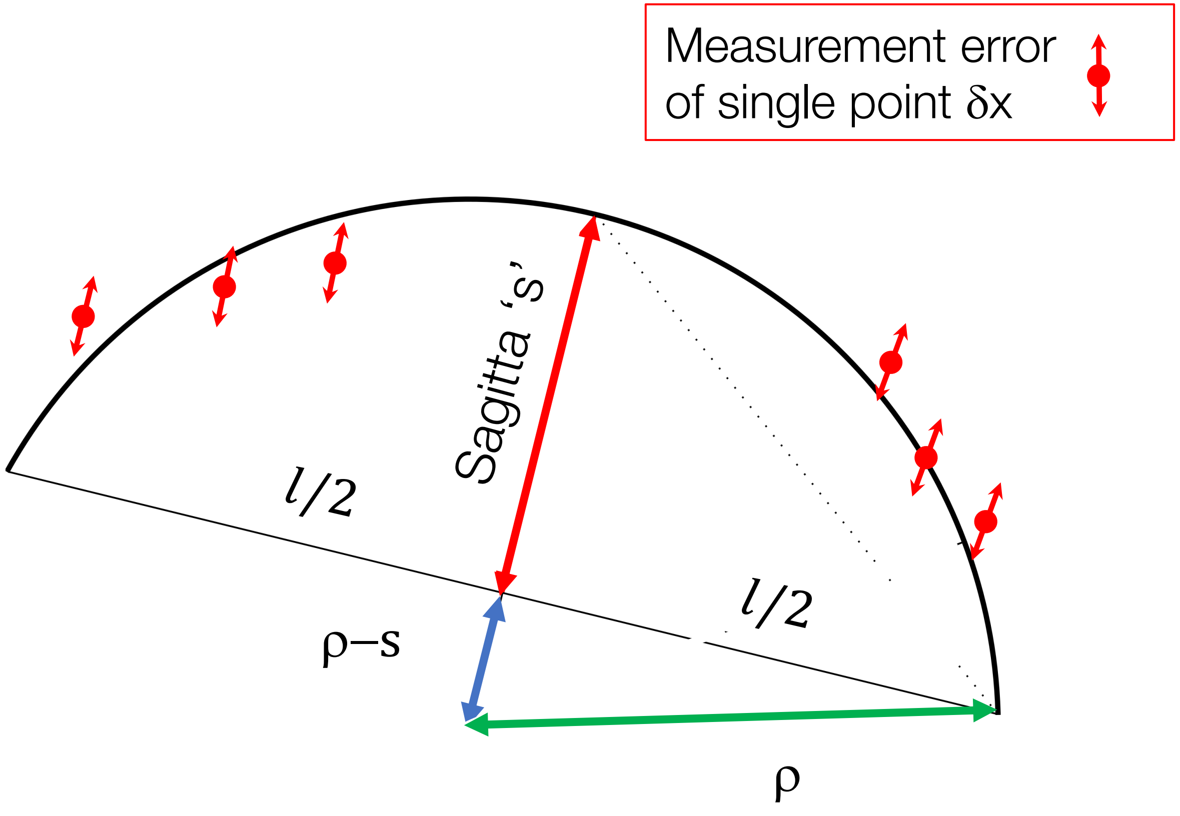
$$\frac{p}{e} = B \cdot \rho$$

- Curvature of a trajectory in B field
- Non-destructive measurement → ionization energy losses (det. elements) are $\ll p$
- Tracking detectors are ~perpendicular to the trajectory of the charged track
- Multiple position measurement along the trajectory → the curvature → momentum

Measurement of Momentum p

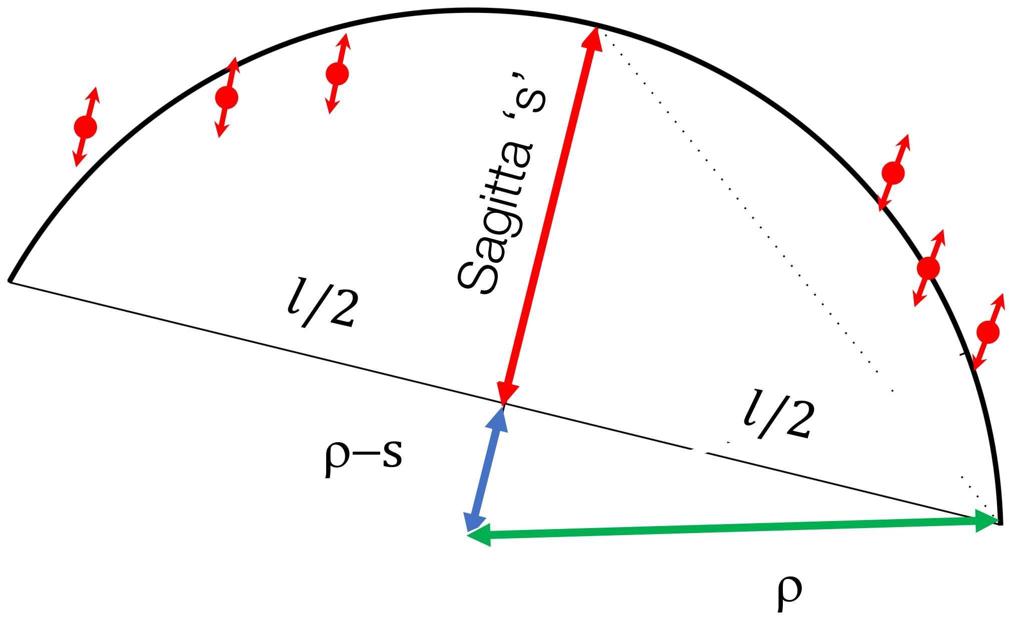


$$\frac{p}{e} = B \cdot \rho$$

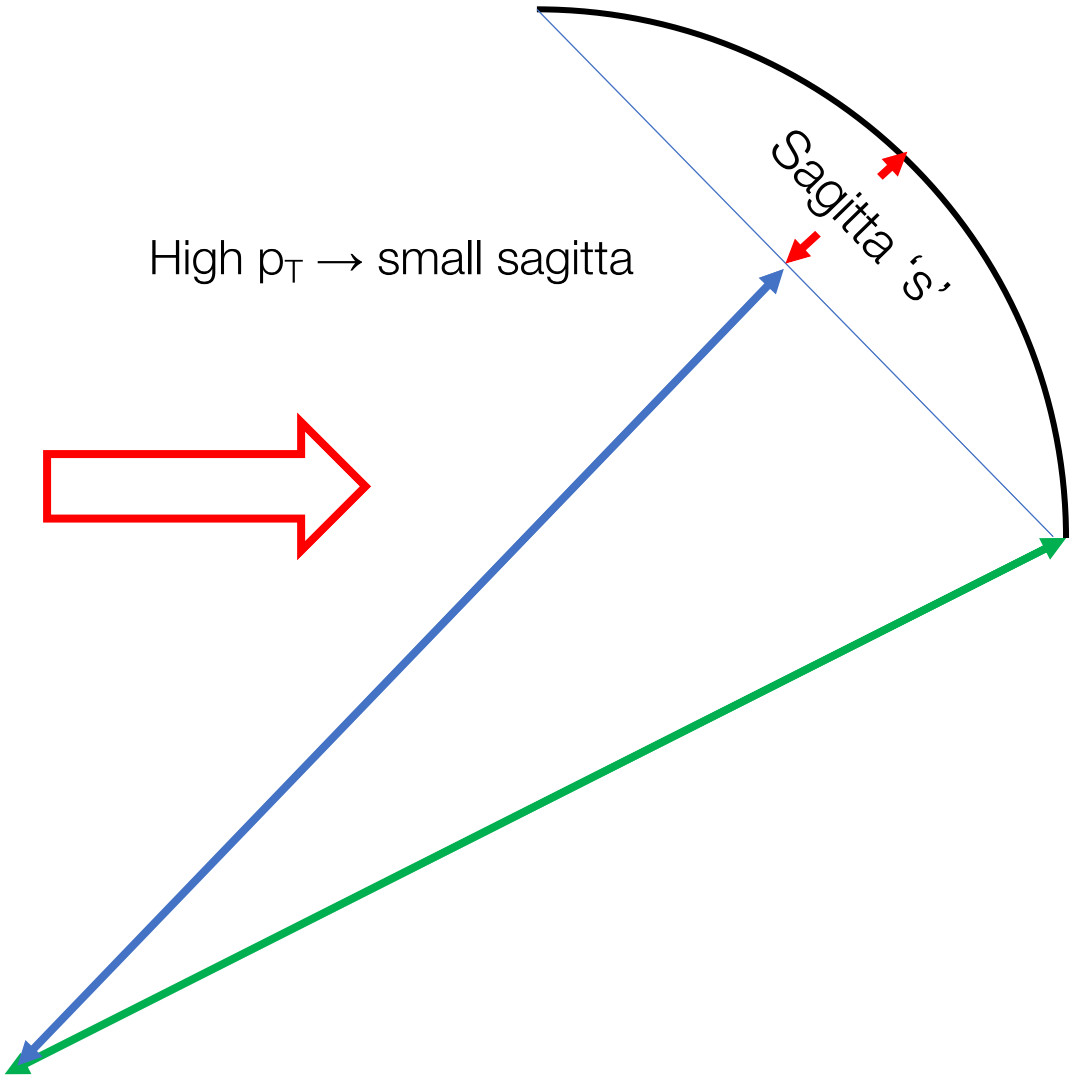


Momentum is determined by measuring the radius of curvature in magnetic field $p \propto \rho$.
In practice what is measured is the sagitta 's'

High p_T



Low p_T → large sagitta



High p_T → small sagitta

$$\frac{p}{e} = B \cdot \rho$$

Measuring Physical Quantities

The component p_T perpendicular to the direction of B is given by

$$\sin\left(180 - 90 - \frac{\theta}{2}\right) = \cos\left(\frac{\theta}{2}\right)$$

$$\frac{p}{e} = B \cdot \rho \rightarrow \qquad p_T(GeV/c) = 0.3 \cdot \mathrm{B(l)} \cdot \rho(\mathrm{Tesla} \cdot m) \rightarrow \frac{1}{\mathrm{p_T}} = \frac{1}{\rho \cdot B(l) \cdot 0.3}$$

with units GeV, Tesla, meters. q is the charge of the particle, r is the radius of curvature and l is the position along the trajectory.

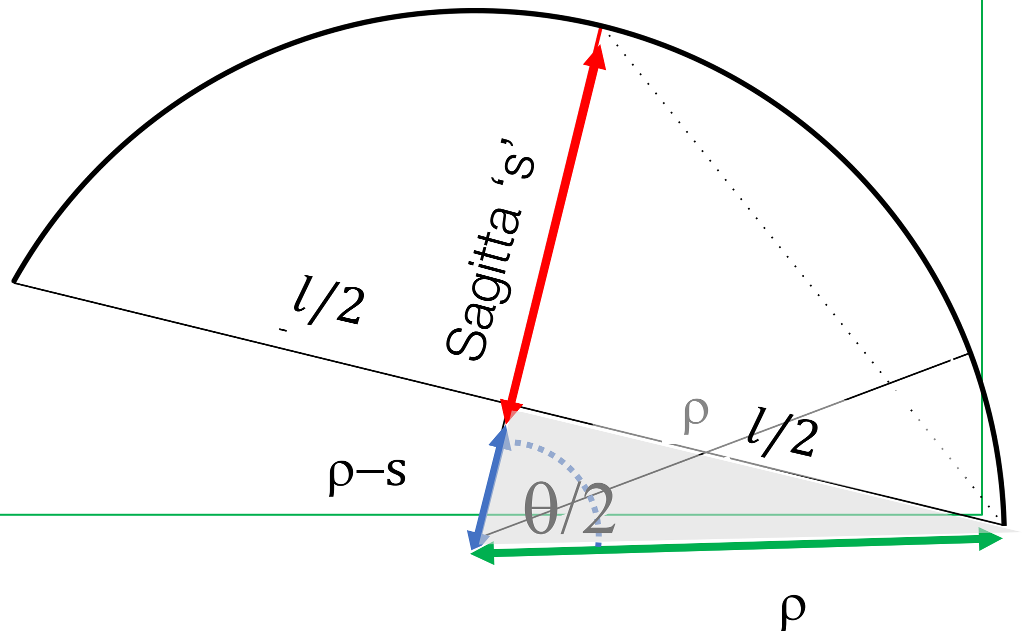
If we consider the triangle enclosed by ‘l/2’, ρ-s and ρ we can write the relation

$$(\rho - s)^2 + (l/2\,)^2 = \rho^2$$

$$\rho \cdot \cos\left(\frac{\theta}{2}\right) = \rho - s \ \rightarrow s = \rho \cdot (1 - \cos\left(\frac{\theta}{2}\right))$$

$$for\ small\ \frac{\vartheta}{2}\ we\ expand\ \cos\left(\frac{\theta}{2}\right) \approx 1 - \theta^2/8$$

$$s = \rho \cdot (1 - \cos\left(\frac{\theta}{2}\right)) \approx \rho \cdot \theta^2/8$$



Measurement of Momentum in B Field

$$s = \rho \cdot \left(1 - \cos\left(\frac{\theta}{2}\right)\right) \approx \rho \cdot \theta^2/8$$

$$\theta \approx \frac{l}{\rho} \rightarrow \quad s = \rho \cdot \frac{l^2}{\rho^2 \cdot 8} = \frac{l^2}{\rho \cdot 8}$$

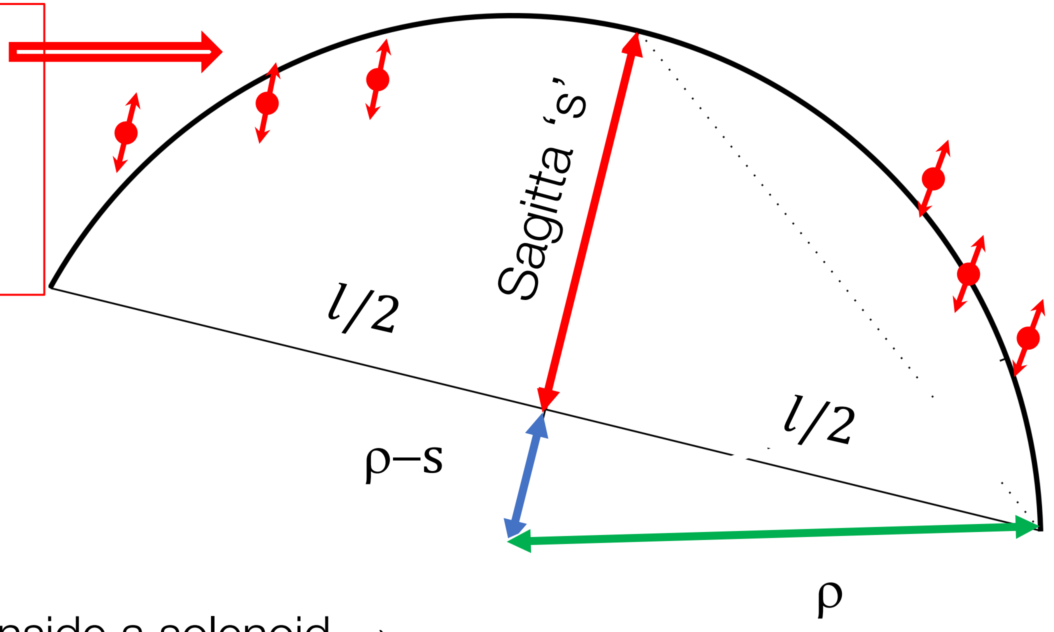
From the slide before

$$\frac{1}{p_T} = \frac{1}{\rho \cdot B(s) \cdot 0.3}$$

$$\rightarrow \quad s = \rho \cdot \frac{l^2 \cdot 0.3 \cdot B(l)}{p_T \cdot 8}$$

The example shown on this figure refers to a VERY low momentum charged track, in practice the sagitta is always much smaller than the radius of curvature

Measurement inside the B field → points with error σ_x



Two ways to measure the sagitta:

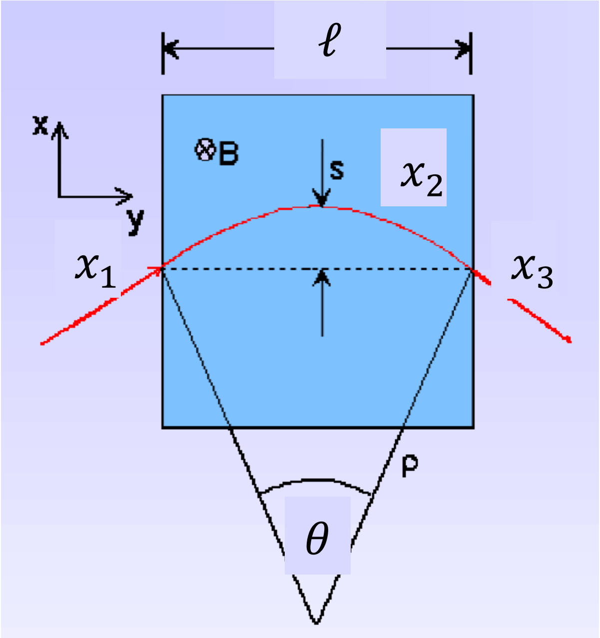
- Using measurements inside the B field: Inner Detectors inside a solenoid → circle that ***best*** passes through the measurement → fit
- Using measurements done outside the magnetic field, in this case the direction of the track before and after the B field region

Error on p_T

Simplified example measurement with 3 points $x_{1,2,3}$:

$$\sqrt{3/2} = \sqrt{1^2 + 1/2^2 + 1/2^2}$$

$$s = x_2 - \frac{x_1+x_3}{2} \rightarrow \frac{\sigma(p_T)}{p_T} = \frac{\sigma(s)}{s} = \frac{\sqrt{3/2}\cdot\sigma_x}{s} = \frac{\sqrt{3/2}\cdot\sigma_x\cdot 8p_T}{0.3\cdot B(l)\cdot l^2}$$



A more general formula has been derived for N equidistant measurements (R.L. Gluckstern, NIM 24 (1963) 381) :

$$\frac{\sigma(p_T)}{p_T} = \frac{\sigma_x\cdot p_T}{0.3\cdot B(l)\cdot l^2}\cdot\sqrt{\frac{720}{N+4}}$$ for N ≥~10

The relative resolution on the measurement of p_T depends

- on the precision of the single measurement and
- linearly on p_T: it worsen with increasing momentum. This is qualitatively intuitive if one considers that the curvature becomes larger (and the sagitta smaller) when p_T increases.
- On the inverse of square root of the number N of measurements
- On the dimension of the measurement area ℓ

Important effect: the multiple scattering.
Charged particles undergo a large number of small deflections when passing through matter

Multiple Scattering Impact on p_T

The deflection of a charged particle, θ_{plane} , after ℓ of a material with X_0 ~

$$\theta_{plane} = (14\frac{MeV}{p\beta c})\sqrt{l/X_0}$$

Rad.Length(cm) = Rad.Length(g/cm^2) * density

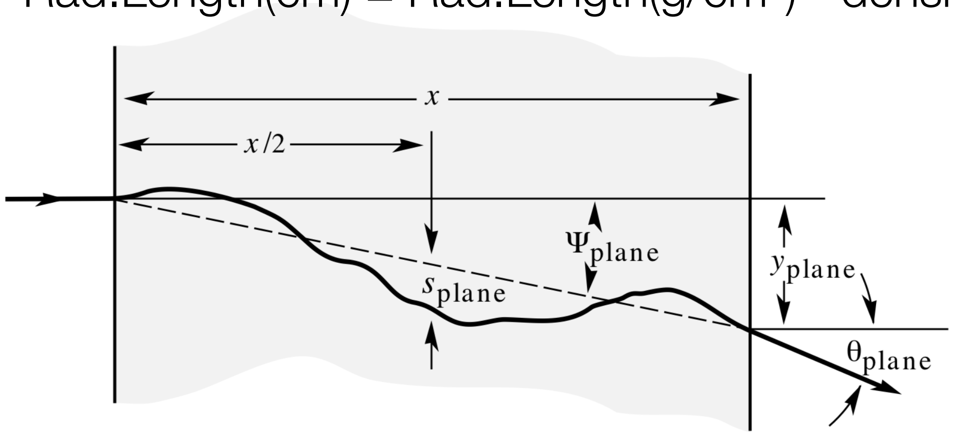


Figure 27.8: Quantities used to describe multiple Coulomb scattering. The particl is incident in the plane of the figure.

Element	Z	Rad. Length (expt.) [g.cm^{-2}]
H	1	63.04
He	2	94.32
C	6	42.7
N	7	37.99
O	8	34.24
F	9	32.93
Ne	10	28.93
Na	11	27.74
Mg	12	25.03
Al	13	24.01
Si	14	21.82
P	15	21.21
S	16	19.5
Cl	17	19.28
Ar	18	19.55
K	19	17.32
Ca	20	16.14
Ti	22	16.16
Cr	24	14.94
Fe	26	13.84
Ni	28	12.68
Cu	29	12.86
Zn	30	12.43
Ag	47	8.97
Pt	78	6.54
Au	79	6.46
Pb	82	6.37

→ Material of Inner Detectors (walls, cables and services) has an impact on p_T.

The relative effect is ~

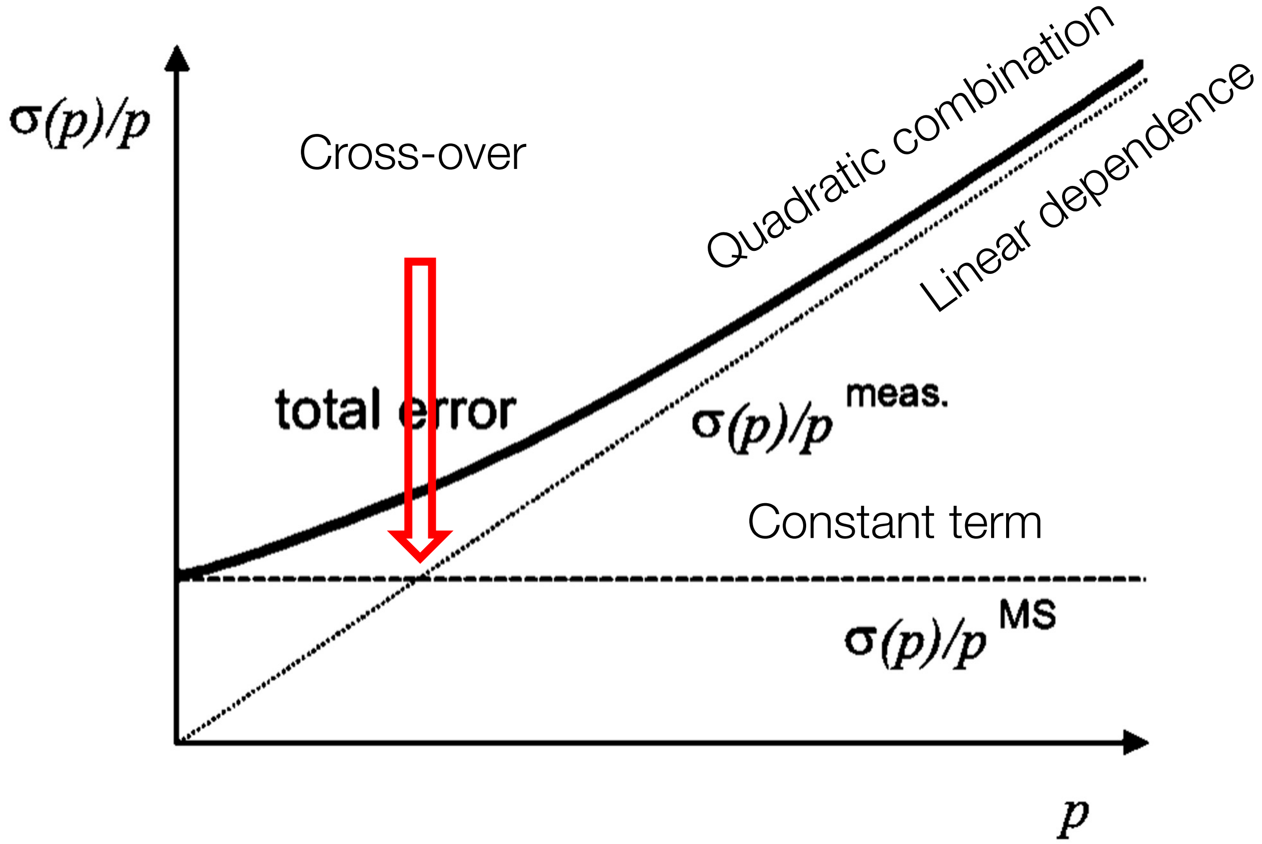
$$\frac{\delta p_n}{p_n} = \frac{\delta\theta}{\theta} = \frac{14\ MeV}{\beta c\ 0.3 \int B(\ell)d\ell}\left[\frac{\ell}{X_o}\right]^{1/2}$$

→ no p_T dependence

The two effects (detector resolution and effect of multiple scattering have to be combined quadratically):

$$\frac{\delta p_T}{p_T} = \sqrt{A^2_{det-res} \cdot p_T^2 + A^2_{mult-scatt.}}$$

Ideal Situation



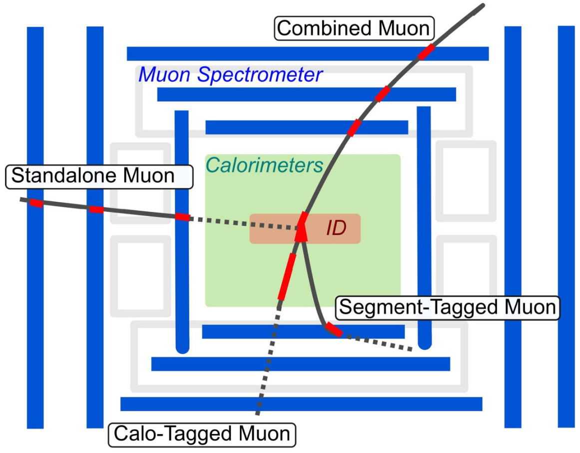
Example:

$p_T = 1$ GeV, ℓ = 1m, B = 1T, N=10, σ_x = .2mm

$$\frac{\delta p_T}{p_T}\Big|^{det-res} = 0.5\%$$

Assume the detector to be filled with atmospheric pressure Argon (gas), X_0 = 110m

$$\frac{\delta p_T}{p_T}\Big|^{mult-scat} = 0.5\%$$



Note: calorimeters filter ALL particles but Muons !

(Muon) p_T Resolution in ATLAS

More effects (in the Muon system after traversing calorimeters!):

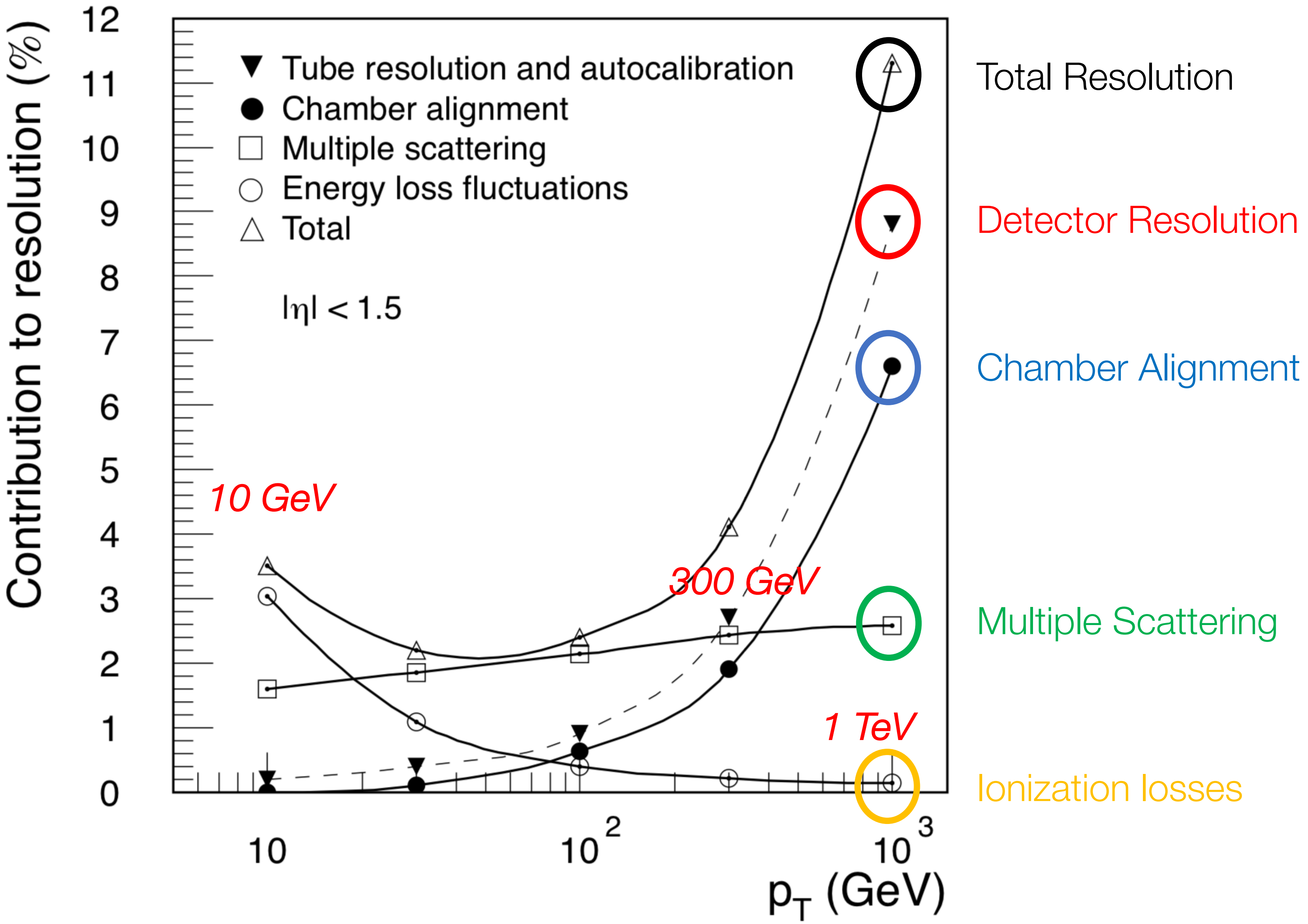
- Alignment of detector elements
- Energy losses when a charged particle (muon) traverses material.

At a p_T of ~10 GeV the dominant contribution is ionization loss and multiple scattering

For muons!

At a p_T of ~ 300 GeV multiple scattering and detector resolution are equally important

At a p_T of ~ 1 TeV detector resolution is most important effect



Energy Measurement in Calorimeters

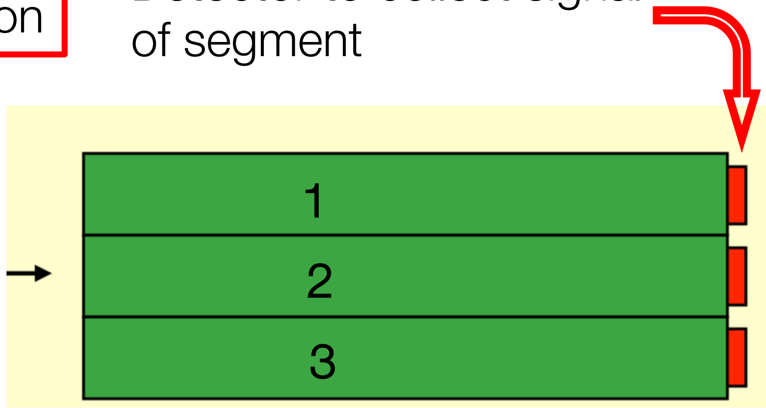
- A destructive measurement: a large number of nuclear and/or EM processes in a dense medium.
- Showers; Shape depends on material and on particle → identify!

There are two types of calorimeters:

Convert signal into energy of primary particle → calibration

- Homogeneous calorimeters:
  - A transparent material (scintillating crystals or high density glasses emitting Cerenkov light) absorbs the energy and measure it.
  - *All charged particles in a shower seen → best energy resolution.*
  - Uniform response in all points.
  - Costly, can be hardly segmented (→ total energy, not shape).
  - Used for electro-magnetic calorimeters → electrons and photons

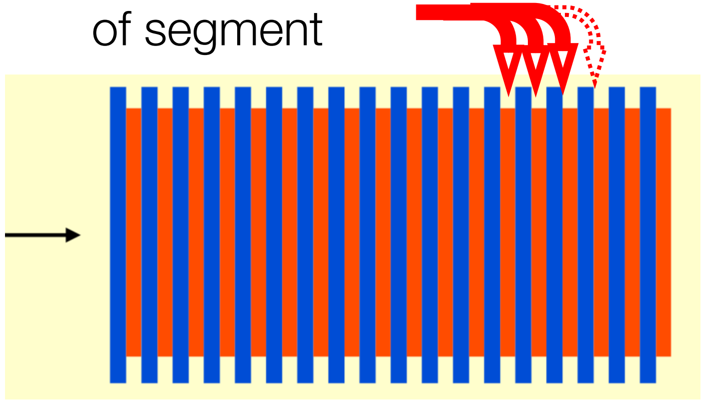
Detector to collect signal of segment



- Sampling:
  - Sampling between dense material and detectors.
  - Often sandwich type structure (absorber / detector) but also fibres.
  - Limited cost, segmentation.
  - *However only a fraction of energy is detected → limited resolution.*

  $f_{sampling} = E_{detected} / E_{total}$ Generally used for hadrons

Detector to collect signal of segment



Dimensions of Calorimeters

A characteristic parameter (→used material) determines the development of showers

- electrons/photons: Radiation Length (EM interactions)
- hadrons showers the Interaction Length (Hadronic interactions)

	Typical Length	Longitudinal Size (95% containment)	Transverse Size (95% containment)
EM Showers	Radiation Length $X_0 \sim \frac{A}{Z^2}$ $if A \approx Z \rightarrow$ $X_0 \sim 1/A$	15 to 20 X_0	~2 X_0
Hadron Showers	interaction length $\lambda_{int} \sim A^{1/3}$	6 to 9 λ_{int}	1 λ_{int}

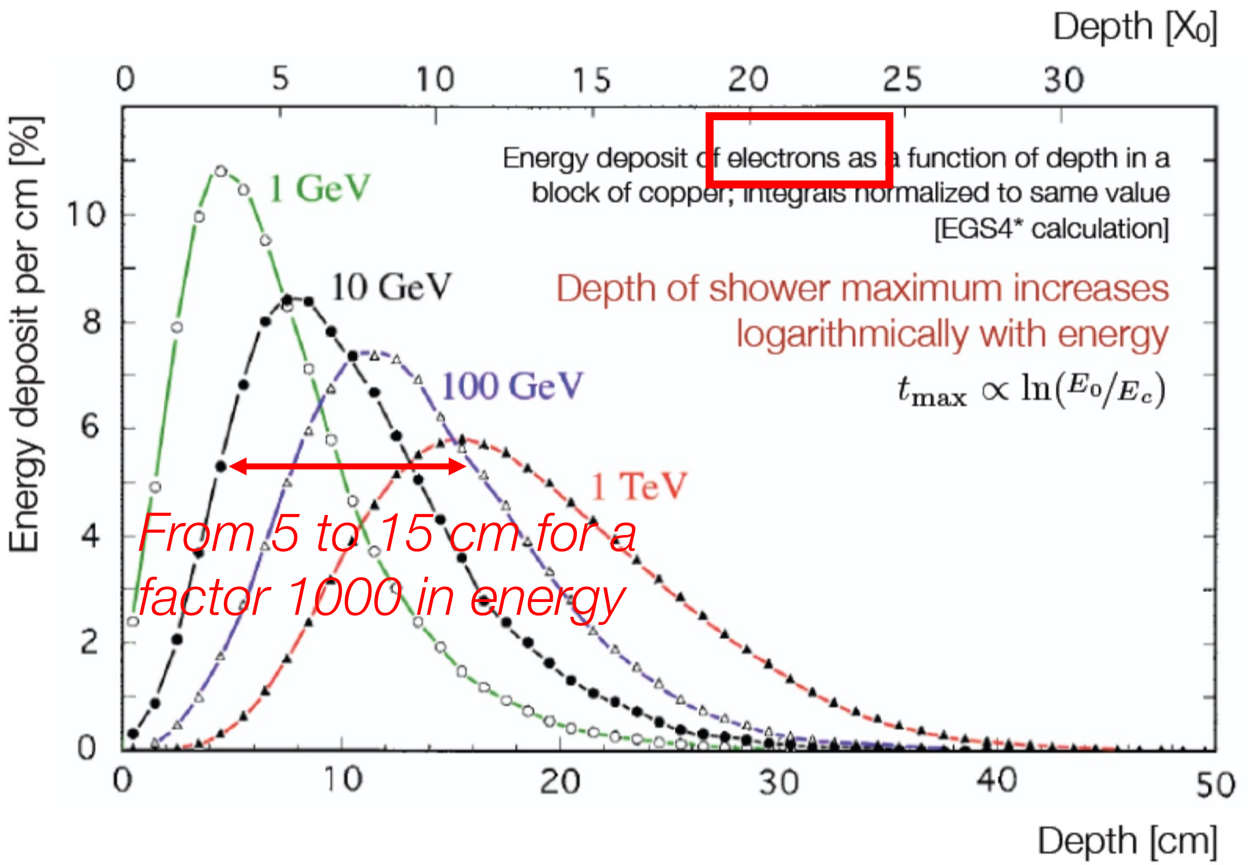
$$\lambda_{int}/X_0 \approx A^{4/3} \rightarrow \lambda_{int} \gg X_0$$

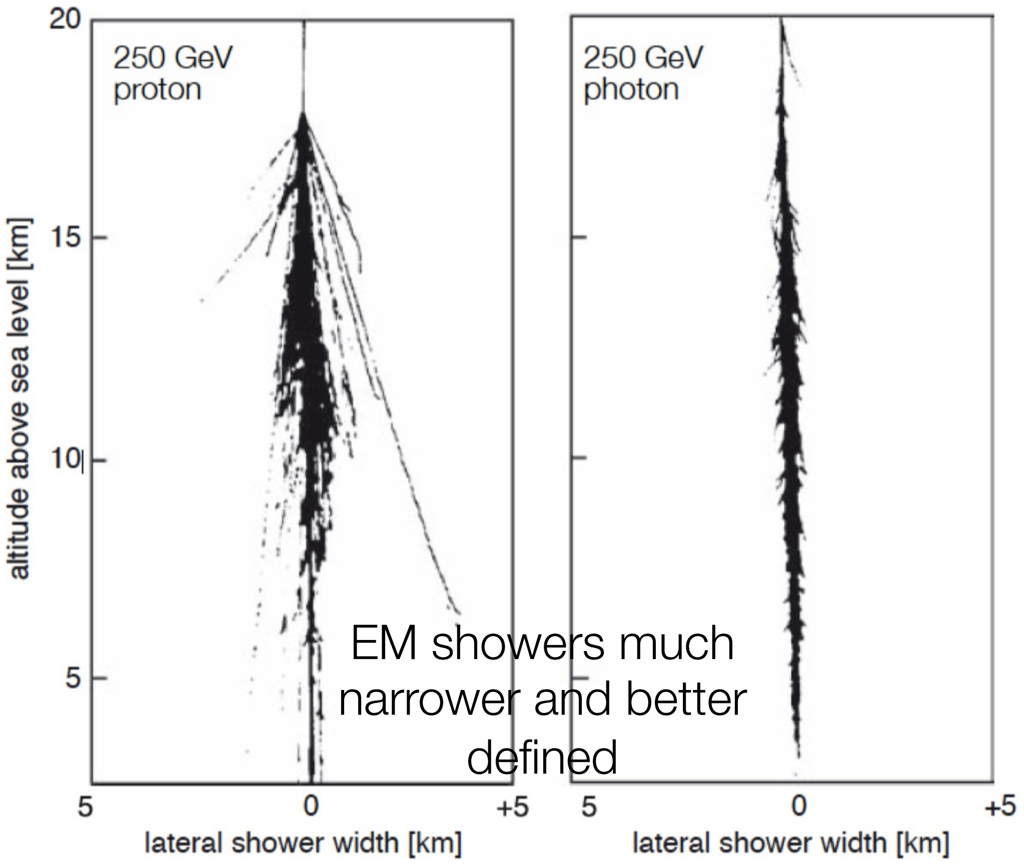
	λ_{int} [cm]	X_0 [cm]
Scint	79.4	42.2
LAr	83.7	14.0
Fe	16.8	1.76
Pb	17.1	0.56
U	10.5	0.32
C	38.1	18.8

→ Hadron calorimeters much longer than EM calorimeters.

- The length of showers ~ log(primary energy)
- → Calorimeters contain showers in large range of energies

The Shower Development





Simulated lateral development of showers in air

Calorimeters & Test Beams

A calorimeter signal S measured ∝ number N of nuclear interactions ∝ energy E.

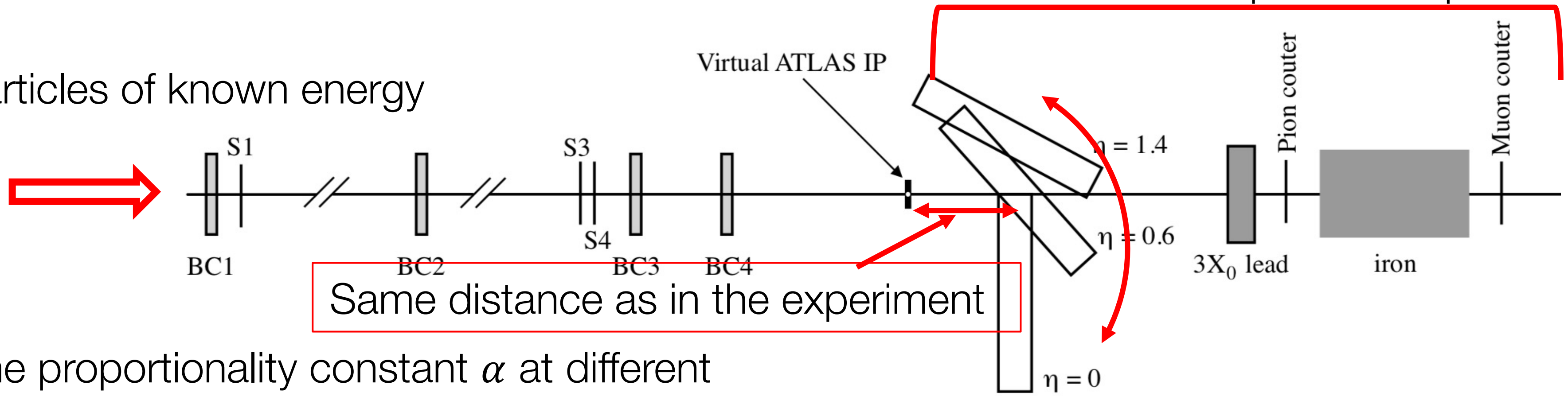
$$S = \sum nuclear\ interactions = \alpha \cdot E$$

α converts the calorimeter signal into energy. α has to be determined.

One method is based on test beam(s).

Mimic the same set-up of the experiment

Beam of known particles of known energy



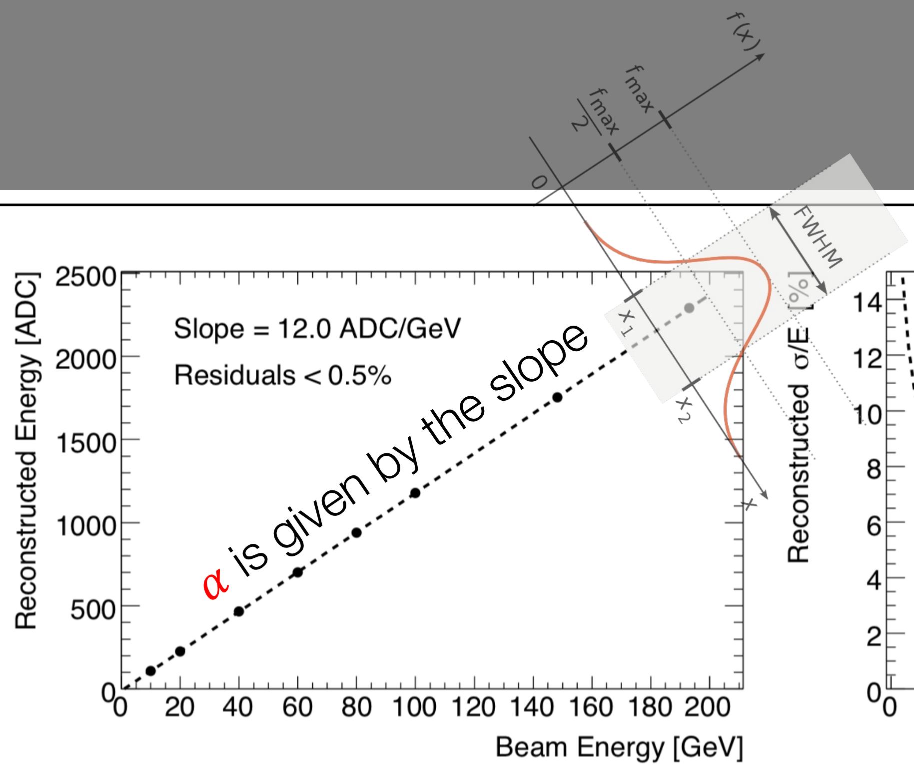
Same distance as in the experiment

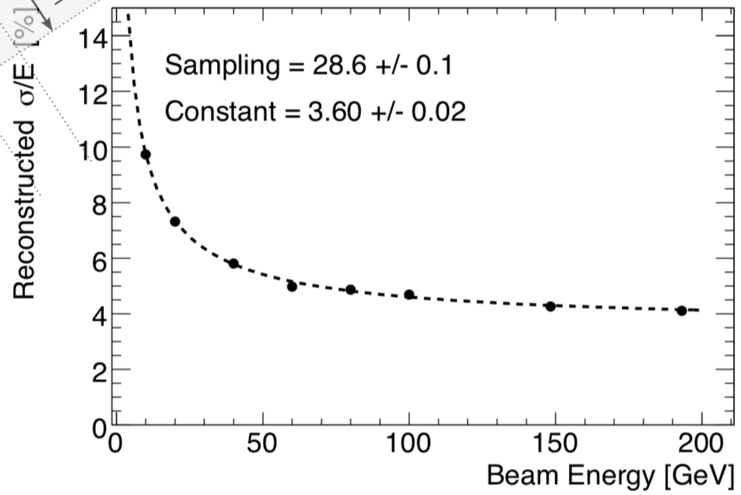
- You measure the proportionality constant α at different incoming energies and check if it does depend on energy (should not!) → *linearity*
- You measure the spread of the signal for a given energy → *resolution*

Rotating LAr EM calorimeter prototype of ATLAS

Energy Response

- The figure → the response of a calorimeter to beam particles of different energies is linear
- The distribution of the signal at a given energy gives the ‘resolution’.





The signal of a shower is linear with energy, the resolution decreases with energy

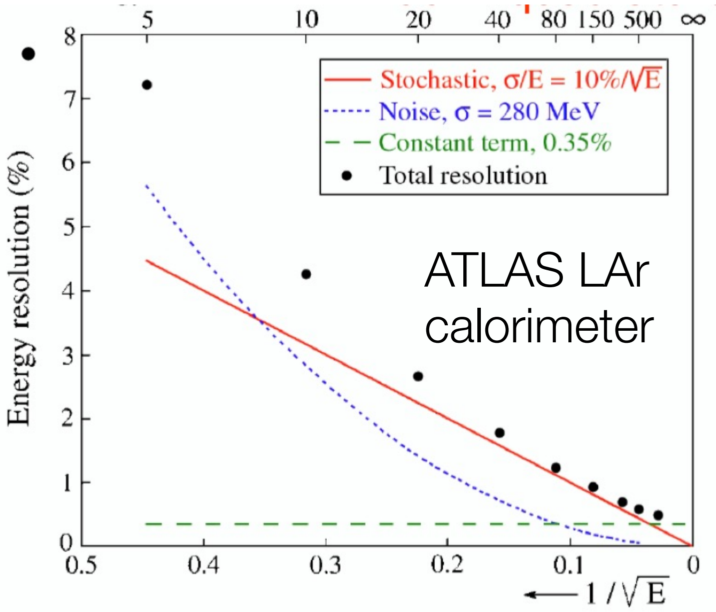
$$\frac{\delta E}{E} \approx \frac{dN}{N} \approx \frac{\sqrt{N}}{N} = \frac{const}{\sqrt{E}}$$

Decreases with energy

In real life the resolution is subject to several effects and they have to be combined quadratically → a more complex parametrisation is normally used:

$$\sigma_{tot}^2 = \sigma_{stat}^2 + \sigma_{lekeage}^2 + \sigma_{electronic\ noise}^2 + \sigma_{non\ uniformities}^2$$

$$\frac{\sigma_{stat}}{E} = \frac{a}{\sqrt{E}} \quad \frac{\sigma_{lekeage}}{E} = \frac{b}{\sqrt[4]{E}} \quad \frac{\sigma_{electronic\ noise}}{E} = \frac{c}{E} \quad \frac{\sigma_{non\ uniformities}}{E} = d$$

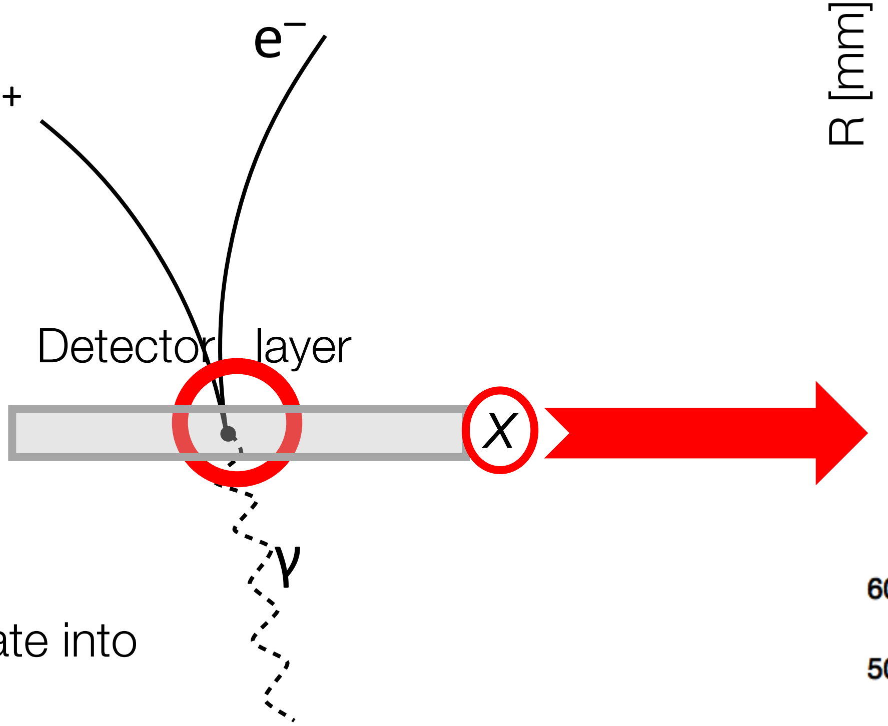


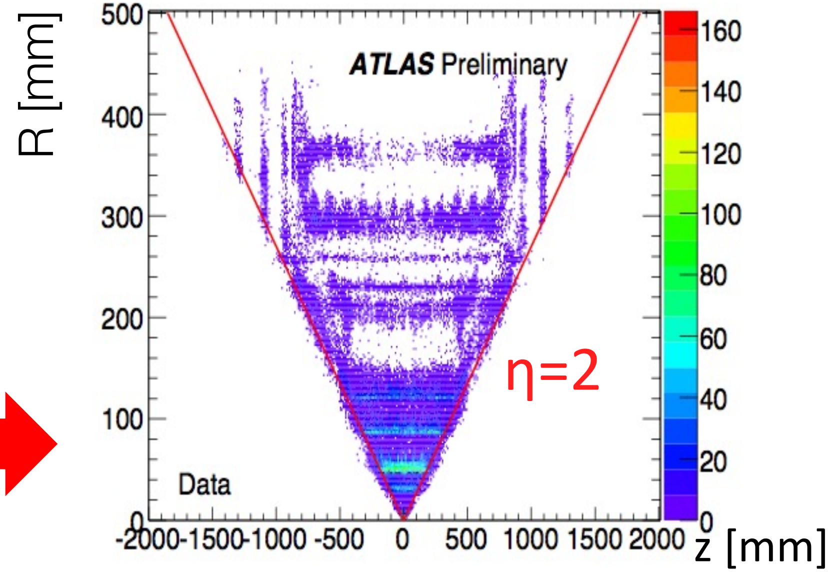
Dead Material: how to Measure it?

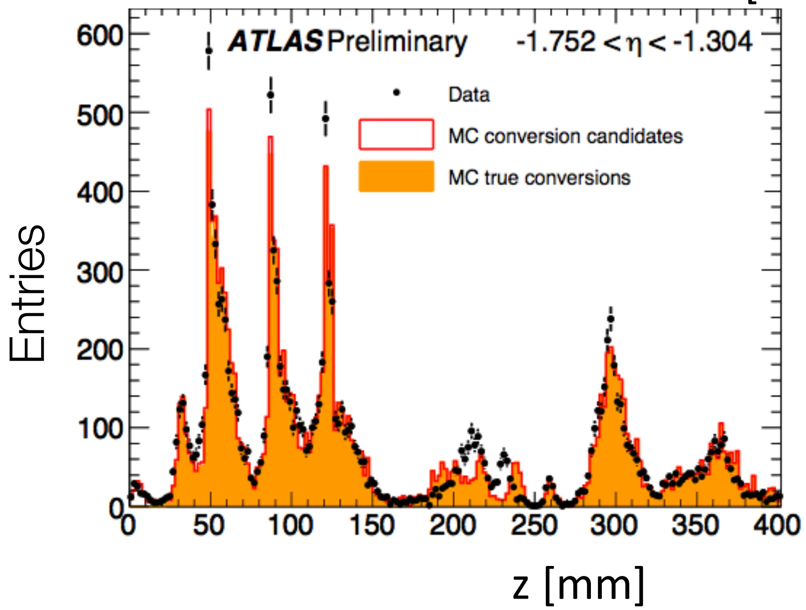
... via photon conversion

Selection:

- Two oppositely charged tracks with $p_T > 0.5$ GeV
- Small distance between tracks
- Good vertex; zero opening angle
- Well reconstructed tracks







Fraction of converted photons translate into radiation length

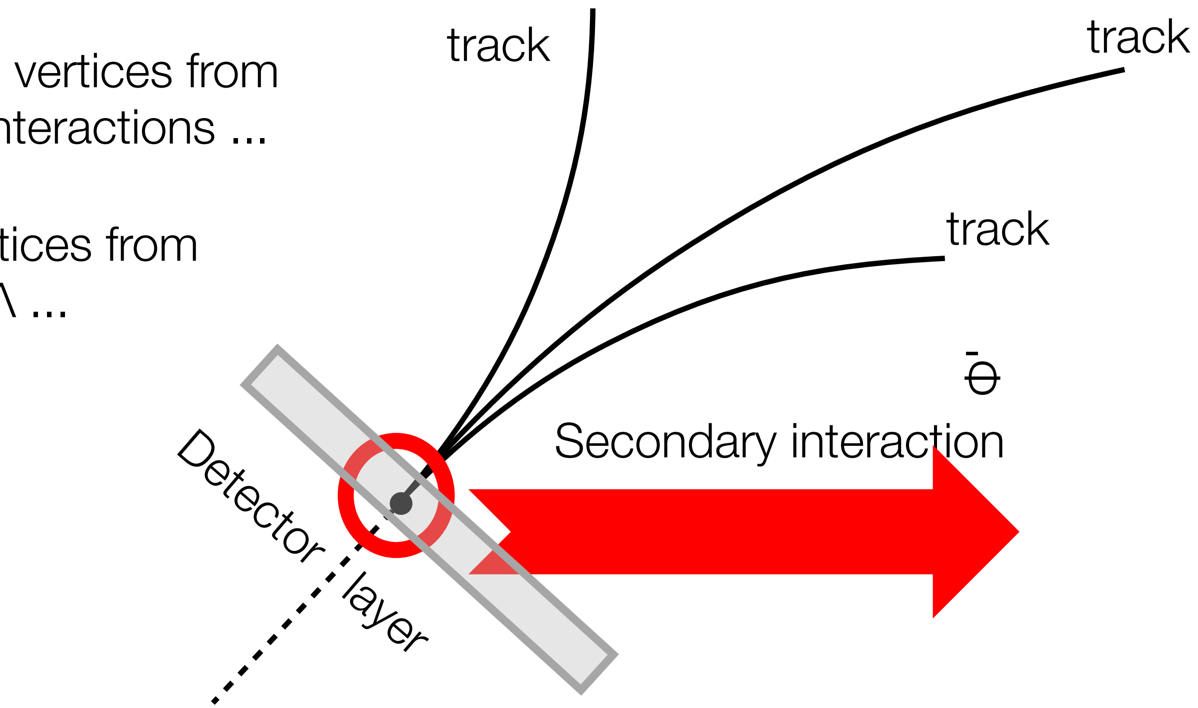
$$\frac{X}{X_0} = -\frac{9}{7}\ln(1 - F_{\mathrm{conv}})$$

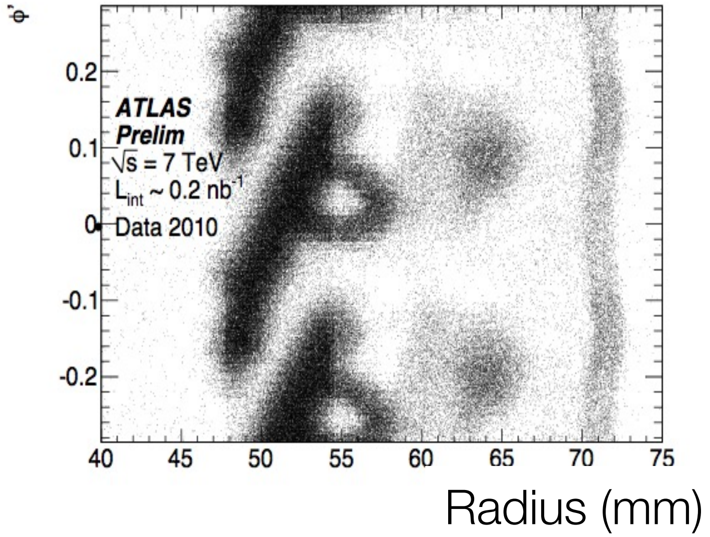
Hadronic Secondary Interactions

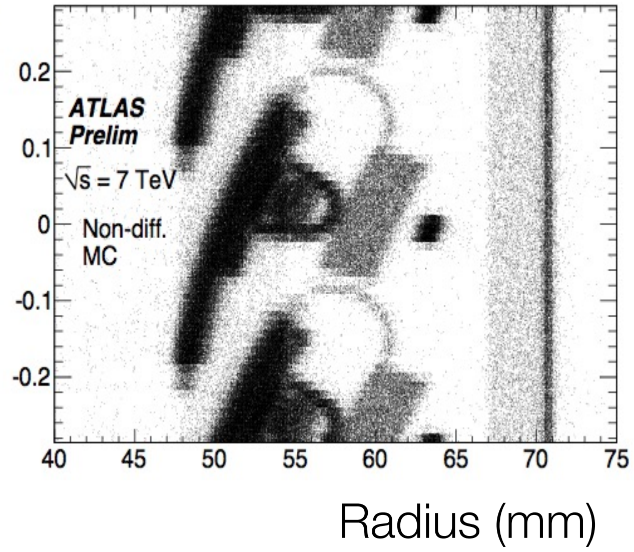
... via secondary vertices

Reconstruct vertices from secondary interactions ...

Remove vertices from Kaons and Λ ...

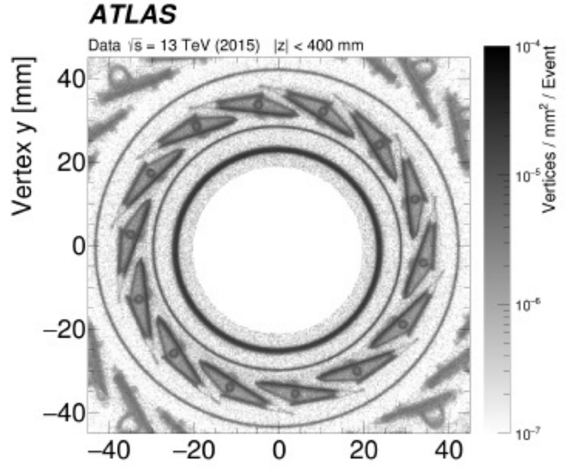






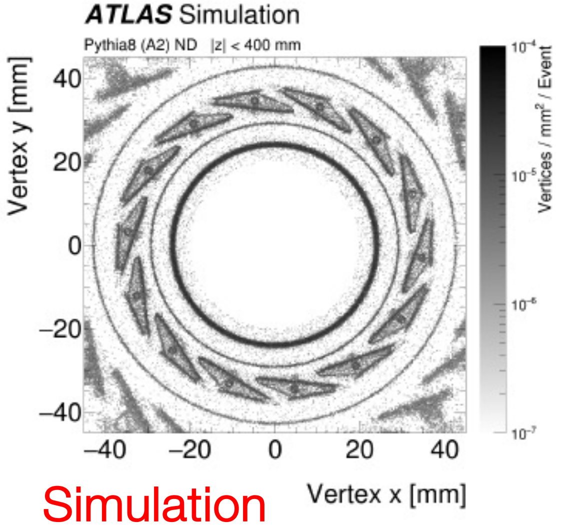
Radiography of the Detector

(a) , (b) The x -y view zooming-in to the beam pipe, IPT, IBL staves
(c) , (d) of the pixel detector.



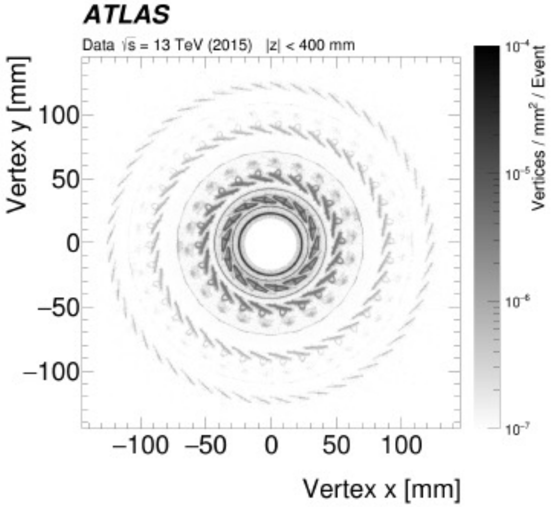
Data

(a)



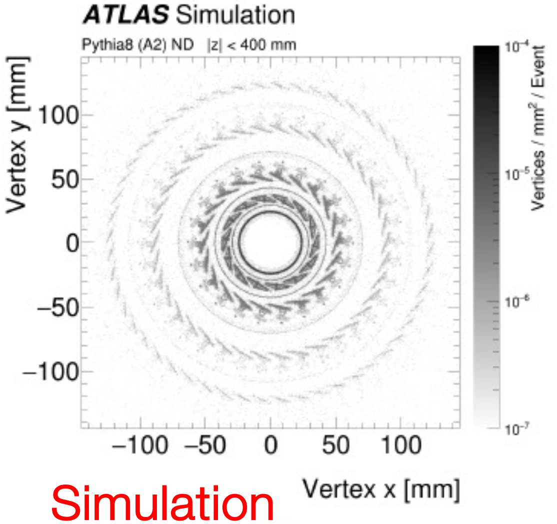
Simulation

(b)



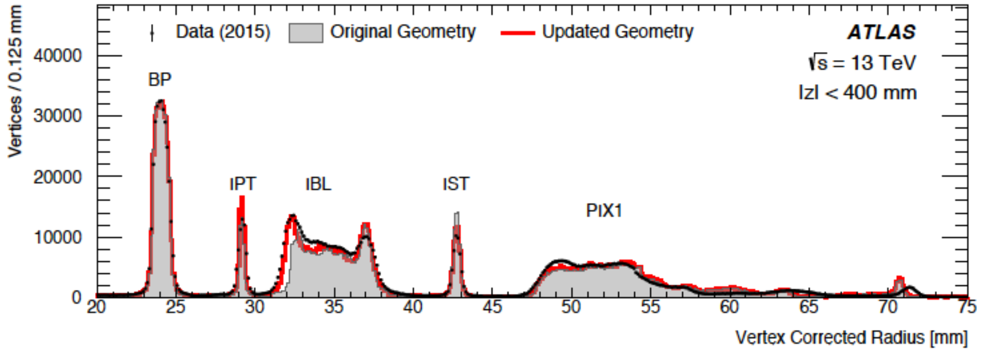
Data

(c)

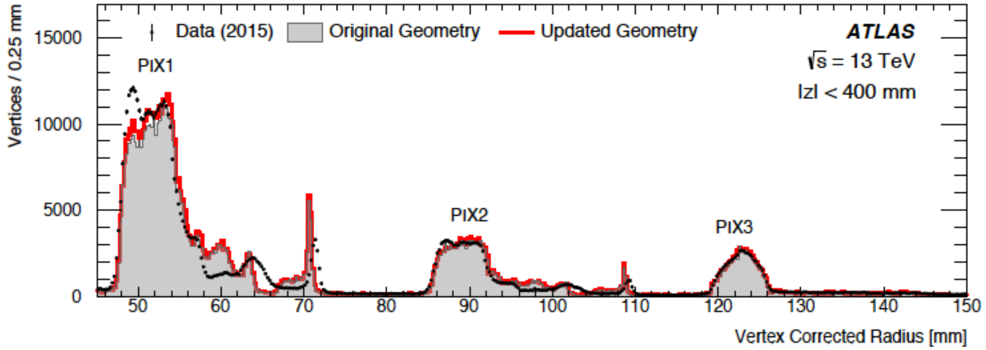


Simulation

(d)



(a) 20 mm < r < 75 mm.



(b) 45 mm < r < 150 mm.

Time Evolution of Material Budget

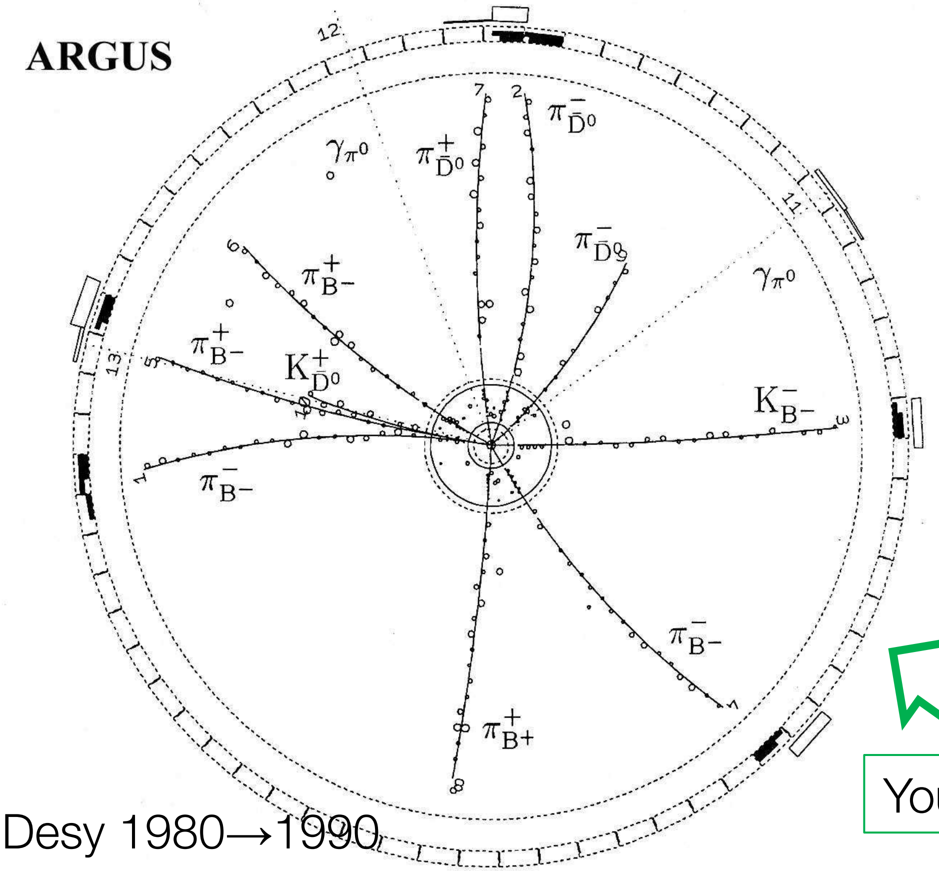
TABLE 5 Evolution of the amount of material expected in the ATLAS and CMS trackers from 1994 to 2006

	ATLAS		CMS	
Date	$\eta \approx 0$	$\eta \approx 1.7$	$\eta \approx 0$	$\eta \approx 1.7$
1994 (Technical Proposals)	0.20	0.70	0.15	0.60
1997 (Technical Design Reports)	0.25	1.50	0.25	0.85
2006 (End of construction)	0.35	1.35	0.35	1.50

The numbers are given in fractions of radiation lengths (X/X_0). Note that for ATLAS, the reduction in material from 1997 to 2006 at $\eta \approx 1.7$ is due to the rerouting of pixel services from an integrated barrel tracker layout with pixel services along the barrel LAr cryostat, to an independent pixel layout with pixel services routed at much lower radius and entering a patch panel outside the acceptance of the tracker (this material appears now at $\eta \approx 3$). Note also that the numbers for CMS represent almost all the material seen by particles before entering the active part of the crystal calorimeter, whereas they do not for ATLAS, in which particles see in addition the barrel LAr cryostat and the solenoid coil (amounting to approximately 2 X_0 at $\eta = 0$), or the end-cap LAr cryostat at the larger rapidities.

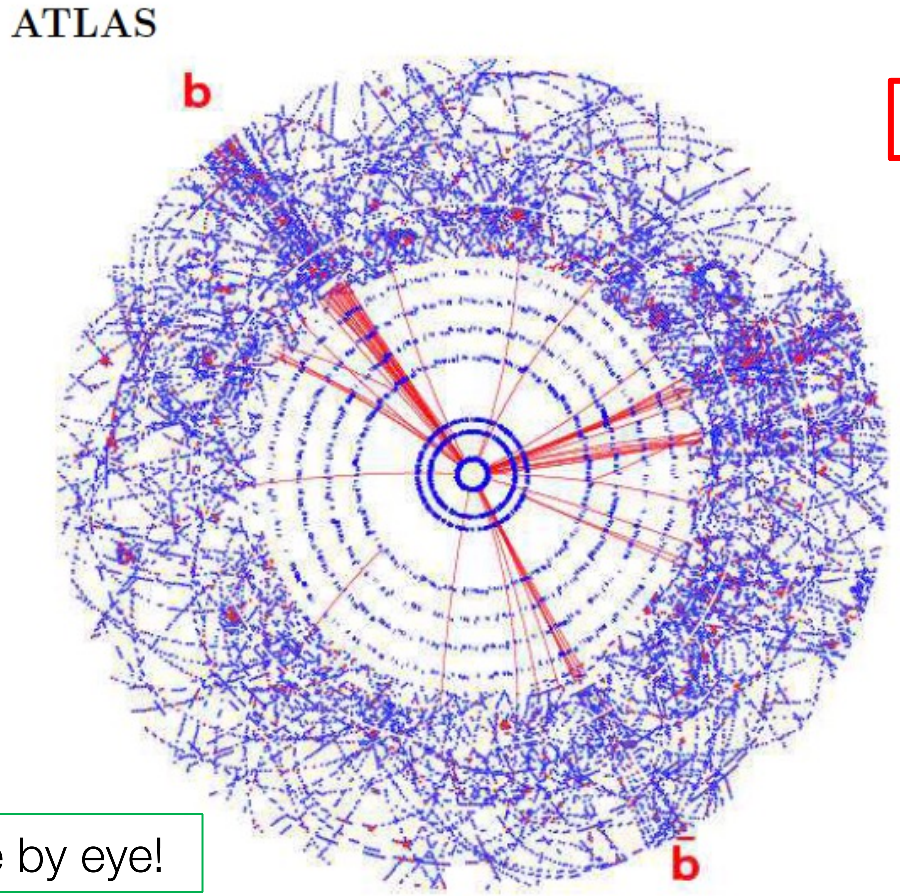
Pattern Recognition

How to find which measurements (*) (hits) make a track and have to be fitted to compute a trajectory?



@ Desy 1980→1990

You see by eye!



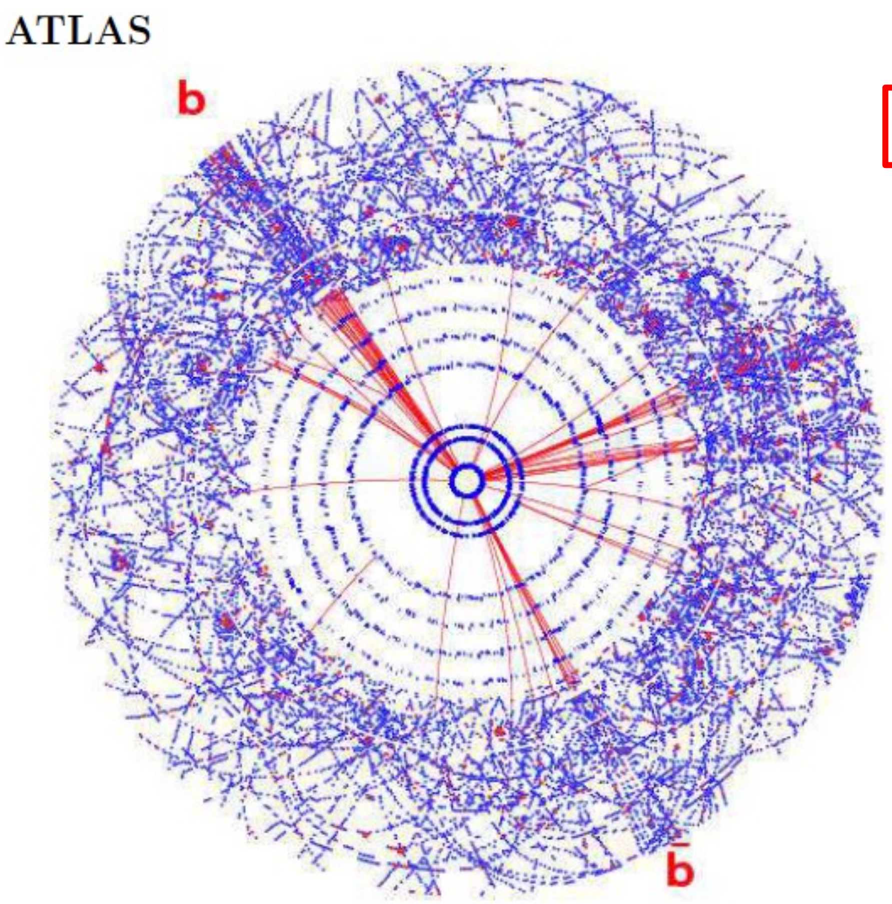
Invisible by eye!

Simulated event:
$H_0 \rightarrow bb$

(*) One possible set of track parameters:

$d_0, z_0, \phi_0, \vartheta_0, q/p$ (or tangent of the angles)

Complexity of Collider Experiments



Invisible by eye!

Simulated event:
$H_0 \rightarrow bb$

In modern Experiments, already at the time the experiment is designed, you need to consider/know

- How different detectors contribute to the analysis of one single *feature (=characteristic)*
- How your analysis programs will solve the problem of very crowded and complex topologies

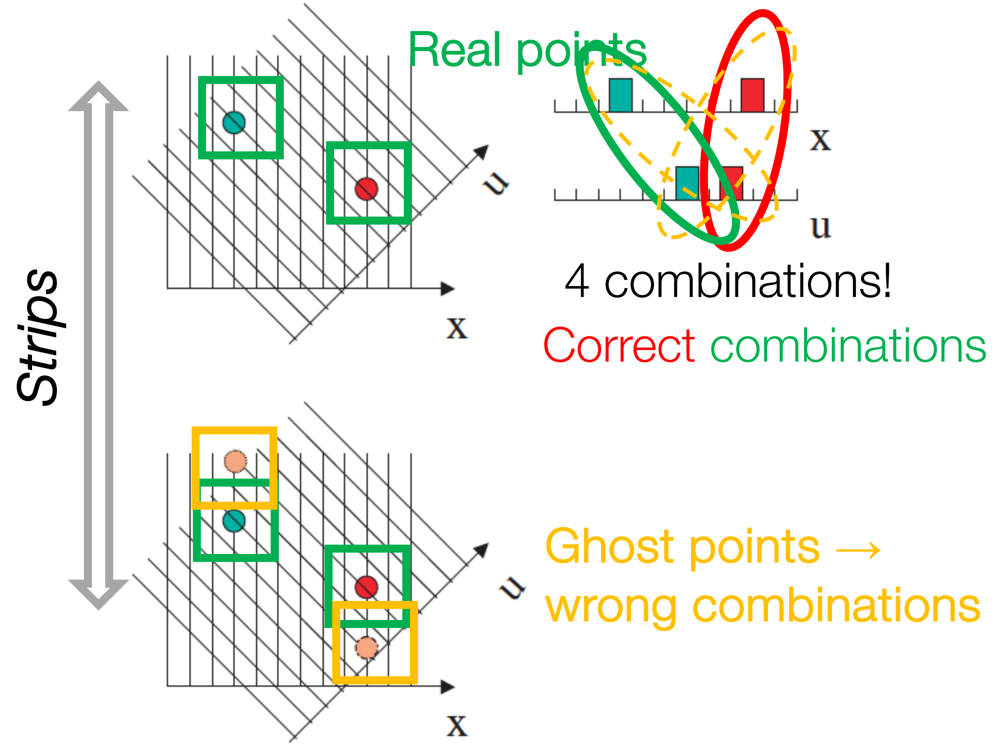
- → it is more and more difficult to think in terms of single/isolated detectors
- → it is more and more difficult to separate hardware and analysis programs

One Experiment = undistinguishable ensemble of many detectors and of analysis programs

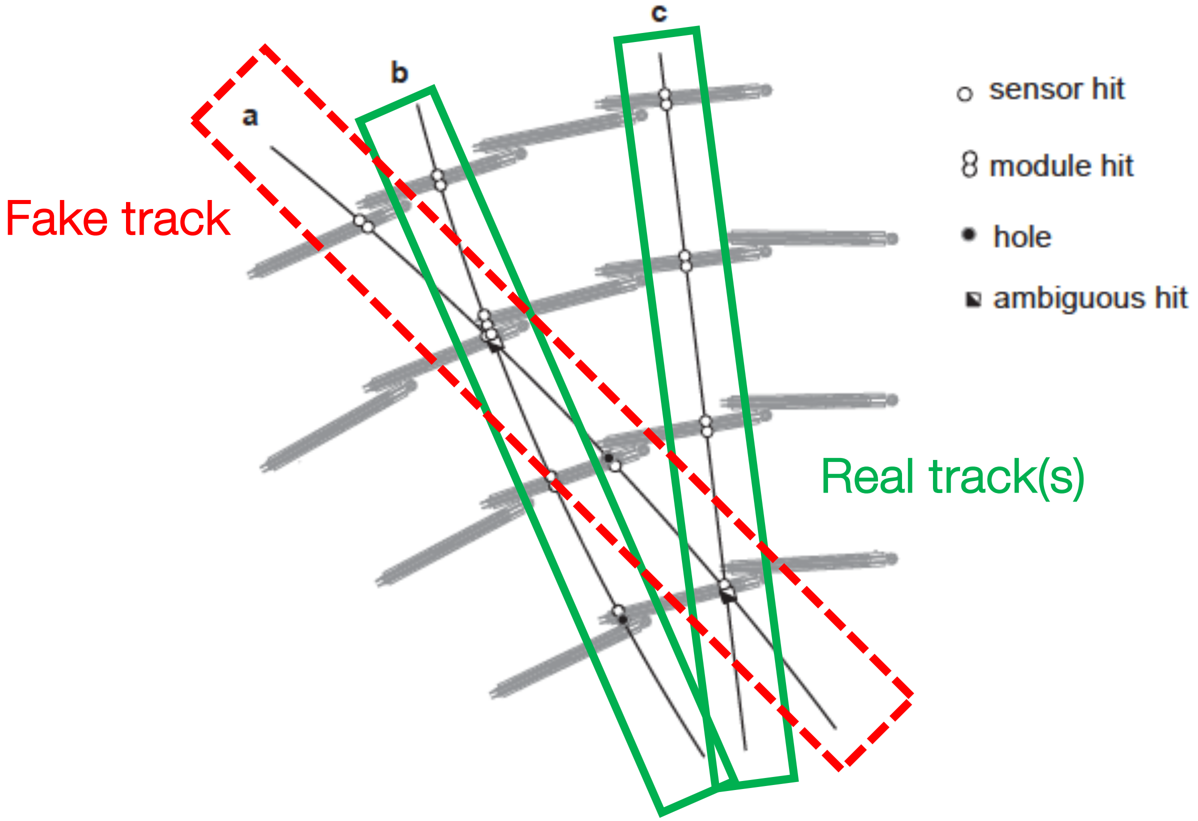
Ambiguities in Pattern Recognition (~History)

How to find which measurements (*) (hits) make a track and have to be fitted to compute a trajectory?

In some cases you may arrange your detector to give you an indication → u,v geometry

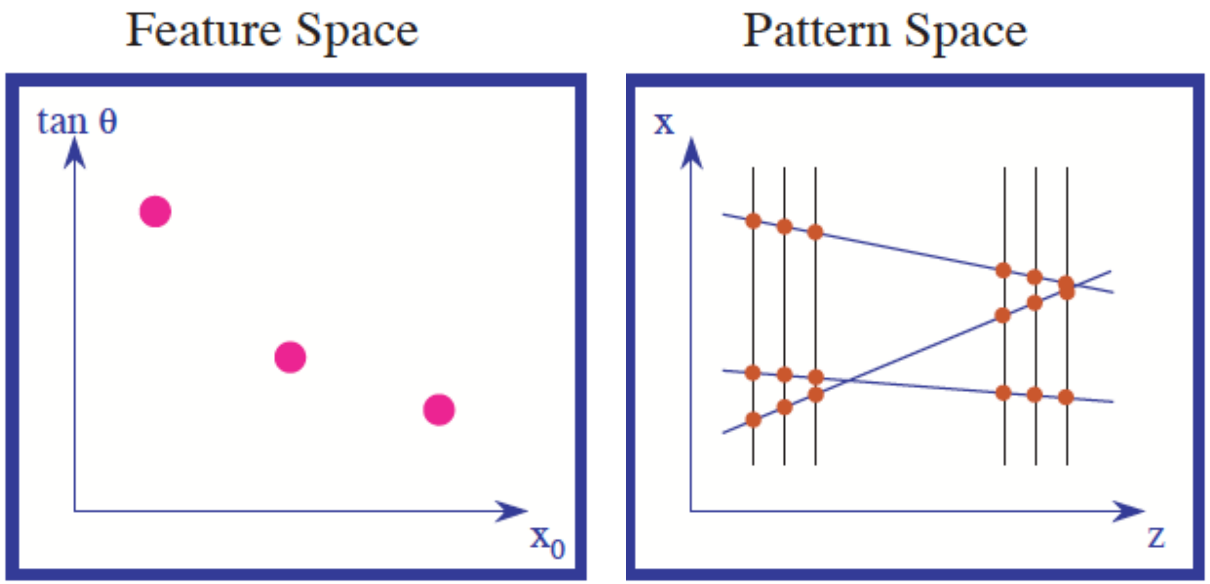


In some other cases you may have to 'score' your points



(*) One possible measurement: (impact parameter, direction and momentum) $d_0, z_0, \phi_0, \vartheta_0, q/p$

Basic Ideas in Pattern Recognition

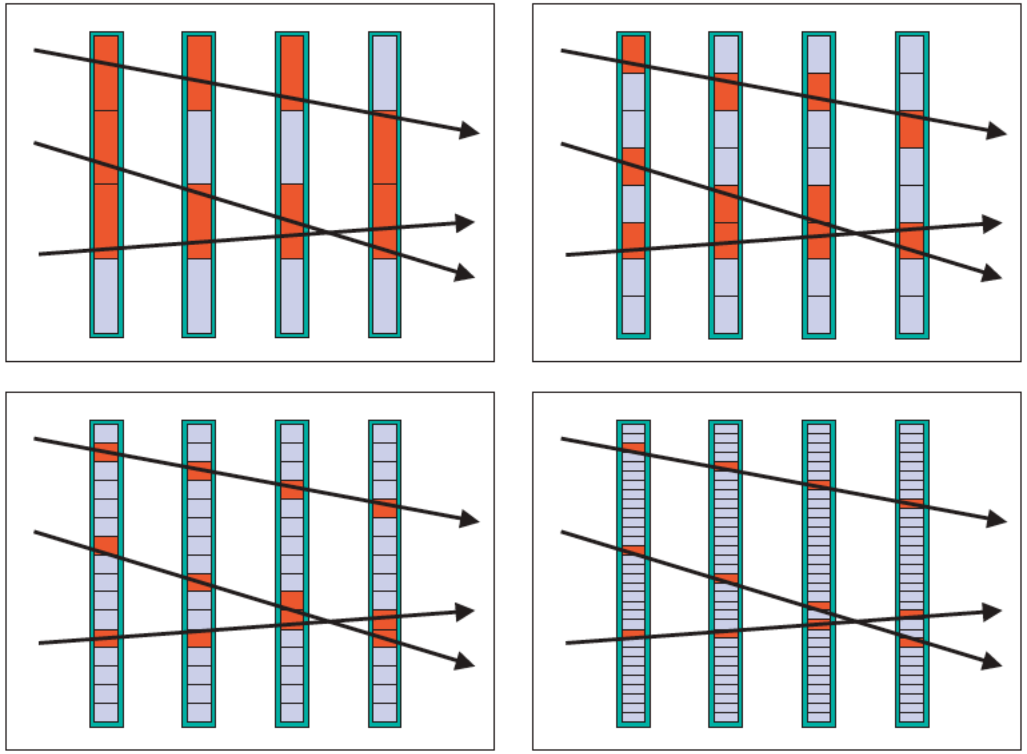


Three tracks are defined by tan(θ) and x_0

They appear like this in your detector

The goal of Pattern recognition is going from Pattern Space to Feature Space

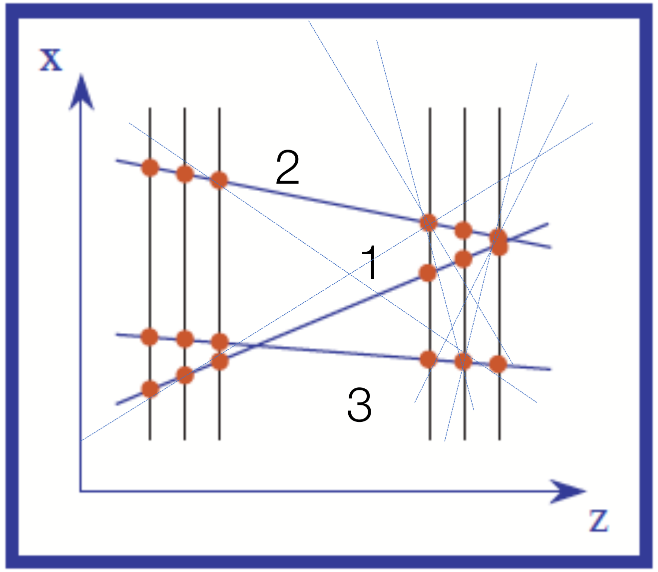
1. templates: if a limited set of topologies → create a 'road' and compare it with your measurements. A correct 'road' will include a large number of points. Works for simple and few topologies



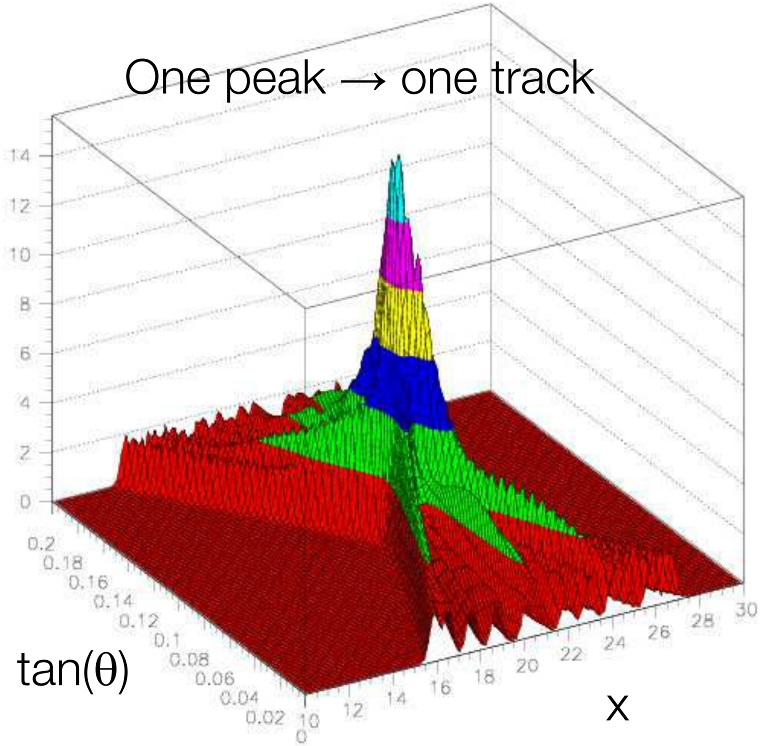
Templates are checked with increasing granularity

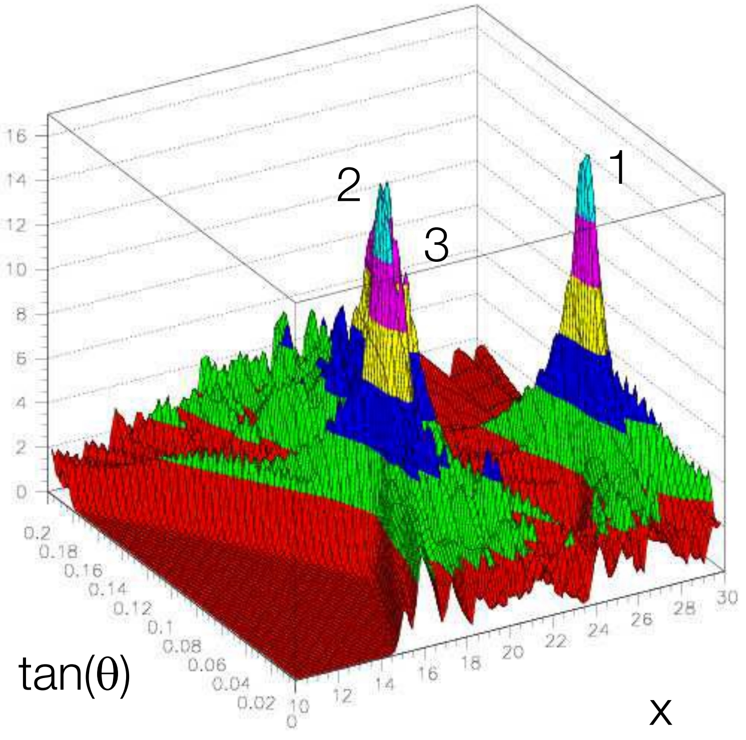
Hough Transform

Pattern Space



(only a few shown…)





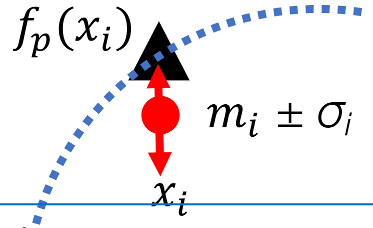
2. Hough transform.

- Join all possible pairs of points with a line characterised by tan(θ) and x_0 .
- each pair of hits in two dimensions becomes a line;
- real track, → many aligned points → same tan(θ) and x_0 → peak in the ‘Feature Space’.
- Wrong associations ~flat distribution.

→ one peak indicates one track → look for peaks

After Pattern Recognition: Track Fitting (~Old Way)

Use the least squares principle to estimate the kinematical parameters of a particle = track fitting.



Definition of "Chi Squared": $$\mathrm{X}^2 = \sum_i \frac{(m_i - f_p(x_i))^2}{\sigma_i^2}$$

Physical meaning: distance between fit function and hit normalised to measurement error

- measured points $m_i \pm \sigma_i$ (at position x_i) of a track have been correctly identified in the *pattern recognition step*.
- trajectory of a particle is described by an analytic expression f_p
  - p is the set of parameters → the momentum in B field is one parameter
  - $f_p(x_i)$ ▲ is the coordinate predicted by the function (*f* might be a circle in a solenoid or a straight line)

Find the set of parameters p that minimises the X^2

Meaning: you find which is the trajectory which minimises the difference^2 between all measurements and trajectory

Better approach: include also multiple scattering and energy losses

$$\chi^2 = \sum_{meas} \frac{r_{meas}^2}{\sigma_{meas}^2} + \sum_{scat} \left(\frac{\theta_{scat}^2}{\sigma_{scat}^2} + \frac{(\sin\theta_{loc})^2 \phi_{scat}^2}{\sigma_{scat}^2} \right) + \sum_{Eloss} \frac{(\Delta E - \overline{\Delta E})^2}{\sigma_{Eloss}^2}$$

$$r_{meas}^2 = residual^2 = (difference\ measurement - function)^2$$

(~Modern) Pattern Recognition

In past experiments the track reconstruction consisted of two steps (possible in 'old' experiments):

- Pattern recognition
- Track fit

In modern track reconstruction, finding + fitting a track at the same time no clear distinction between pattern finding and track fitting.

As a consequence, the full chain of pattern recognition and track fitting will be a single unit.

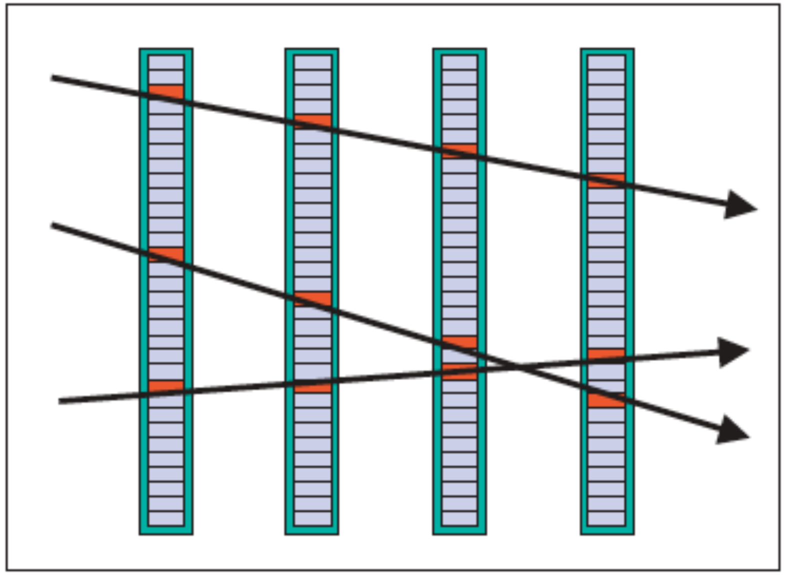
The ATLAS / CMS track finding / fitting currently consists of three sequences

1. the *main inside-out track reconstruction* (start with a seed defined by the beam spot and the innermost hits of the vertex detector)
2. Followed by a consecutive outside-in tracking (recover ~unused / unassigned hits)
3. As a third sequence, the pattern recognition for the finding of V_0 vertices, kink objects due to bremsstrahlung and their associated tracks follows

Track Fitting and Kalman Filter (~ Modern Way)

The χ^2 method is not always convenient:

1. You need to have all points attributed to one track ***before*** the fit
2. It is expensive in terms of computing-time: a large number of points have to be handled in the χ^2 fit: # measurements x # parameters of each measurement
3. to be repeated for many tracks! $N_{tracks} \cdot N_{hits} \cdot N_{parameters}$



→ *use pattern recognition methods which are based on* ***track following****, where it is not clear a-priori the right hit combination*

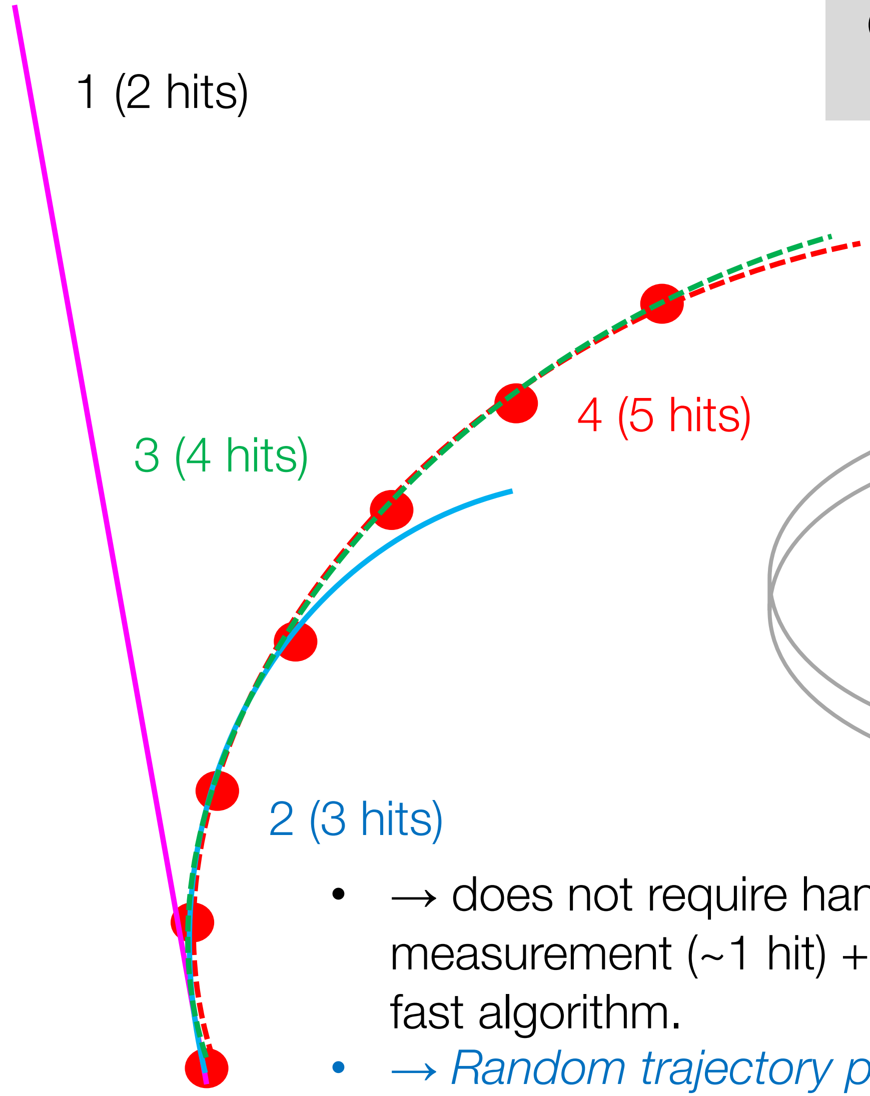
track following == the path is not clear a-priori → the direction becomes clearer as you follow the trajectory → Kalman filter technique

The Kalman filter proceeds progressively from one measurement to the next, improving the knowledge about the trajectory with each new measurement.

With a traditional global fit, this would require a time consuming complete refit of the trajectory with each added measurement.

Kalman Filter in a Cartoon

Goal: compute X, observable using a sequence of measurements (k=1,2… indicates successive measurements/states)



Kalman filter is an iterative procedure

- Starts from a seed (2 hits)
- Extrapolates and includes next hit; accounts for material, multiple scattering, energy loss
- Recalculates track parameters, refines extrapolation

Hits left?

Yes — No

- → does not require handling of all k+1 hits, only one measurement (~1 hit) + parameters of state before → very fast algorithm.
- *→ Random trajectory perturbations, (multiple scattering or energy loss) can be accounted for efficiently.*

$$x_k = F_k \cdot x_{k-1}$$

x_{k-1}: ‘state’ at ‘time k-1’
F_k: ‘Transfer matrix’
x_k: ‘new state’ at ‘time k’

Kalman Filters

Kalman Filter approach consists of two steps:

- The prediction step: extrapolate current trajectory (state vector) to next measurement from the → discard noise signals and hits from other tracks.
- The transfer step, which updates the state vector

System state vector at the time k includes k-1 measurements and contains the parameters of the fitted track, given at the position of the k^{th} hit (including hits before!)
The corresponding measurement errors covariance matrix (*contains measurement errors*) by C_k.
The matrix F_k describes the propagation of the track parameters from the $(k-1)^{th}$ to the k^{th} hit.

Example: planar geometry with one dimensional measurements and straight-line tracks

$t_x = \tan\theta_x$ the track slope in the xz plane,

F_k = transfer matrix

$$x_k = F_k \cdot x_{k-1}$$

State vector @ measurement k

$$\begin{pmatrix} x \\ t_x \end{pmatrix}_k = \begin{pmatrix} 1 & z_k - z_{k-1} \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ t_x \end{pmatrix}_{k-1}$$

State vector @ measurement k-1

$$\rightarrow x_k = x_{k-1} + t_x \cdot (z_k - z_{k-1})$$

$$\rightarrow t_k = t_x @ k-1$$

Propagation of States

The extrapolation from one state to another (in page before) is valid in general:

$$x_k = F_k \cdot x_{k-1}$$

The transfer matrix F_k transports the state x_{k-1} (at the measurement point 'k-1') to the next state x_k at measurement point k

Error on track parameters

$$C_k = F_k \, C_{k-1} \, F_k^T + Q_k$$

- C_k is the error matrix extrapolated from the state x_{k-1} (generally called Covariance Matrix). It contains errors on measurements (diagonal terms) but also the correlation among different terms.

A new term appears: Q_k is due to 'random' perturbations to the particle trajectory (mostly) multiple scattering

→ ~ *exact knowledge of material distribution*

1. We extrapolated the state x_{k-1} from measurement k-1 to state x_k at measurement point k
2. We have to include new measurement k. The formalism is a bit complicated and can be found in reference (*)

A Kalman-Filter approach is used in modern collider experiments

(*) Pattern Recognition and Event Reconstruction in Particle Physics Experiments: R. Mankel1

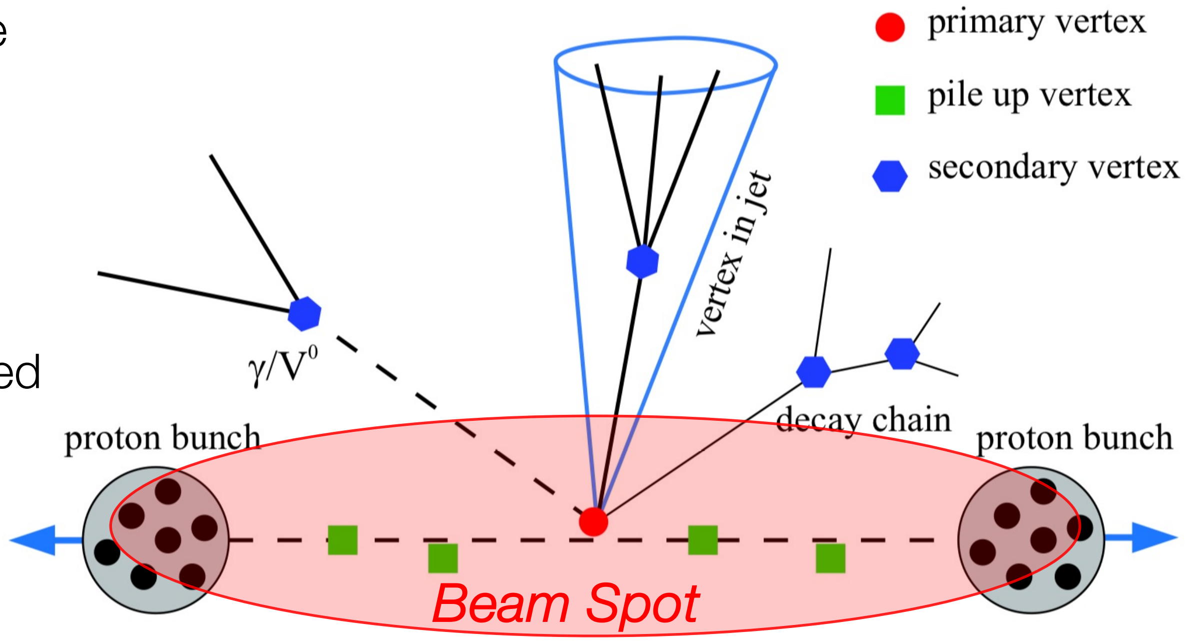
Vertices in Events Produced at LHC

The recording of one event is started by the 'trigger system' that detects 'interesting characteristics'
→ primary vertex

→ during the time window of the trigger more than one interaction takes place → Pile-up vertices *(next slide)*

Collision event:

- One primary vertex from the hard inelastic collision
- Several pile-up vertices (pp interactions, superimposed to the *triggered* primary vertex)
- Secondary vertices are produced due to
  - ✓ Decay-chain: decays of long-lived b-particles decaying into c-particles (tertiary vertex)
  - ✓ (V^0) Decays of neutral particles (like photon conversions into electron pairs $\gamma \to e^+e^-$)

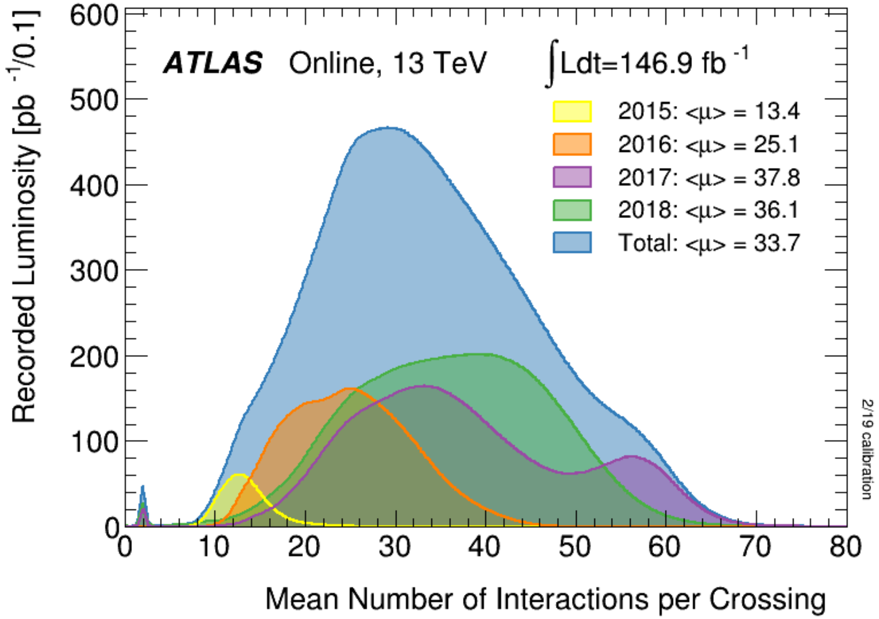


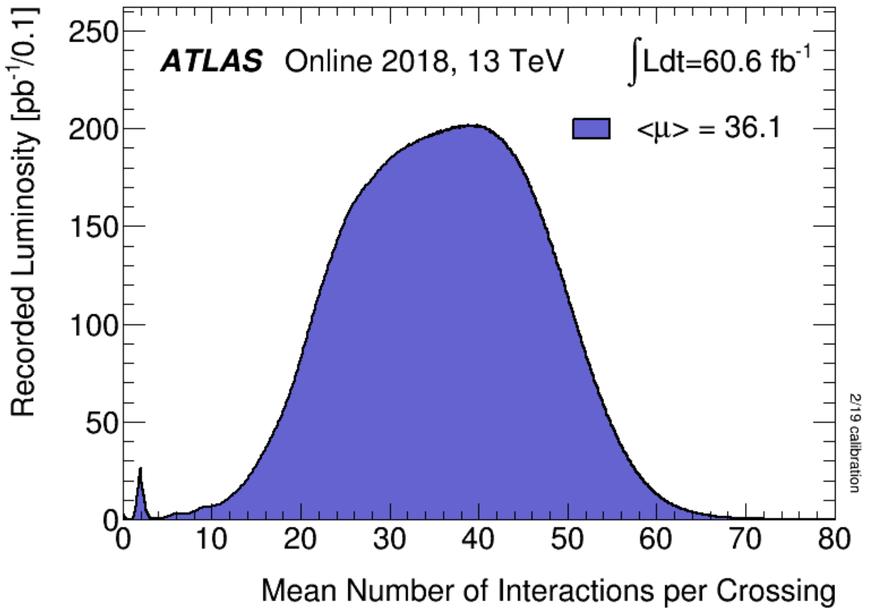
Pile-up

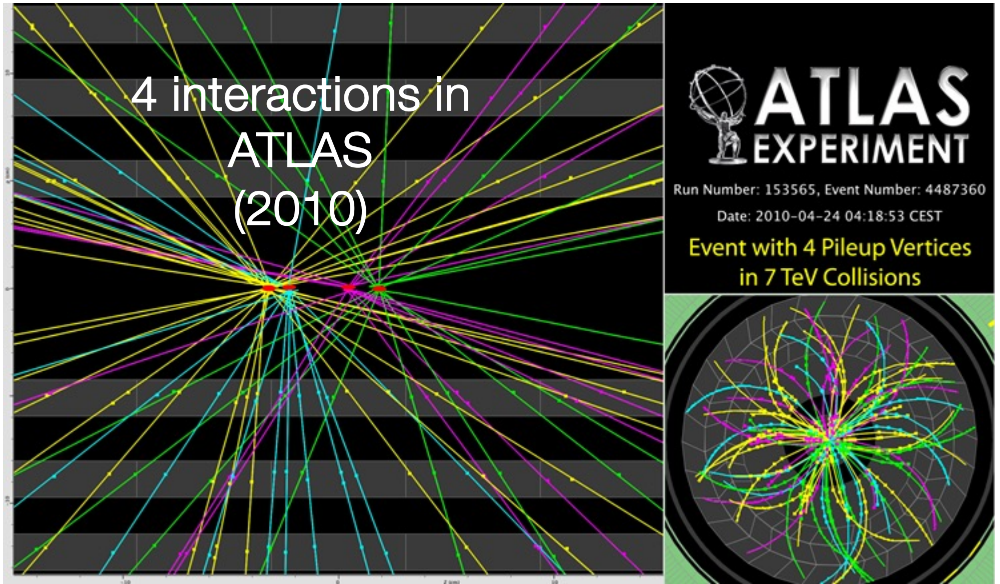
$\langle \mu \rangle = \langle Num. of\ interactions\ in\ 1\ bunch \rangle$

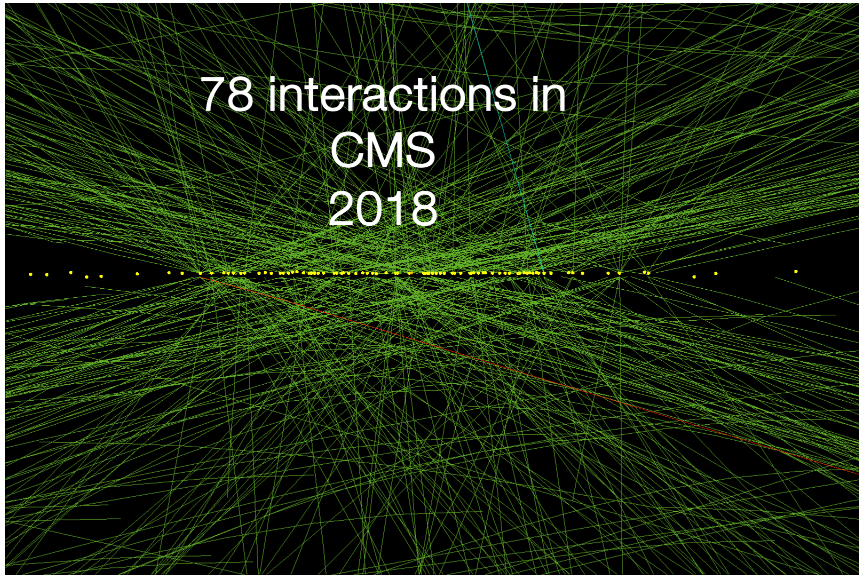
The luminosity (→ intensity of the beams at LHC) is so high than MANY interactions occur during the same bunch crossing. ~ Only one (at most) is interesting → hard inelastic collision)

FILTER EVENTS!









2015: <μ> = 13.4
2016: <μ> = 25.1
2017: <μ> = 37.8
2018: <μ> = 36.1
Total: <μ> = 33.7

Time ↑ Pile-up ↑

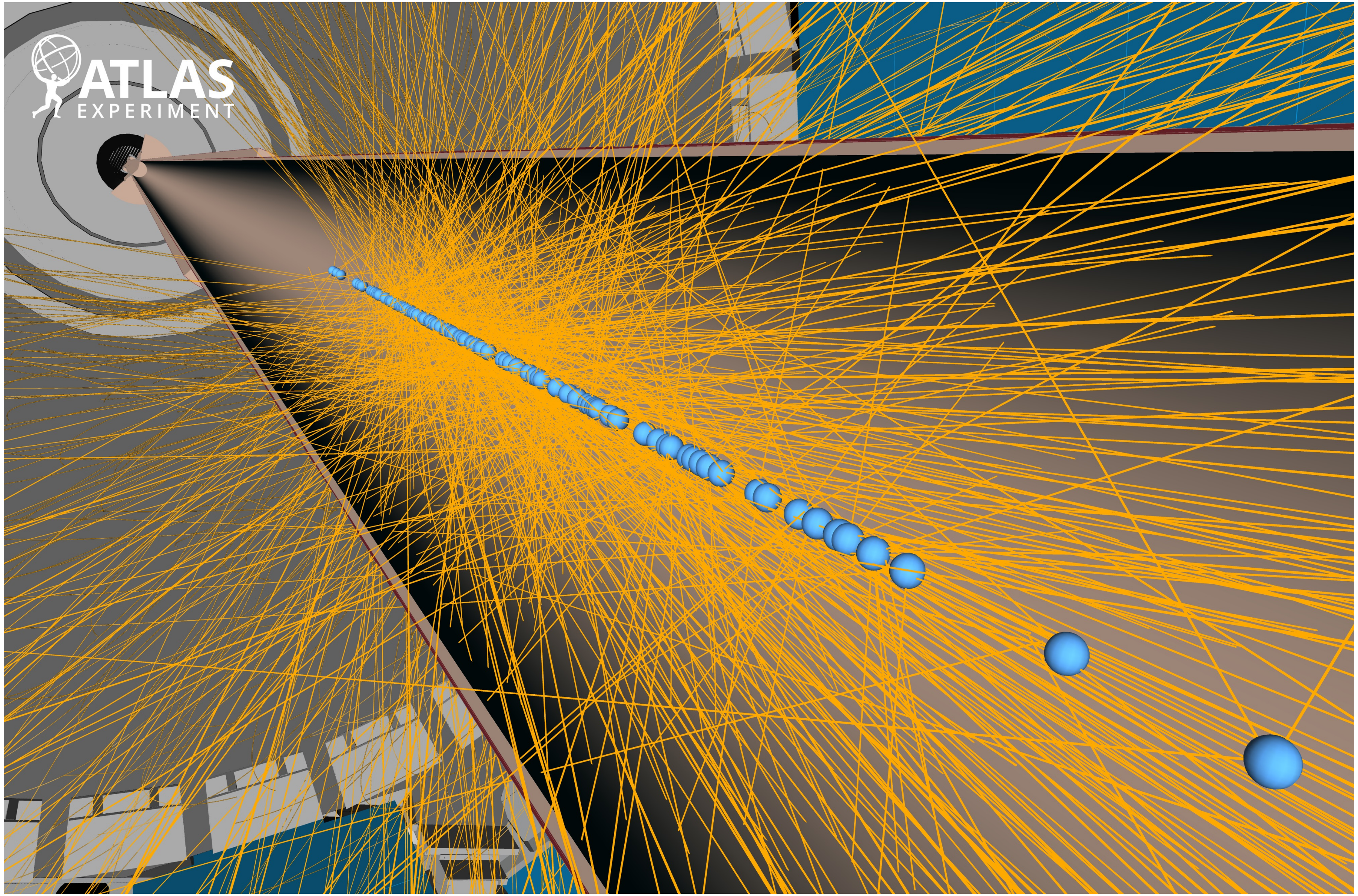
One simulated event with 88 reconstructed vertices

A visualisation of simulated $t\bar{t}$ quark pair production in a pp collision at

14 TeV HL-LHC

The simulated event includes approximately

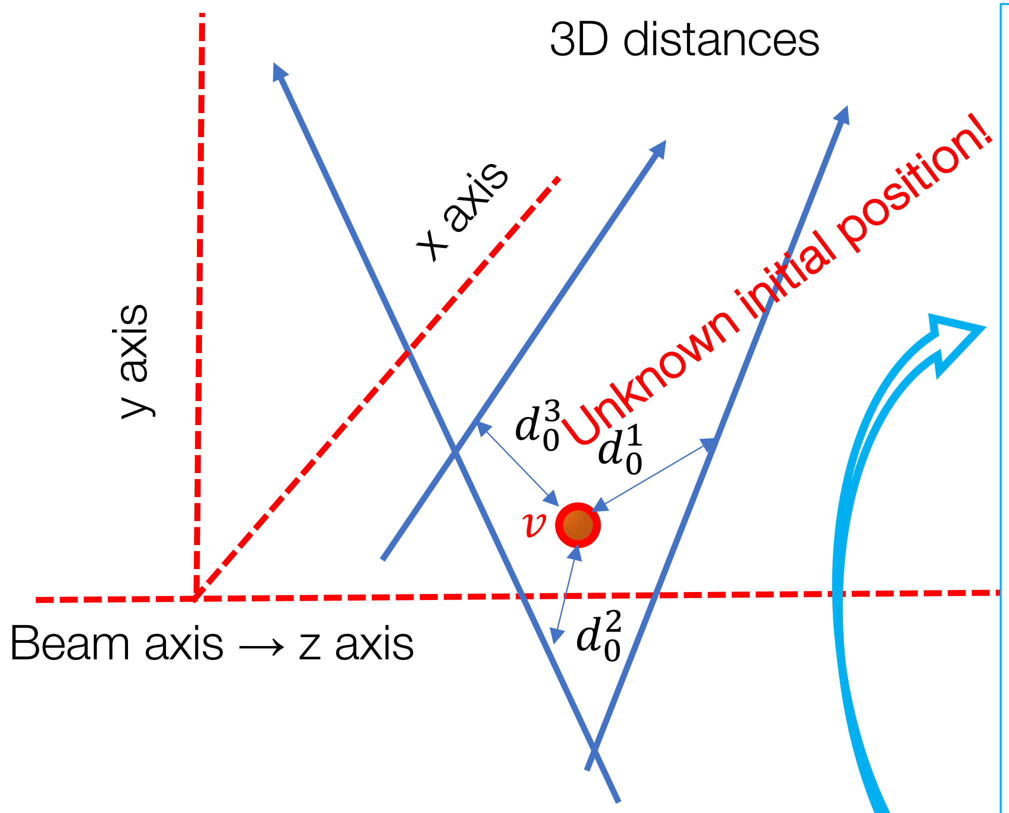
- **200 pileup interactions in the same bunch crossing**
- **88 primary vertices** (blue balls) reconstructed along the beam line.



Vertex Finding and Fitting

d_0^i = *distance of minimum approach of track i to 3D vertex* "v"

σ_i = *error on* d_0^i



What counts is the ratio d_0^i/σ_i

Vertex fitting: identification of a vertex and computation of its in 3D position.

distance of minimum approach d_0^i between good quality tracks to the vertex (*impact parameter*).

1. Start with a seed (beam spot of interaction region)
2. Compute distances of all tracks from vertex v and weight distances with a weight computed using formula

$$w_i\left(\chi_i^2\right) = \frac{\exp(-\chi_i^2/2T)}{\exp(-\chi_i^2/2T) + \exp(-\chi_c^2/2T)}.$$

3. Minimize

$$\frac{1}{2}\sum_{i=1}^{n} d_i^2(\boldsymbol{v})/\sigma_i^2$$

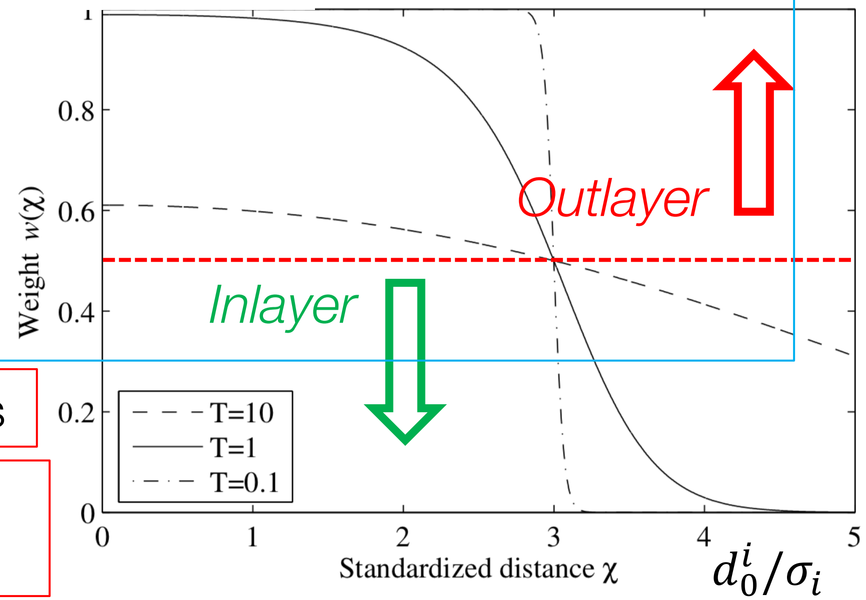
and find new v

4. Vertex $v_n = v_{n-1}$?

No → Lower T

Yes

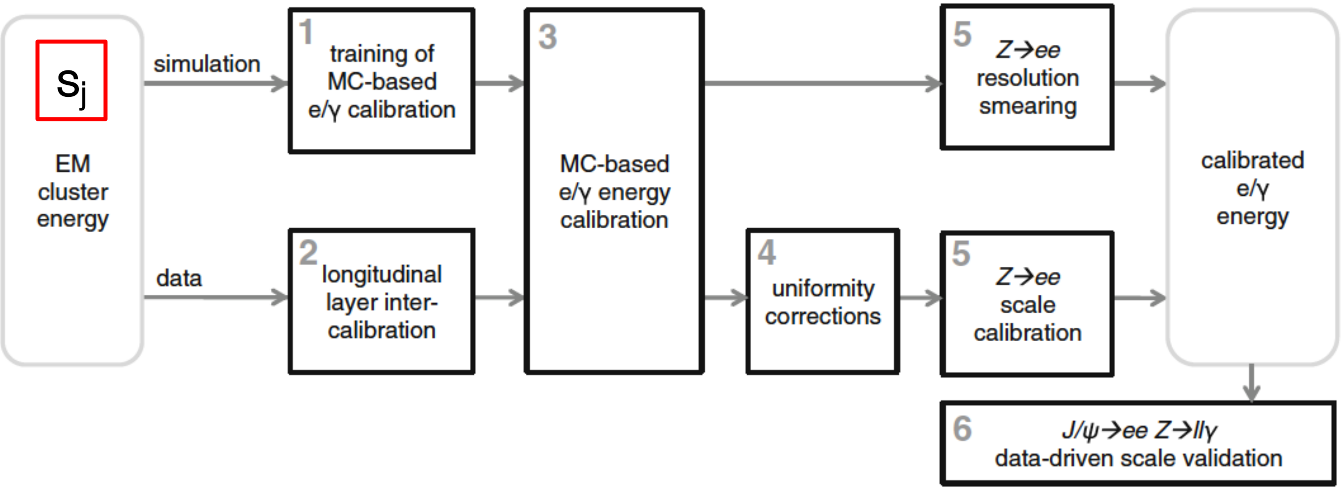
No improvement during last step, vertex found. Remove tracks incompatible with vertex (w_i <0.5) and use them for a secondary vertex



EM – Calorimetry: Calibration

From electronic signals to energy: a long way

$$E_{\text{cell}} = F_{\mu\text{A}\rightarrow\text{MeV}} \times F_{\text{DAC}\rightarrow\mu\text{A}} \times \frac{1}{\frac{Mphys}{Mcali}} \times G \times \sum_{j=1}^{N_{\text{samples}}} a_j(s_j - p),$$

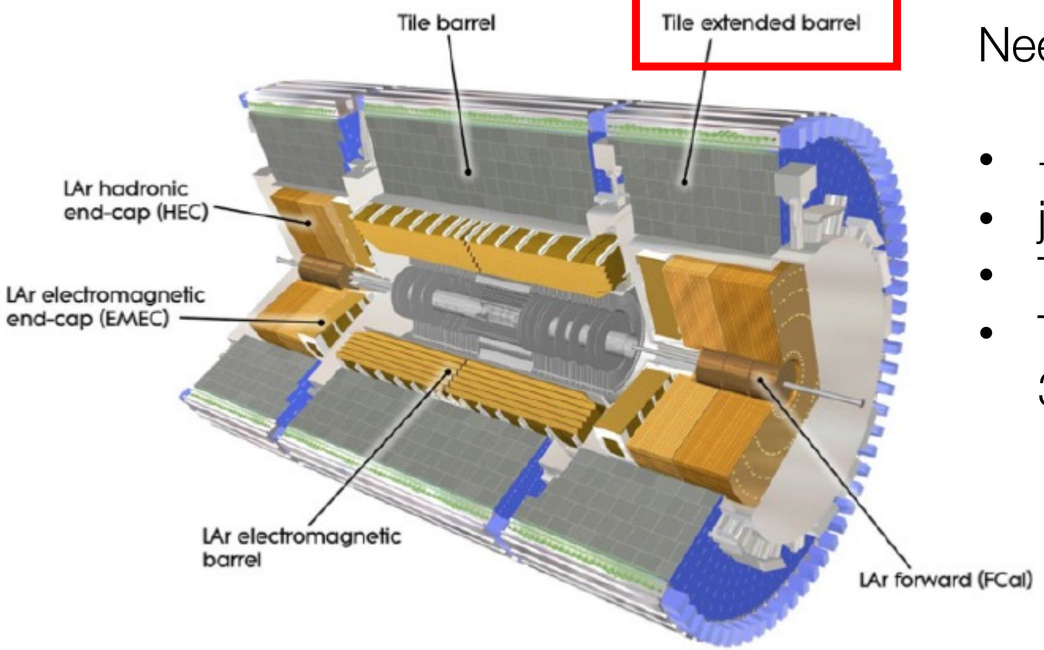


- s_j are the digital signal digitised, measured in ADC counts
- p is the read-out electronic pedestal, measured in dedicated calibration runs;
- a_j weights are coefficients derived from the predicted shape of the ionisation
- The cell gain **G** is computed by injecting a known calibration signal and reconstructing the corresponding cell response. (equalise response)
- The factor M_{phys}/M_{cali} quantifies the ratio of the maxima of the physical and calibration pulses corresponding to the same input current, *corrects the gain factor G obtained with the calibration pulses to adapt it to physics-induced signals*;

Calibration pulses and physical pulses are different

- The factor $F_{DAC\rightarrow\mu A}$ converts digital-to-analog converter (DAC) counts set on the calibration board to a current in μA;
- The factor $F_{\mu A\rightarrow MeV}$ converts the ionisation current to the total deposited energy at the EM scale and is determined from test-beam studies.

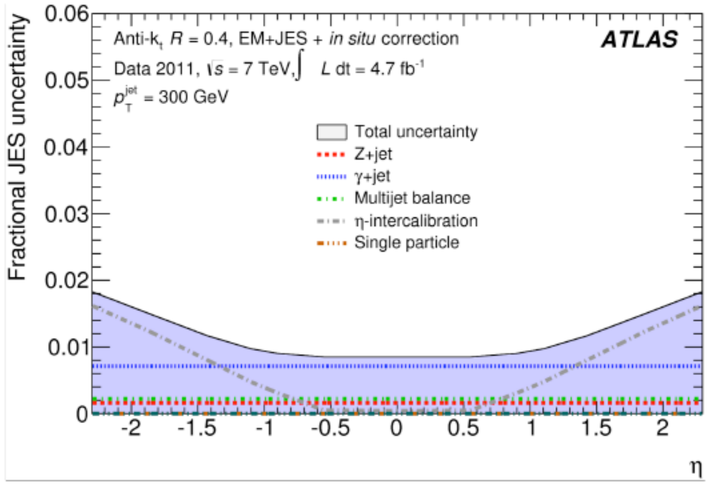
Hadron Calorimetry (example: ATLAS)



Need: keep Hadron-Calorimeter cells calibrated at the % precision

- → good jet and missing transverse energy performance
- jet energy scale (JES) is a measure of the uncertainty
- The JES is one of the main uncertainties in many physics results
- This uncertainty is illustrated in Fig. as a function of η for jets p_T = 300GeV. In the central η region the uncertainty is ~ 1%.

Mostly used for jets reconstruction.



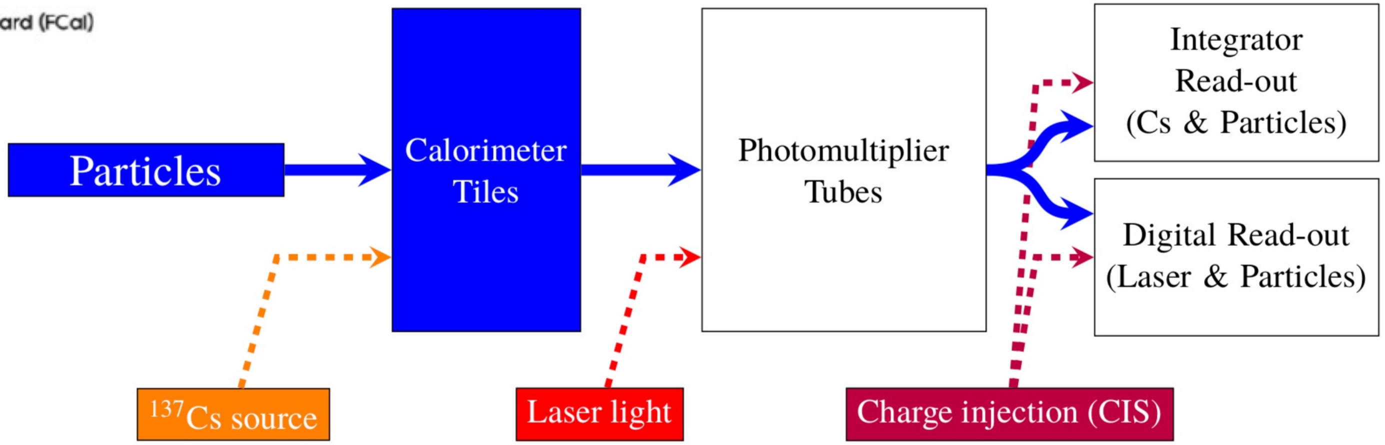


Figure 13: The signal paths for each of the three calibration systems used by the TileCal. The physics signal is denoted by the thick solid line and the path taken by each of the calibration systems is shown with dashed lines.

EM – Calorimetry: Absolute Calibration

Z and J/Ψ decays to a pair of e^+e^- can be used to verify and adjust the calibration of EM calorimeters (but use also $W \rightarrow e\nu$):

Well known! $m^2_{Z,J/\psi} = (E_{e^+} + E_{e^-})^2 - (\vec{p}_{e^+} + \vec{p}_{e^-})^2 = f(E_{e^+}, E_{e^-}) \rightarrow$

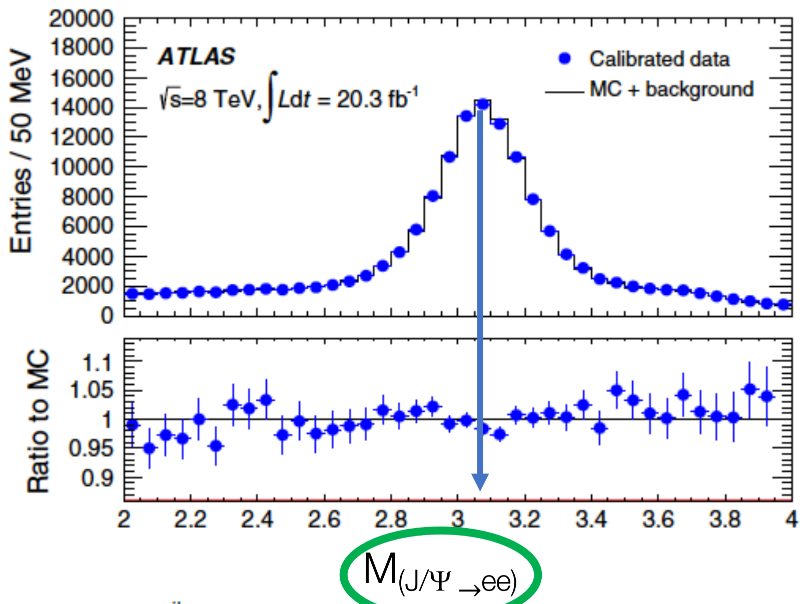
Find the transformation (simple example: $E^{corrected} = \boldsymbol{a} \cdot E$), of the two energies that which gives the

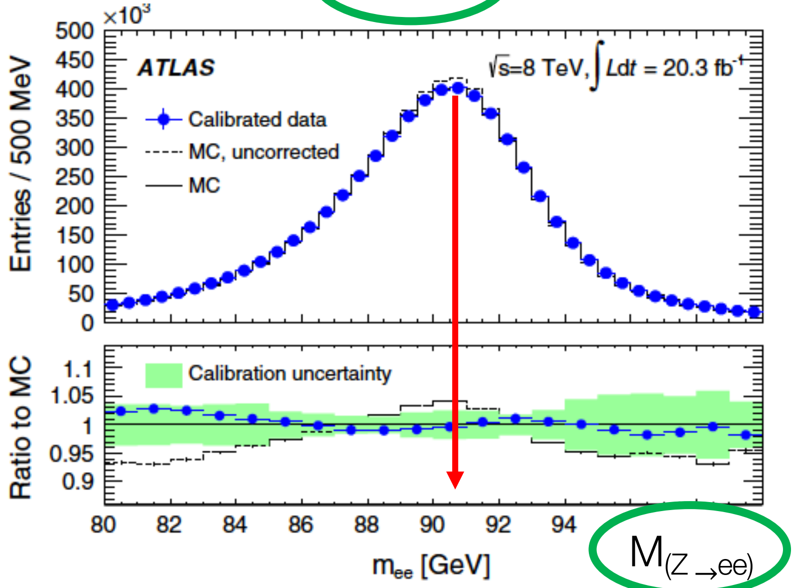
- Correct mass of Z and J/Ψ
- Gives the narrowest invariant mass distribution

Use large samples of events → (and verify if the response is constant in different η,ϕ regions *(Also adjust MC!)*.

Process	Selections	N^{data}_{events}
$Z \rightarrow ee$	$E^e_T > 27$ GeV, $\lvert\eta^e\rvert < 2.47$	5.5 M
	$80 < m_{ee} < 100$ GeV	
$W \rightarrow e\nu$	$E^e_T > 30$ GeV, $\lvert\eta^e\rvert < 2.47$	34 M
	$E^{miss}_T > 30$ GeV, $m_T > 60$ GeV	
$J/\psi \rightarrow ee$	$E^e_T > 5$ GeV, $\lvert\eta^e\rvert < 2.47$	0.2 M
	$2 < m_{ee} < 4$ GeV	

Different kinematic regions





Hadron Calorimeters: Absolute Calibration

In EM calorimeters decays to Z and J/Ψ to e± to check reconstruction.

Hadron Calorimeters: two approaches are used.

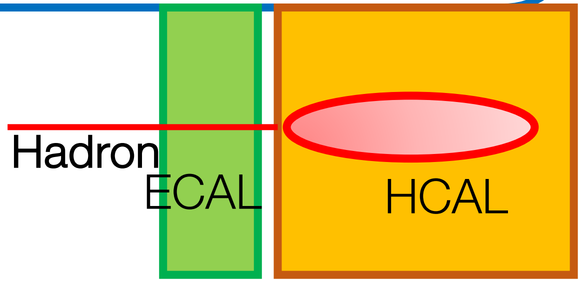
- Use cosmic muons: single isolated muons (from cosmic muons or Z/W decays), measure

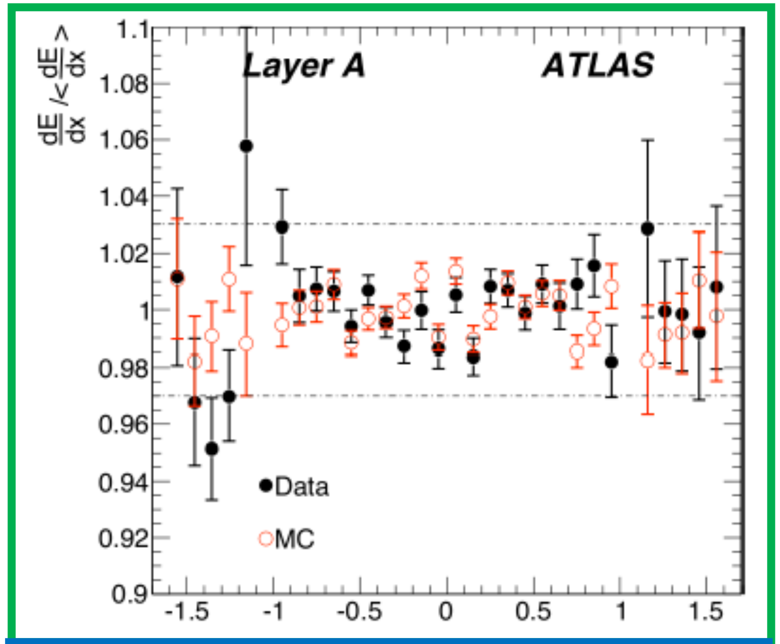
$$energy\ deposited/path\ length$$ (~very large extrapolation!!)

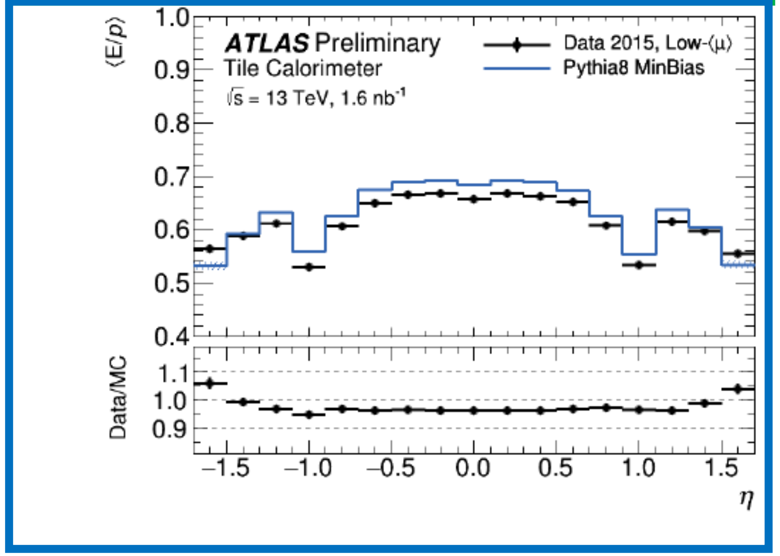
- Use single isolated charged hadrons, *require a signal compatible with a minimum ionizing particle in the electromagnetic calorimeter in front of the hadron calorimeter was required* (shower starts in Hadron Calorimeter) measure

$$energy\ measured/momentum\ of\ charged\ tracks$$

→ compare data & MC → good agreement







(Topological) Clusters in Calorimeters

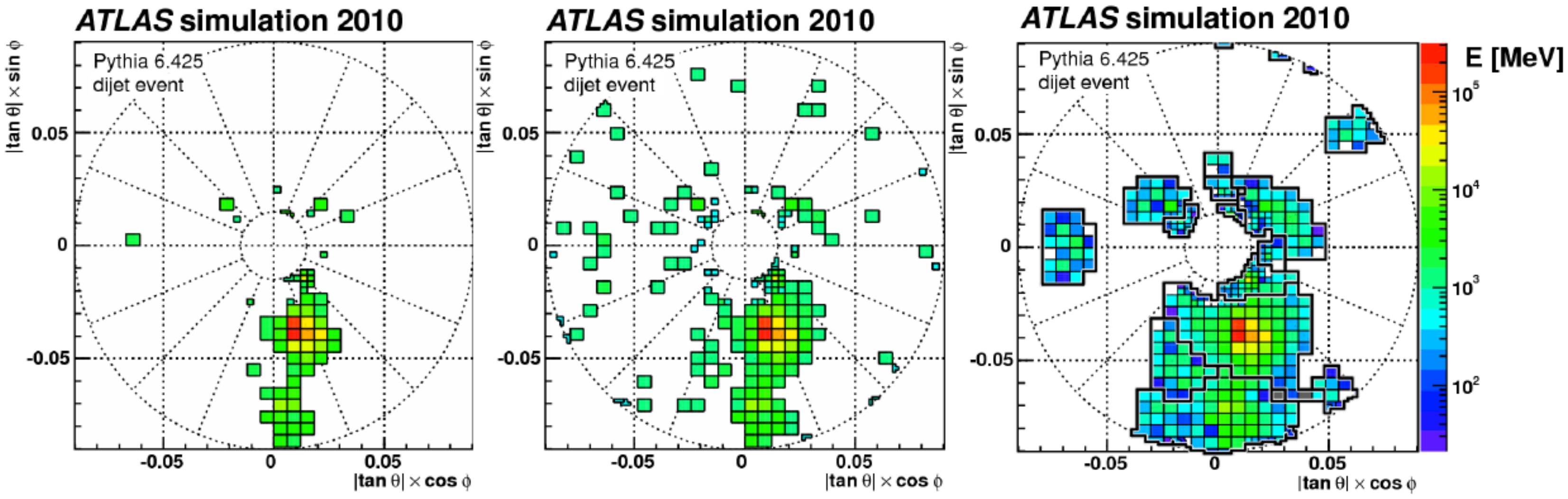
Cells in calorimeters → Clusters of energy deposition

- Identify 'starting' cells (*seeds*) with energy measurements $E_{deposition} > 4 \cdot \sigma_{noise}$
- Associate more cells laterally and longitudinally in two steps

  ✓ add all adjacent cells with energy measurements $E_{deposition} > 2 \cdot \sigma_{noise}$
  ✓ add all adjacent cells with energy measurements $E_{deposition} > \sigma_{noise}$

σ_{noise} is the threshold electronic signal that indicates a significant $E_{deposition}$

- Split two local energy maxima into separate clusters



$|E^{EM}_{cell}| > 4\,\sigma^{EM}_{noise,cell}$ $|E^{EM}_{cell}| > 2\,\sigma^{EM}_{noise,cell}$ $|E^{EM}_{cell}| > 0\,\sigma^{EM}_{noise,cell}$

Comments to Topo-Clusters

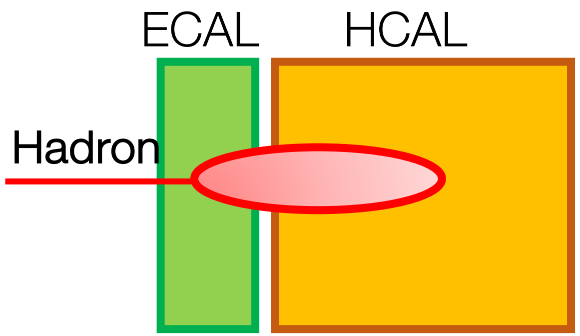
The topological clustering algorithm employed in ATLAS is not designed to separate energy deposits from different particles, but rather to separate continuous energy showers of different nature, i.e. electromagnetic and hadronic, and also to suppress noise.

Few comments:

- A large fraction of low-energy particles are unable to seed their own clusters: In the central barrel 25% of 1 GeV charged pions do not seed their own cluster.
- They are *initially calibrated to the electromagnetic scale (EM scale)* to give the same response for electromagnetic showers from electrons or photons.
- Hadronic interactions produce responses that are lower than the EM scale, by amounts depending on where the showers develop.
- To account for this, the mean ratio of the energy deposited by a particle to the momentum of the particle is determined based on the position of the particle's shower in the detector. A local cluster (LC) weighting scheme is used to calibrate hadronic clusters to the correct scale.
- → Further development is needed to combine this with particle flow

Split Showers in ECAL and HCAL Calorimeters

Hadrons may deposit energy in both Electromagnetic calorimeters (ECAL) and Hadron calorimeters (HCAL).



Conversion factors $E_{deposition} \rightarrow True\ Energy$ are different for ECAL & HCAL and depend on particle type, position, true energy

$$\rightarrow E_{calibrated} = a + b(E)f(\eta)E_{ECAL} + c(E)g(\eta)E_{HCAL}$$

- $E_{calibrated}$ is the 'real particle energy'
- E_{ECAL} and E_{HCAL} are the energies measured in the ECAL and the HCAL
- a accounts for energy lost because of σ_{noise} threshold
- $b(E)$ and $c(E)$ are conversion factors
- $f(\eta)$ and g(η) correct energy in different η regions

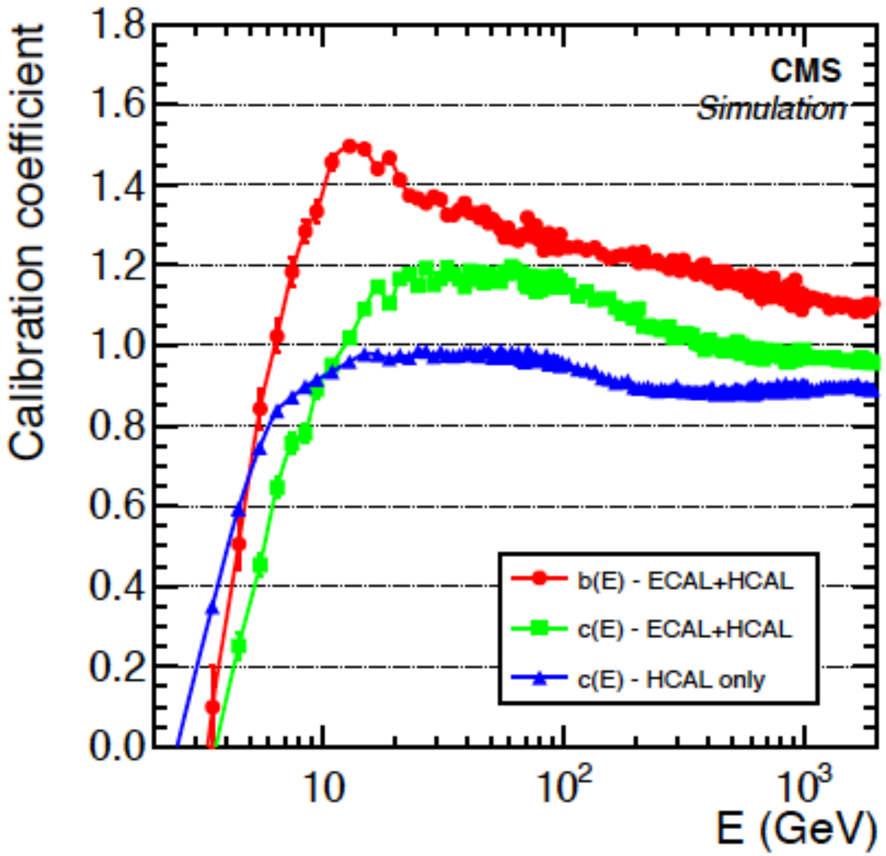
These parameters have to be determined from data: use

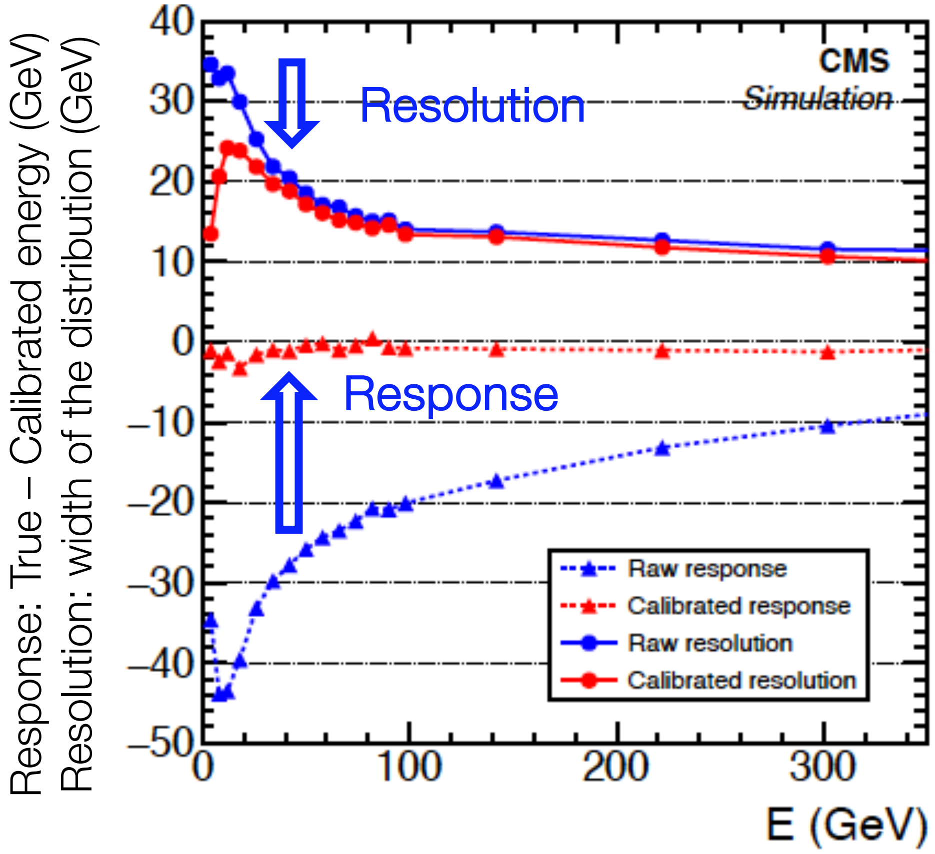
$$\chi^2 = \sum_{i=1}^{N} \frac{\left(E_i^{\mathrm{calib}} - E_i\right)^2}{\sigma_i^2},$$

- Simulated data: true energy (MC!) is taken as $E_{calibrated}$
- Large samples of isolated charged showers: the momentum reconstruction is taken as $E_{calibrated}$

In a first pass, the functions f (η) and g(η) are fixed to unity.

Results: $(E_{calibrated} = a + b(E)f(\eta)E_{ECAL} + c(E)g(\eta)E_{HCAL})$





Calibration coefficients vs energy E, for hadrons

- HCAL only (blue triangles),
- ECAL and HCAL, for
  - ✓ the ECAL (red circles) and
  - ✓ for the HCAL (green squares)

Single isolated hadrons:

- Relative raw (blue) and calibrated (red) energy response (dashed curves and triangles)
- resolution (full curves and circles)

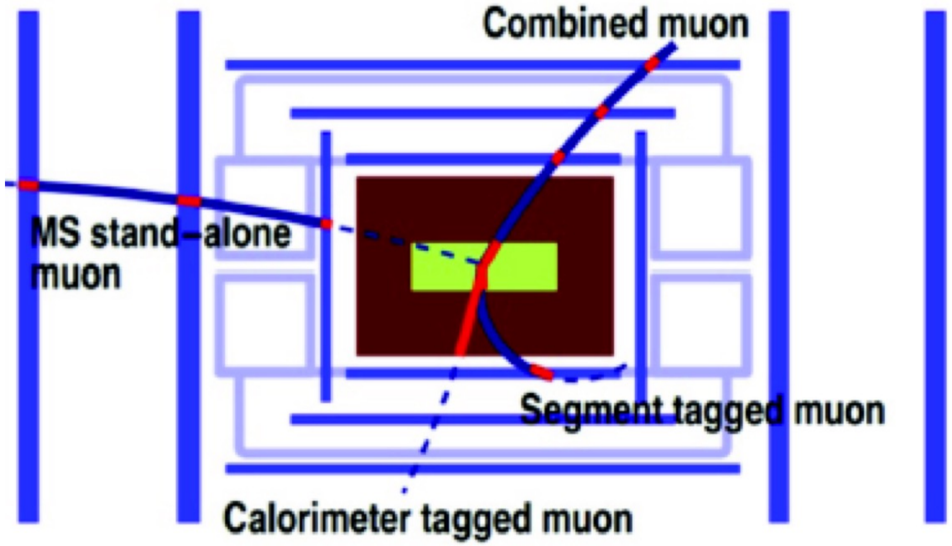
Muon Reconstruction at LHC

<table>
<tr><th>Issue</th><th>ATLAS</th><th>CMS</th></tr>
<tr><td>Design</td><td>Air-core toroid magnets
Standalone muon reconstruction</td><td>Flux return instrumented
Tracks point back to collision point</td></tr>
<tr><td>Barrel Tracking</td><td>Drift tubes
Precision: ~ 80-120 μm</td><td>Drift tubes
Precision: 100–500 μm</td></tr>
<tr><td>End-cap Tracking</td><td>Cathode strip chambers
High rate capability</td><td>Cathode strip chambers
High rate capability</td></tr>
<tr><td>Barrel Trigger</td><td>Resistive plate chambers
Fast response [5 ns]</td><td rowspan="2">Resistive plate chambers
Fast response [5 ns]</td></tr>
<tr><td>End-cap Trigger</td><td>Thin gap chambers
Fast response, high rates</td></tr>
</table>

Muon Reconstruction in ATLAS

Muons

- are filtered by calorimeters
- Seen in the Inner detector and in the muon spectrometer.
  - These two tracks have to be associated @ reference plane
  - The momentum has to be computed by combining the two associated tracks + account the energy lost in calorimeters



Very high energy muons (close to 1 TeV) may shower like electrons, these cases are called "catastrophic energy losses"

Different types (== different reconstructions)

- Combined: ID + MS + full track refit. Main reconstruction type
- Stand-alone (SA): MS-only track with identification and reconstruction. Recovers muons for $|\eta|>2.5$
- Segment-tagged: one ID track is associated to one segment of track measured in the MS (incomplete MS track)
- CaloTag: charged track in the ID associated to an energy deposition of a minimum ionizing particle in the calorimeter. Low energy muons that do not penetrate up to the MS

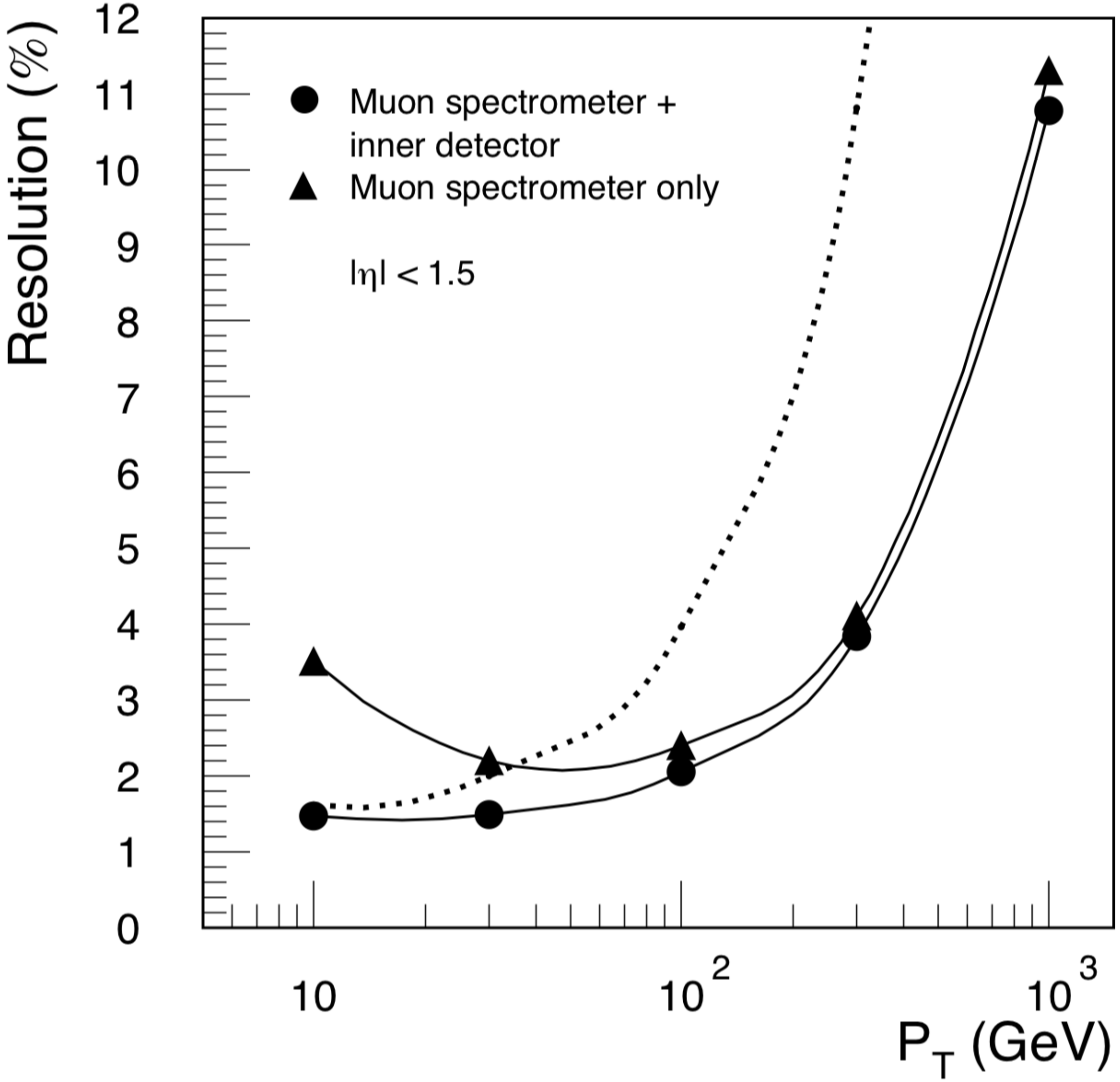
Muon Reconstruction in CMS

The momentum of muons is measured both in the inner tracker and in the muon spectrometer. There are three different muon types:

- *standalone muon*. Hits in the muon spectrometer only are used to form muon segments that are combined in a track describing the muon trajectory. The result of the final fitting is called a standalone-muon track.
- *global muon*. Each standalone-muon track is matched (if possible!) to a track in the inner tracker if the parameters of the two tracks propagated onto a common surface are compatible. The hits from the inner track and from the standalone-muon track are combined and fit to form a global-muon track. At large transverse momenta, p_T>200 GeV, the global-muon fit improves the momentum resolution with respect to the tracker-only fit.
- *tracker muon*. Each inner track with p_T larger than 0.5 GeV and a total momentum p in excess of 2.5 GeV is extrapolated to the muon system. If at least one muon segment matches the extrapolated track, the inner track is defined as a tracker muon track.

About 99% of the muons produced within the geometrical acceptance of the muon system are reconstructed either as a global muon or a tracker muon and very often as both. Global muons and tracker muons that share the same inner track are merged into a single candidate. Muons reconstructed only as standalone-muon tracks have worse momentum resolution and are contaminated by cosmic. Charged hadrons may be mis-reconstructed as muons if some part of the hadron shower reach the muon system (punch-through).

Muon p_T Resolution in ATLAS



Combining ID + MS improves resolution always.

Effect is mostly visible at low p_T values ~ 10 GeV where a factor of two is gained in resolution

At high p_T (~1 TeV) the resolution mostly comes from the MS

Tag & Probe Method

How to check the reconstruction efficiency of muons?

Total reconstruction efficiency

$$\varepsilon = \varepsilon(ID) \times \varepsilon(MS) \times \varepsilon(comb)$$

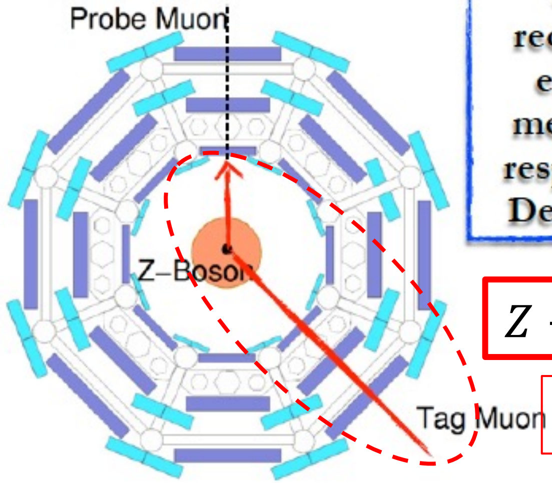
Inner tracker reconstruction efficiency

Muon Spectrometer reconstruction efficiency

Combinati on efficiency

The muon reconstruction efficiency is measured with respect to Inner Detector tracks

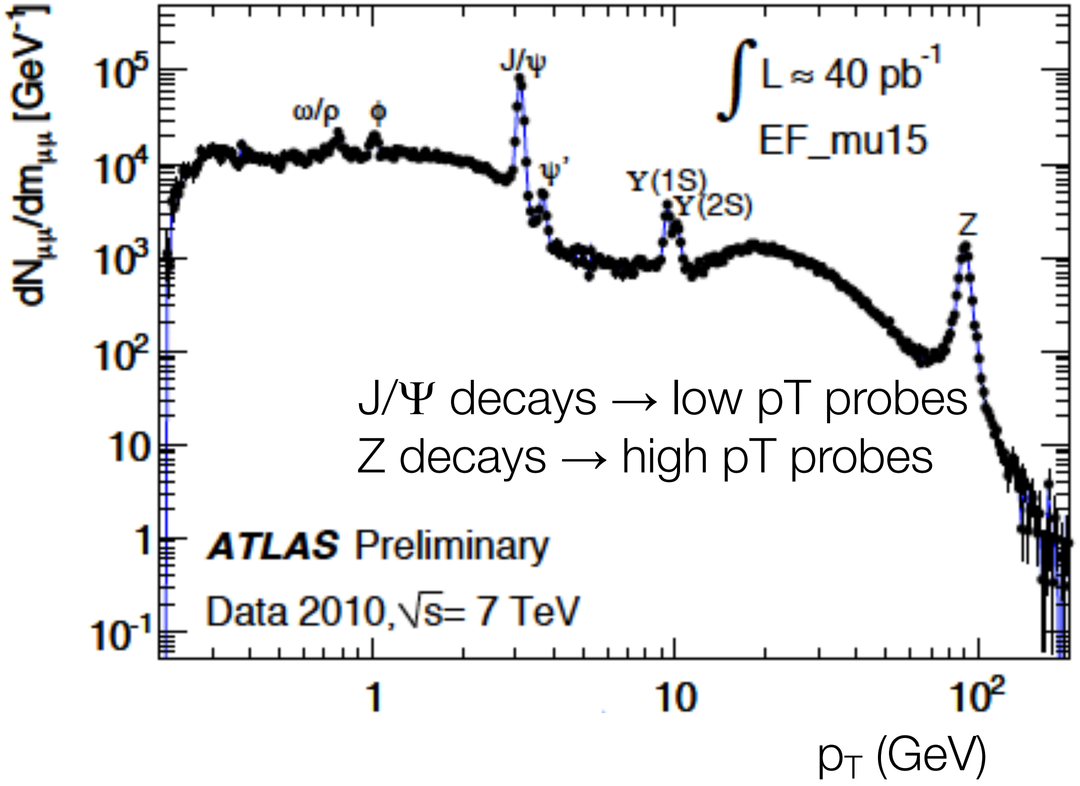
How many times is a 'Probe' muon found?



$Z \to \mu^-\mu^+ \to m_Z$

= real muon

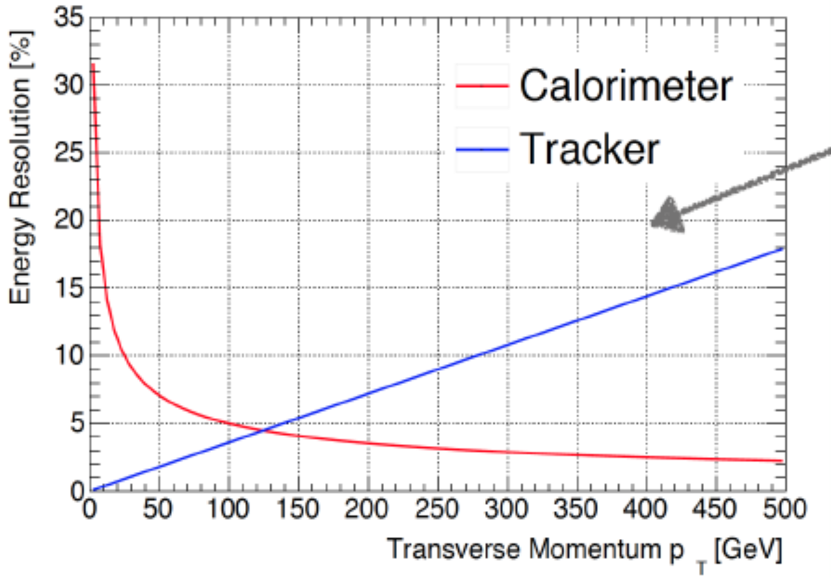
$$SF = \frac{\varepsilon^{\mathrm{Data}}(\mathrm{Type})}{\varepsilon^{\mathrm{MC}}(\mathrm{Type})}.$$



The measurement of the muon reconstruction efficiency is done using well known resonances:

1. A combined muon "Tag"
2. the tag is paired with an ID track giving an invariant mass close to the considered resonance mass
3. the fraction of reconstructed signal "**Probes**" measures the muon identification efficiency

Modern Experiments: Particle Flow, Basic Idea



Parametrisation of the relative resolution of

- calorimeters and
- p_T measured in the Inner Detector

$$\frac{\sigma(E)}{E} = \frac{50\,\%}{\sqrt{E}} \oplus 3.4\,\% \oplus \frac{1\,\%}{E}\text{, Calorimeters}$$

$$\sigma\left(\frac{1}{p_T}\right) \cdot p_T = 0.036\,\% \cdot p_T \oplus 1.3\,\%\text{, Inner Detector}$$

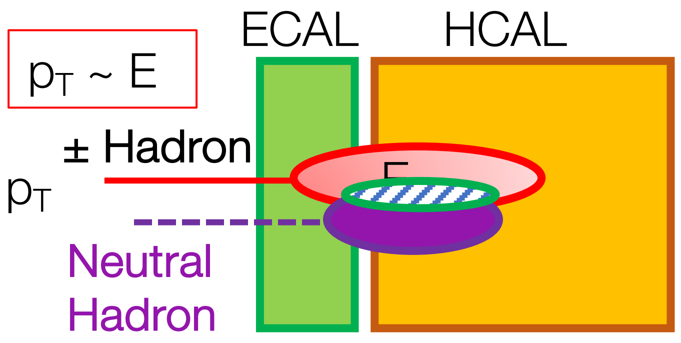
→ For low-energy charged particles, the momentum resolution of the tracker is significantly better than the energy resolution of the calorimeter.

Problem #1

A charged particle is measured in trackers (p_T) and in calorimeters (ECAL & HCAL) → **avoid double-counting its energy** → associate tracks and showers → choose only one!

Problem #2

Showers are often superimposed → subtract a part of the energy deposition

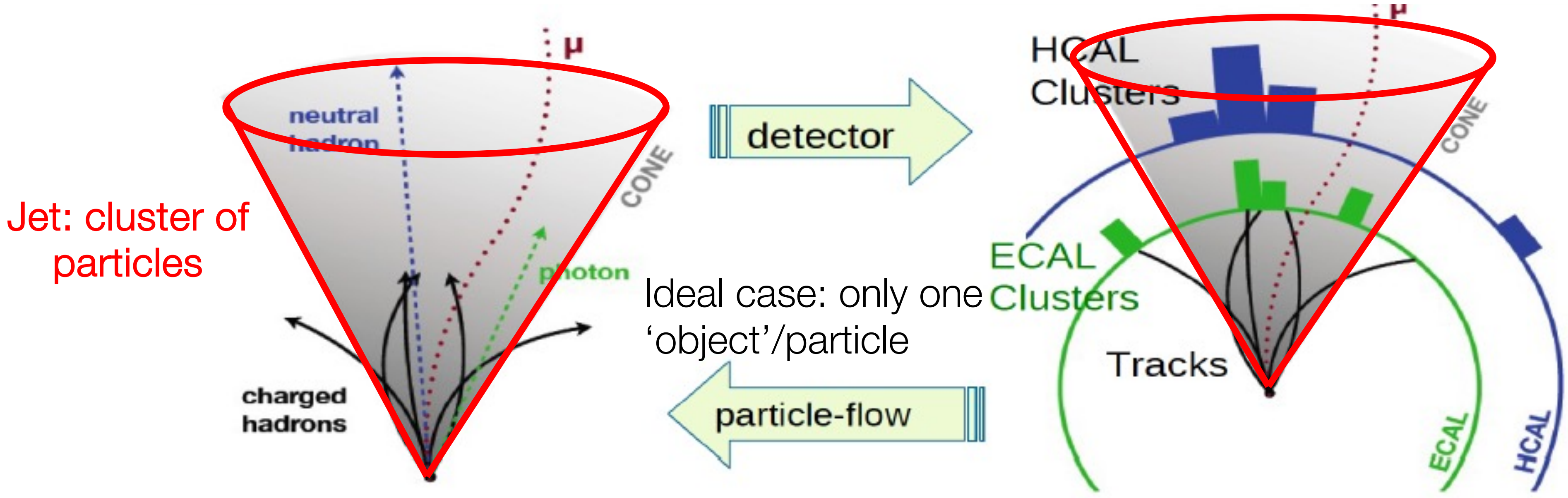


Particle Flow (~Jets): basic idea

Why Particle Flow (PF)?

Two possibilities to reconstruct the topology (*) of one event

- Use calorimeters: they are sensitive to ALL particles, charged, neutral, photons hadrons, (partly) muons. BUT the energy resolution ~not very good at ~low/medium energies
- use PF: t gives an optimal use of measurements: when you have two independent measurements of the same particle → take the best!



(*) Topology = general characteristics of the event, like # of jets

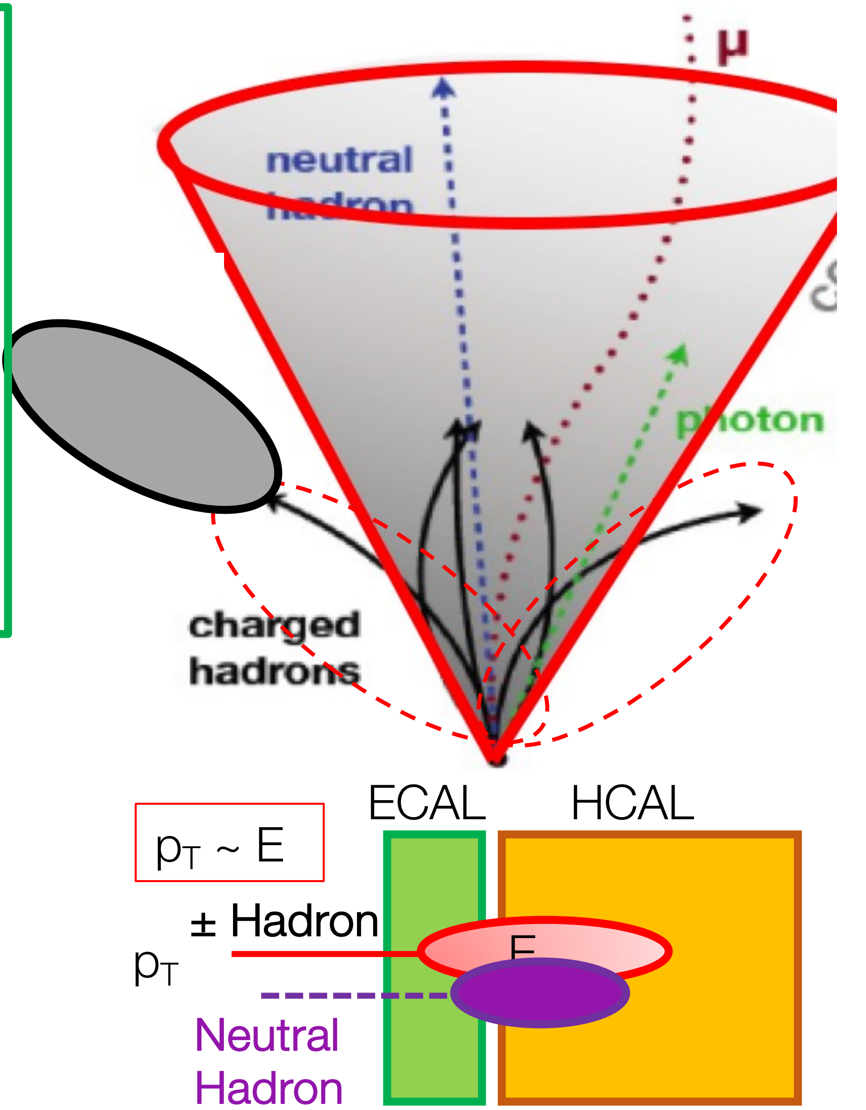
Particle Flow: Advantages & Disadvantages

- Particles below detection threshold;
- $\sigma^{Tracker}_{direction} \ll \sigma^{Calorimeter}_{direction}$
- Low-p_T tracks in a jet are swept out of the jet cone by the magnetic
- *→ use track's coordinates at the IP →* these particles are recovered into the jet.
- pile-up interactions: distinguish primary vertex from pile-up vertices

For each charged particle

- Avoid double-counting energy (Calorimeters) & Momentum (trackers)
- Cancel E_{dep} calorimeters of charged tracks *→ only neutrals*
- Handle one neutral h close to a charged h

Do not remove any energy deposited by neutral particles.



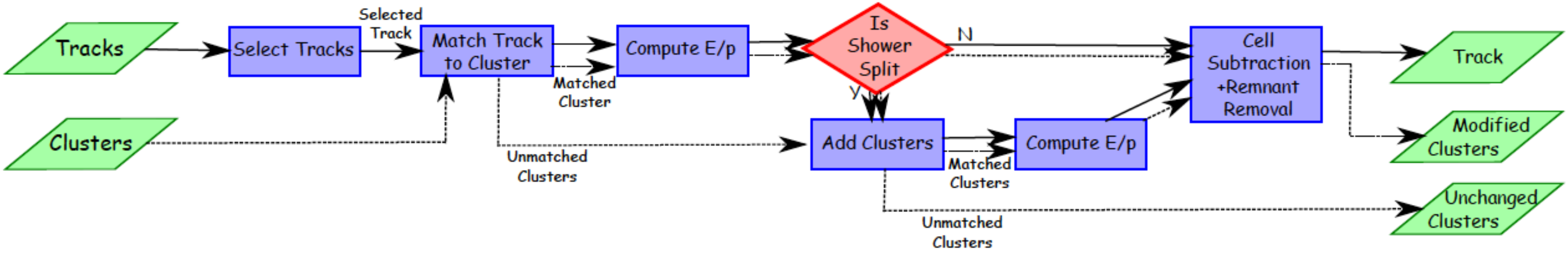
The Particle Flow Algorithm

Before applying PF Algorithm it is necessary to know how much energy $\langle E_{dep} \rangle$ a particle with measured momentum p_{trk} deposits on average in calorimeters. This is needed to correctly subtract the energy from the calorimeter for a particle whose track has been reconstructed. This is done using the expression

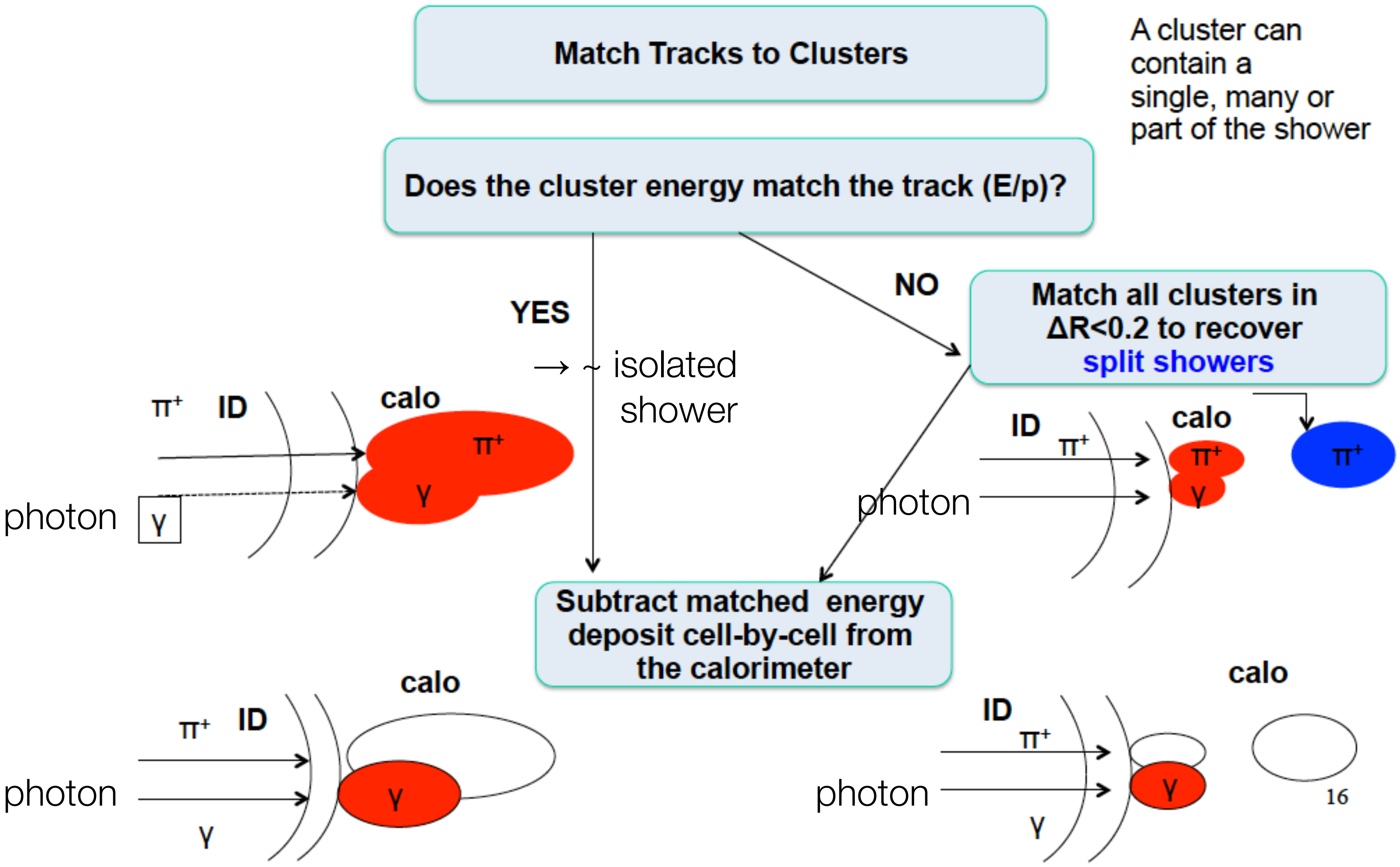
$$\langle E_{dep} \rangle = p^{trk} \cdot \langle E^{clus}_{ref} / p^{trk}_{ref} \rangle$$

The value $\langle E^{clus}_{ref} / p^{trk}_{ref} \rangle$ (which is also a measure of the mean response) is determined using single-particle samples without pile-up by summing the energies of topo-clusters in a R cone of size 0.4 around the track position, extrapolated to the EM calorimeter. This cone size is large enough to entirely capture the energy of the majority of particle showers. The subscript 'ref' indicates values $\langle E^{clus}_{ref} / p^{trk}_{ref} \rangle$ determined from single-pion samples.

The PF algorithm is skematically shown below



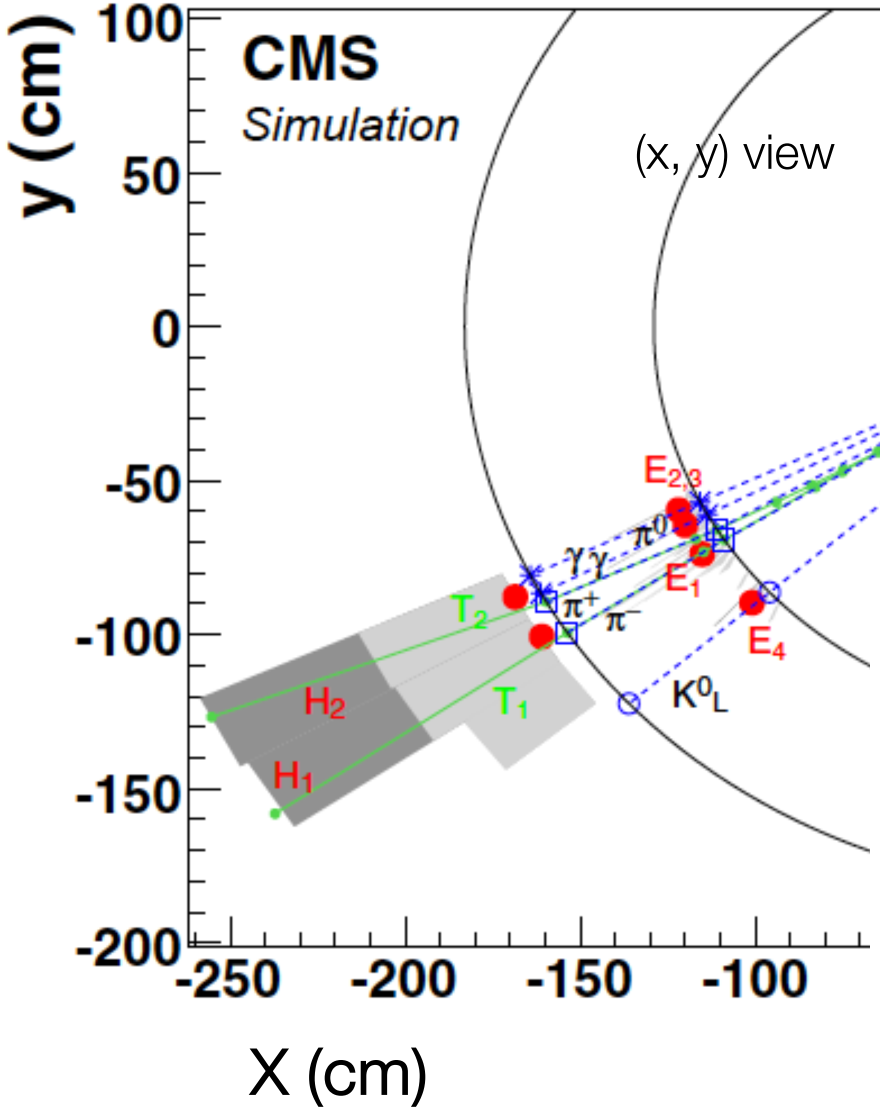
Particle Flow in One Cartoon

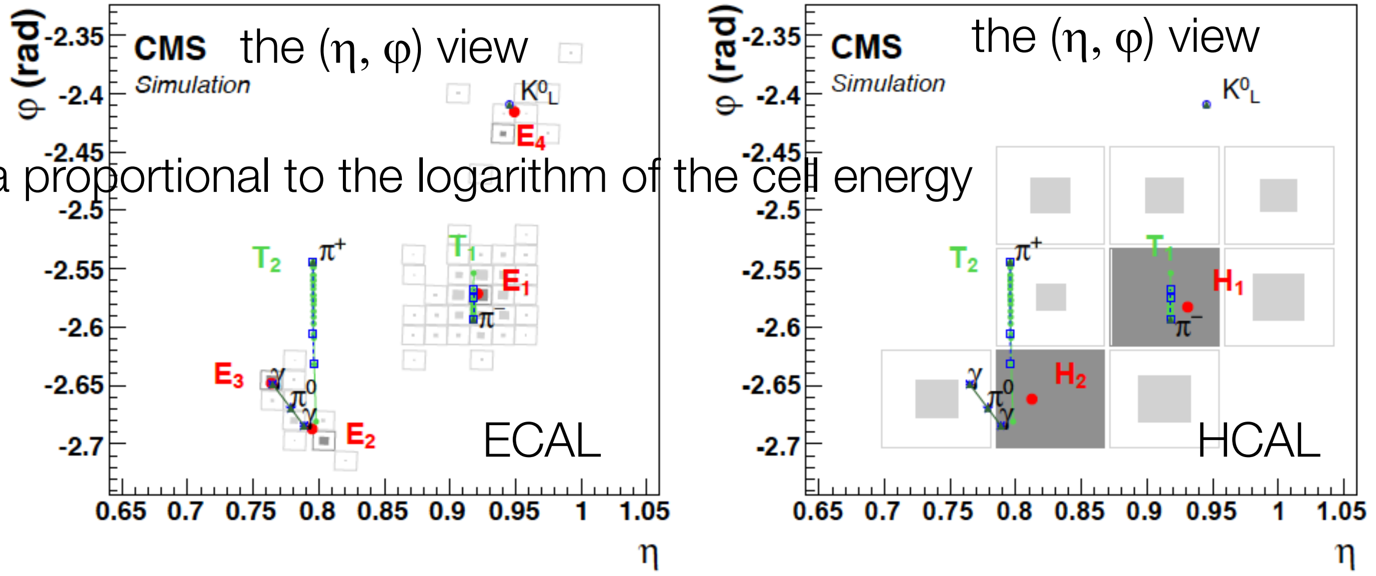


PF in CMS, one Event

jet made of five particles only

ECAL is EM calorimeter HCAL is the hadronic calorimeter





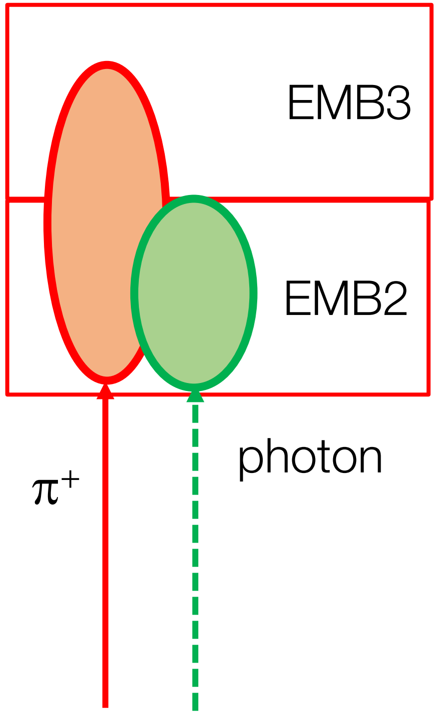
area proportional to the logarithm of the cell energy

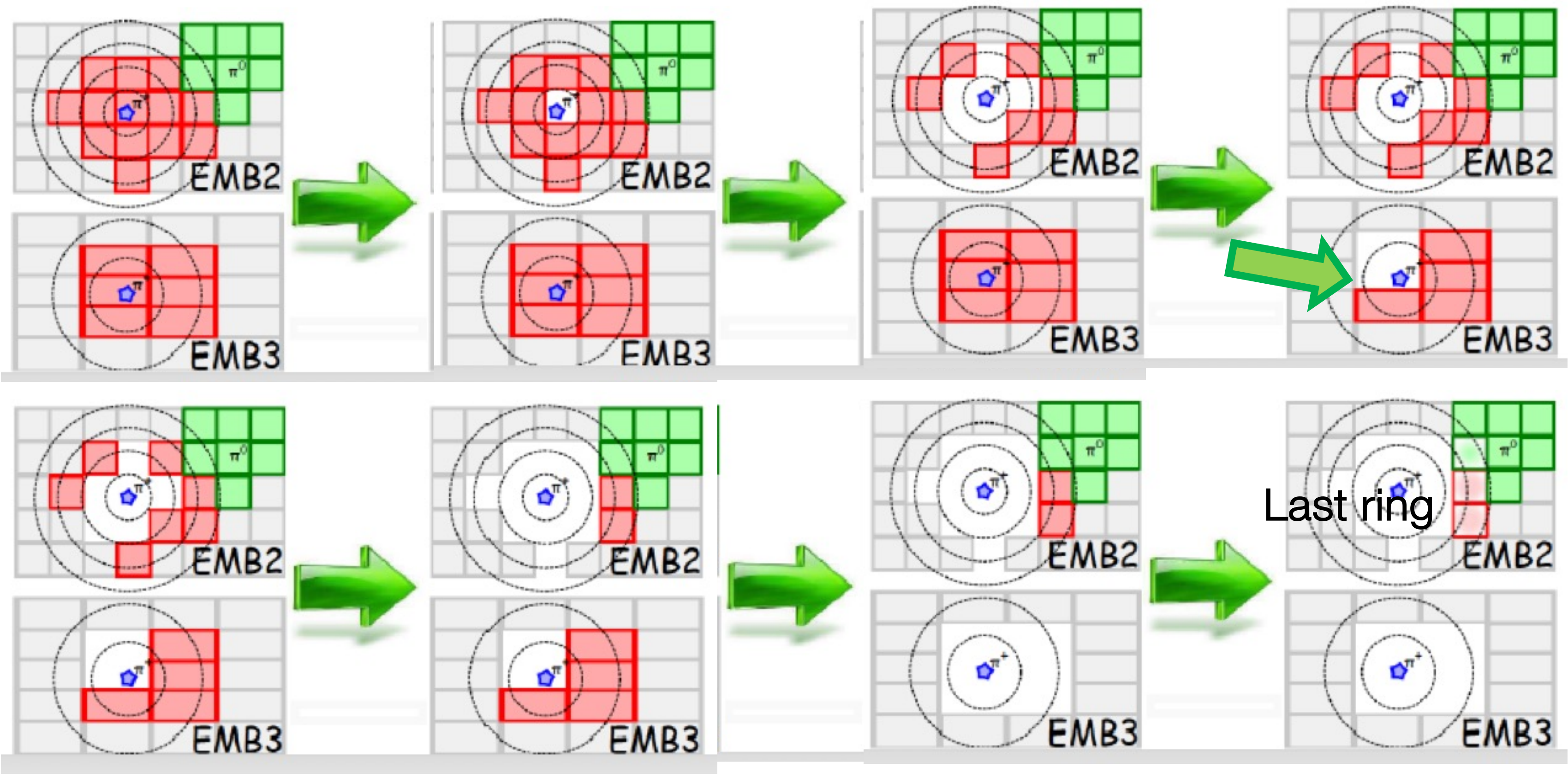
The K_0^L, the π^-, and the two photons from the π^0 decay are detected as four well-separated ECAL clusters denoted E1,2,3,4. The π^+ does not create a cluster in the ECAL. The two charged pions are reconstructed as charged-particle tracks T1,2, appearing as vertical solid lines in the (η, φ) views and circular arcs in the (x, y) view. These tracks point towards two HCAL clusters H1,2 cluster positions are represented by dots, the simulated particles by dashed lines, and the positions of their impacts on the calorimeter surfaces by various open markers.

Subtracting Calorimeter Cells

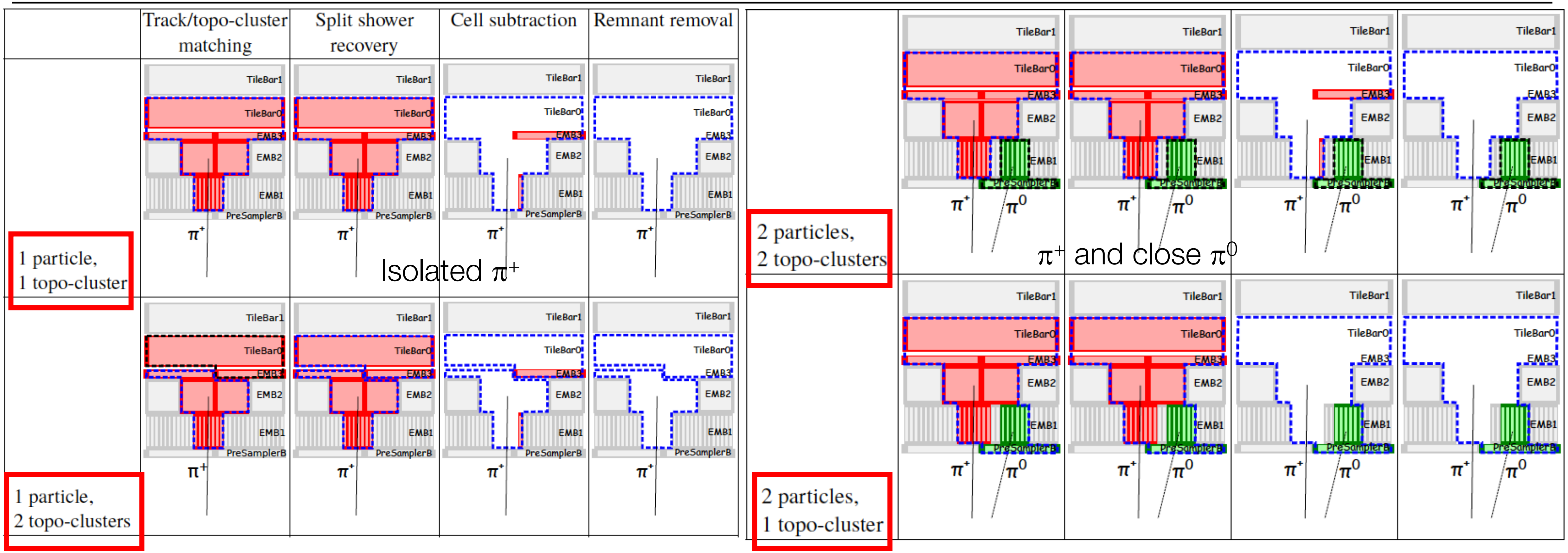
- Important parameter: the ratio $E_{calorimeter}/p^{trk}$ → rings around the extrapolated track
- Remove rings if $E_{cl} > p^{trk}$

EMB2 & EMB3 two calorimeter layers



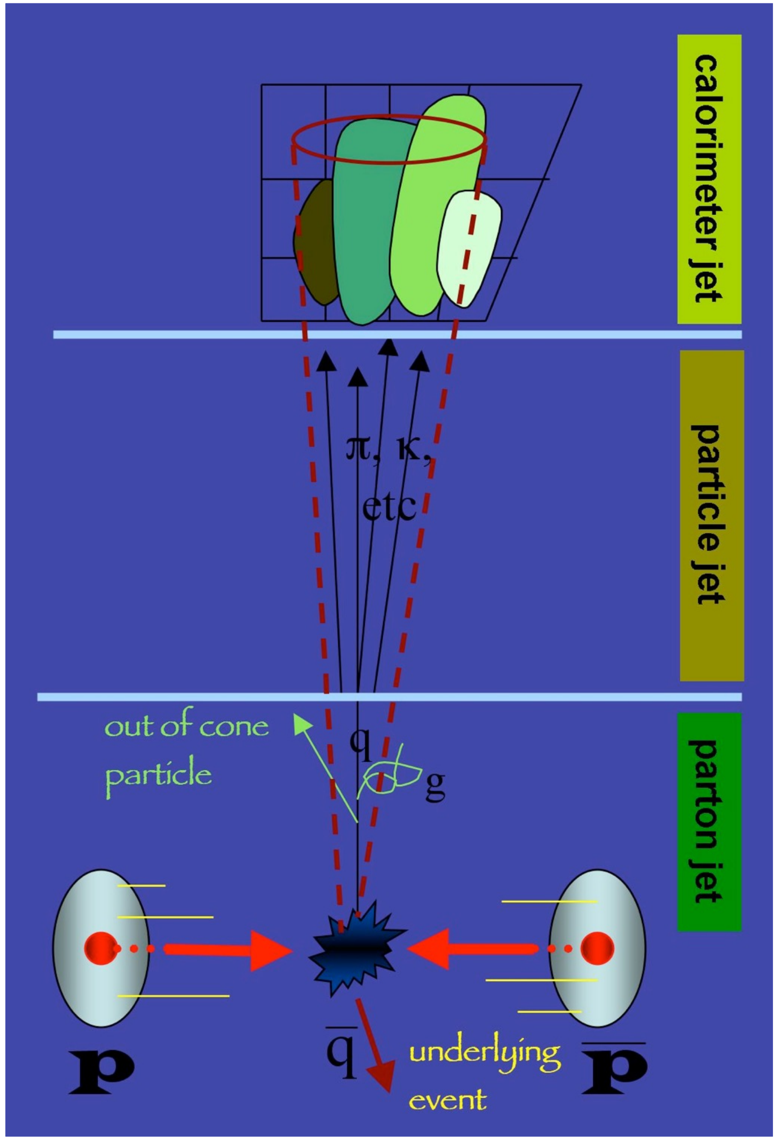


Particle Flow in Action: Example



- The red cells are from the π^+,
- the green cells energy from the photons from the π^0 decay
- the dotted lines represent the borders of the calorimeter-cluster

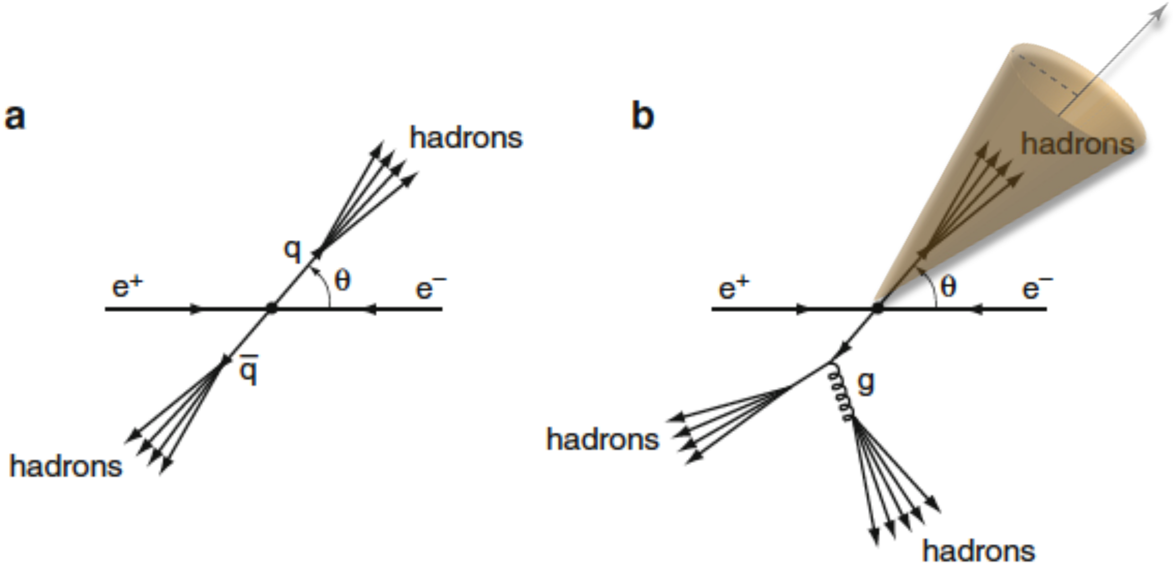
Jets: Introduction



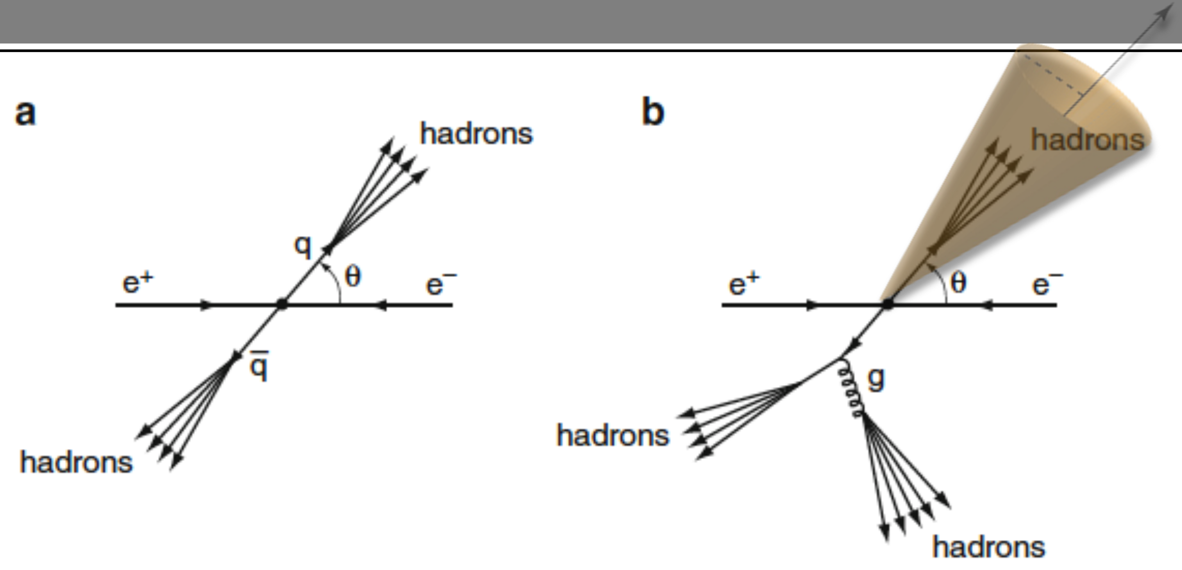
Jets are a collection of ‘close by’ objects that reflect the initial parton
→ try to reconstruct the momentum of the initial parton

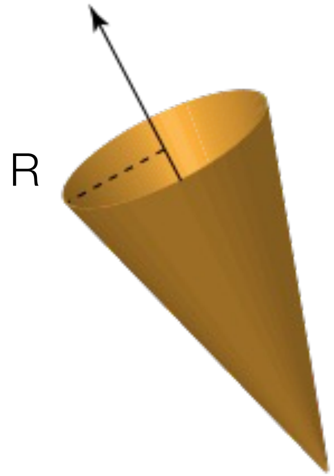
Construction of jets:

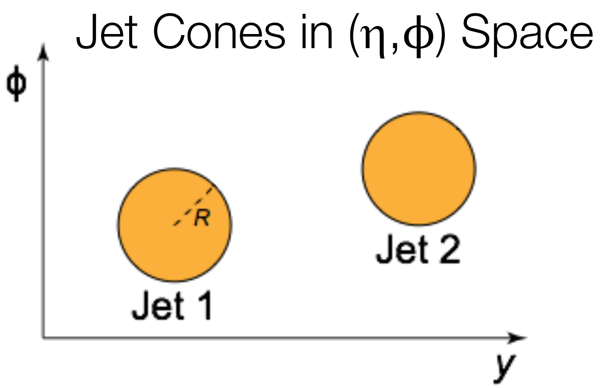
- Before Particle Flow → calorimeters
- After Particle Flow → the best defined object between with track or calorimeter cluster



Jets (What & How?)



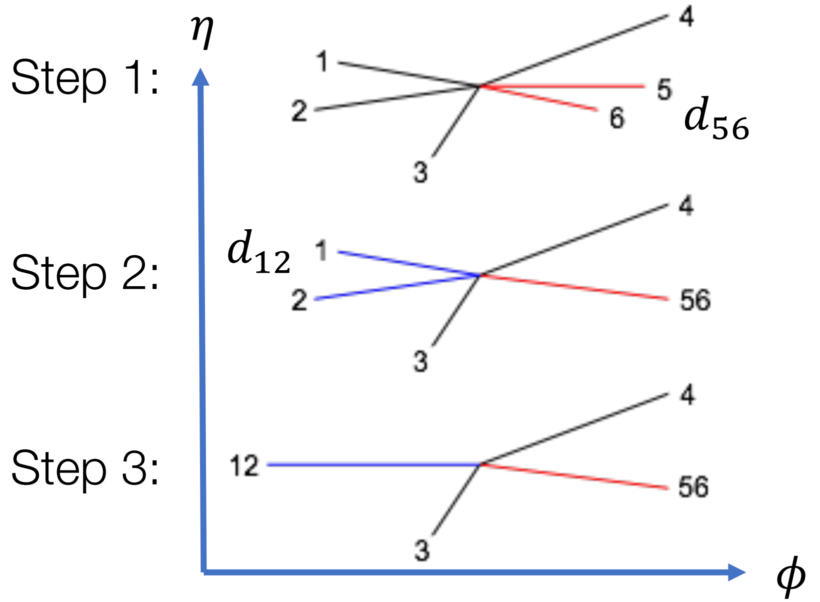




Iterative cone algorithms: Jet defined as energy flow within a cone of radius R in (η,ϕ) space:

$$R = \sqrt{(\eta - \eta_0)^2 + (\Phi - \Phi_0)^2}$$

- Start with most energetic energy deposition
- Define distance measure d_{ij}
- Calculate d_{ij} for all pairs of objects ...
- Combine particles with minimum d_{ij} below cut ...
- Stop if minimum d_{ij} above cut ...



Limit: all ‘distances’ count the same! → weight using momentum or energy

Jets, Different Algorithms, see reference(*)

The definition of distance is very important: the formula below if most used today. NOTE the parameter '*p*' in $k_{t,i}^{2p}$.

- $k_{t,i}$ *is the transverse momentum of particle i*
- $\Delta_{ij}^2 = (\eta_i - \eta_j)^2 + (\varphi_i - \varphi_j)^2$

$$d'_{ij} = distance' = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) \frac{\Delta_{ij}^2}{R^2},$$

R^2 is a parameter of the algorithm → opening of the cone

If *p*=0 you have the so-called *Cambridge/Aachen* algorithm

$$d_{ij} = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) \frac{\Delta_{ij}^2}{R^2} \rightarrow \mathrm{d_{ij}} = \frac{\Delta_{\mathrm{ij}}^2}{\mathrm{R}^2}$$

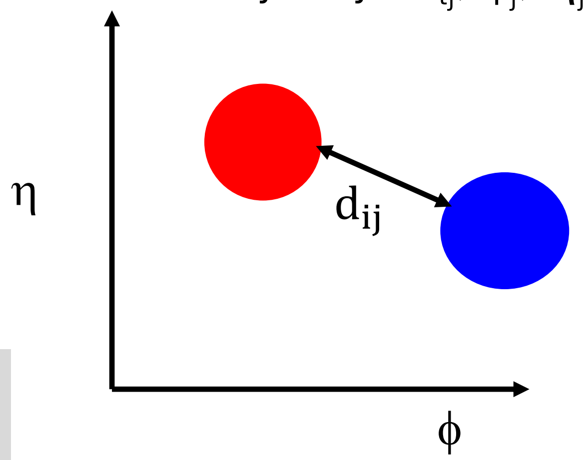
If *p*=1 you have the so-called K_T algorithm

$$d_{ij} = \min(k_{t,i}^2, k_{t,j}^2) \frac{\Delta_{ij}^2}{R^2}$$

If *p*=-1 you have the so-called *anti* K_T algorithm

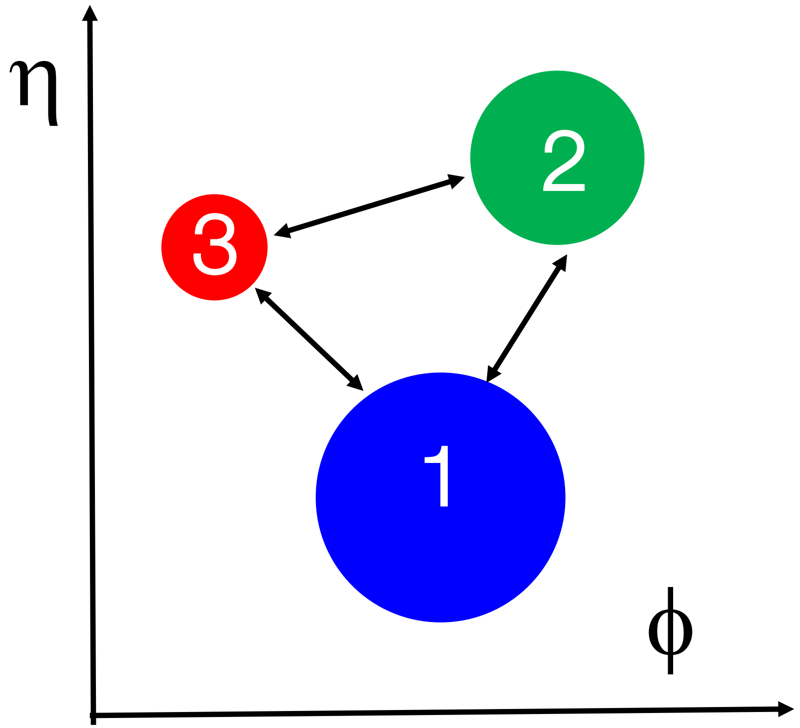
$$d_{ij} = \min(\frac{1}{k_{t,i}^2}, \frac{1}{k_{t,j}^2}) \frac{\Delta_{ij}^2}{R^2}$$

Object j : k_{tj}, ϕ_j, η_j



(*) Cacciari et al. https://arxiv.org/pdf/0802.1189

k_T and anti-k_T Jet Algorithms



$$d_{ij} = \min(k_{t,i}^{2p}, k_{t,j}^{2p}) \frac{\Delta_{ij}^2}{R^2}$$

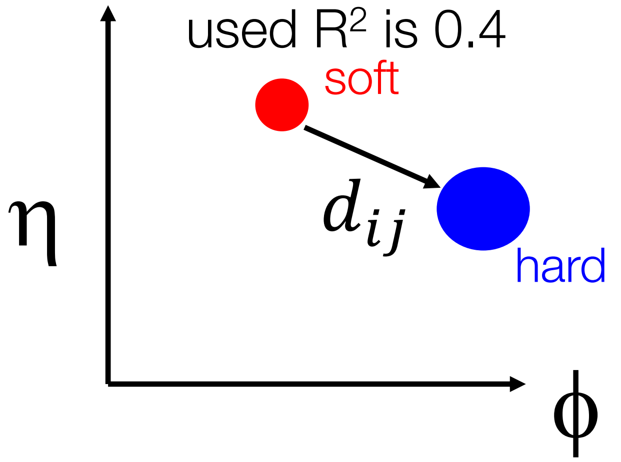
neglect case with p=0, only of historical interest, does not contain any dependence on E/p/p_T

$$\Delta_{ij}^2 = (\eta_i - \eta_j)^2 + (\varphi_i - \varphi_j)^2$$

Δ_{ij}^2 are ~ simlar

p_T: 1 > 2 > 3

Anti k_T is most used, most used R^2 is 0.4



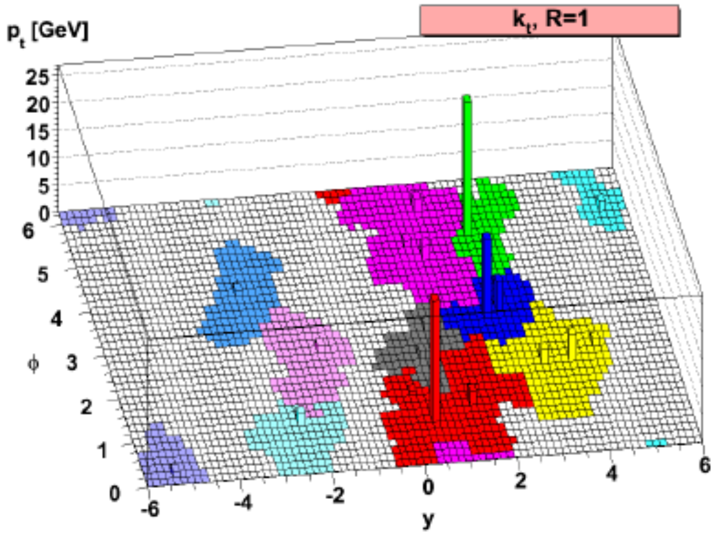
k_T $\quad d_{ij} = \min(k_{t,i}^2, k_{t,j}^2) \frac{\Delta_{ij}^2}{R^2}$ $\quad d_{13}<d_{23}<d_{12}$ $\quad$ Distance~$(p_T)^2$→ cluster around the particle with smallest p_T → particle 3

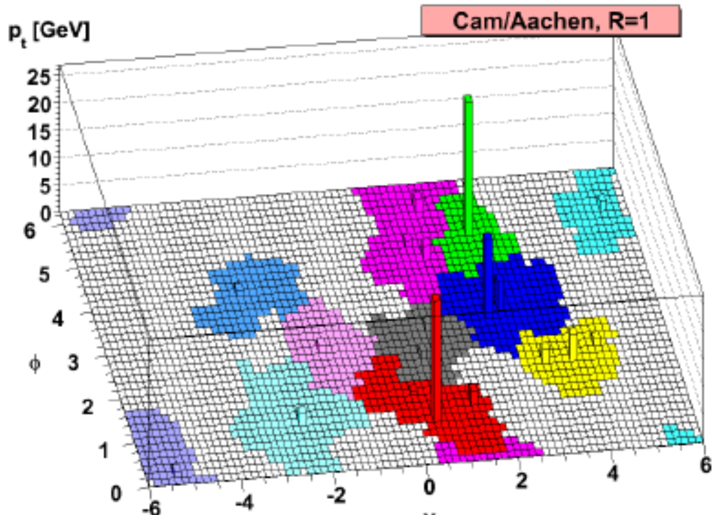
Anti k_T $\quad d_{ij} = \min(\frac{1}{k_{t,i}^2}, \frac{1}{k_{t,j}^2}) \frac{\Delta_{ij}^2}{R^2}$ $\quad d_{13}<d_{23}<d_{32}$ $\quad$ Distance~$(1/p_T)^2$→ cluster around the particle with highest p_T → particle 1

Natural choice: the particle with highest energy in a jet keeps the best memory of the initial

Jet Shapes in Different Algorithms

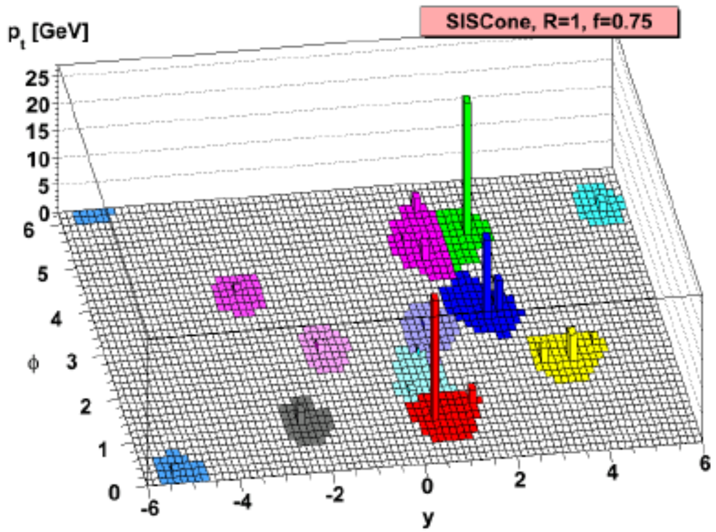
kT jet reconstruction algorithm

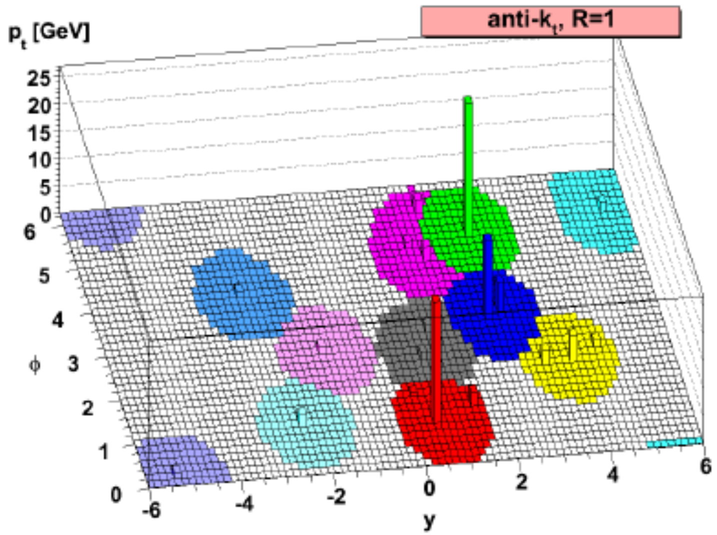




Simulated events: 3 partons + large number of ghosts

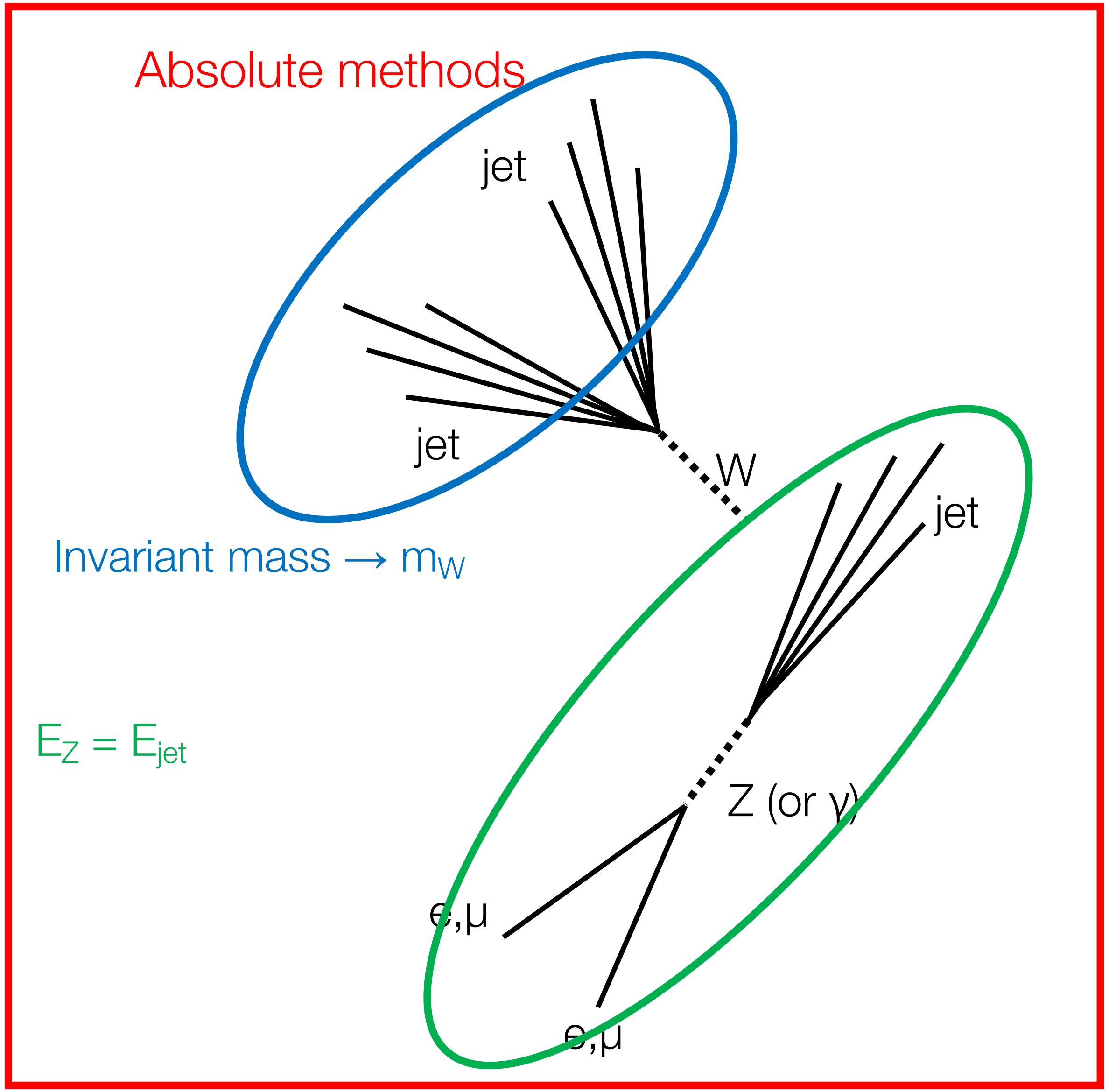
anti-kT jet reconstruction algorithm

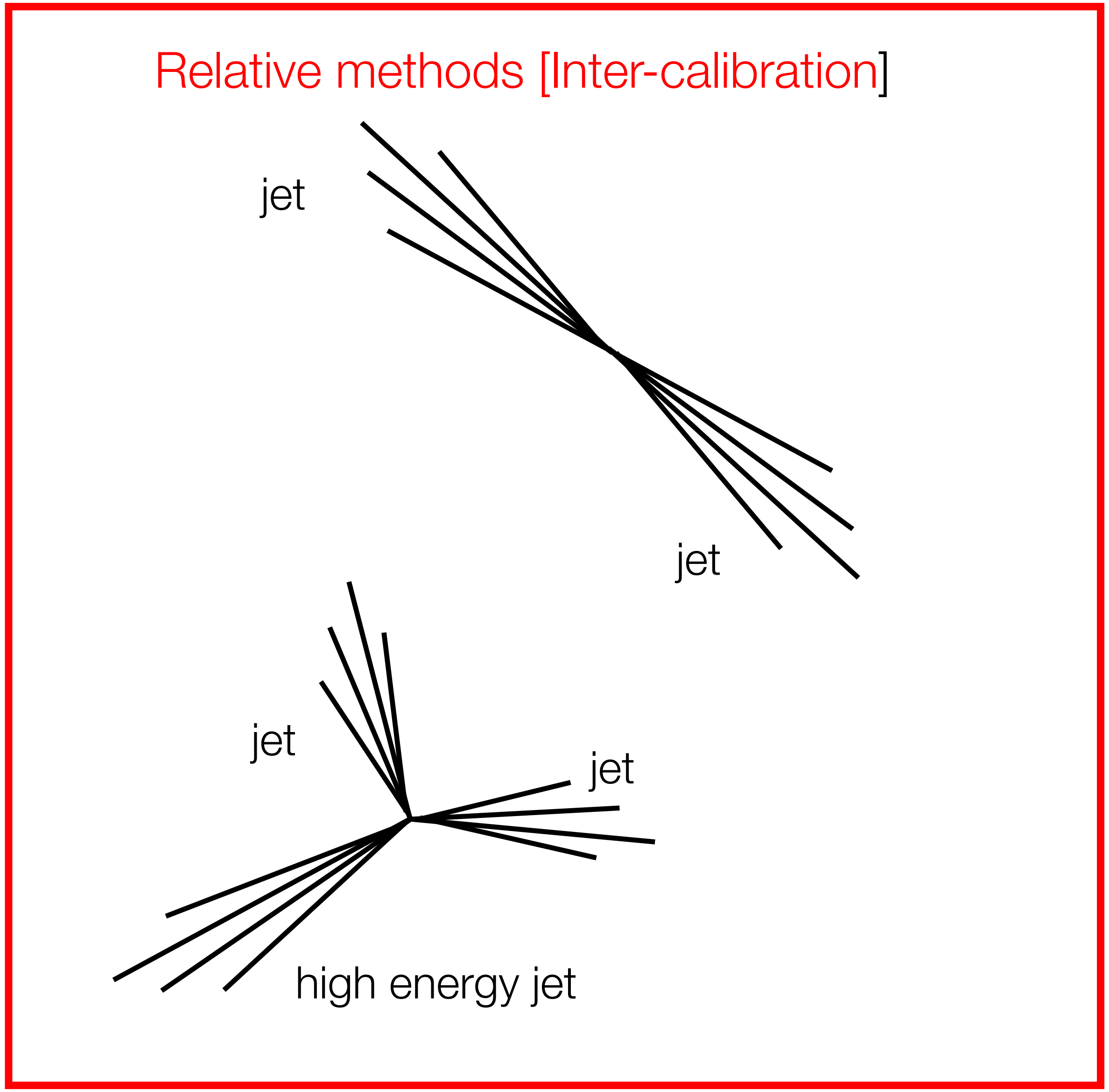




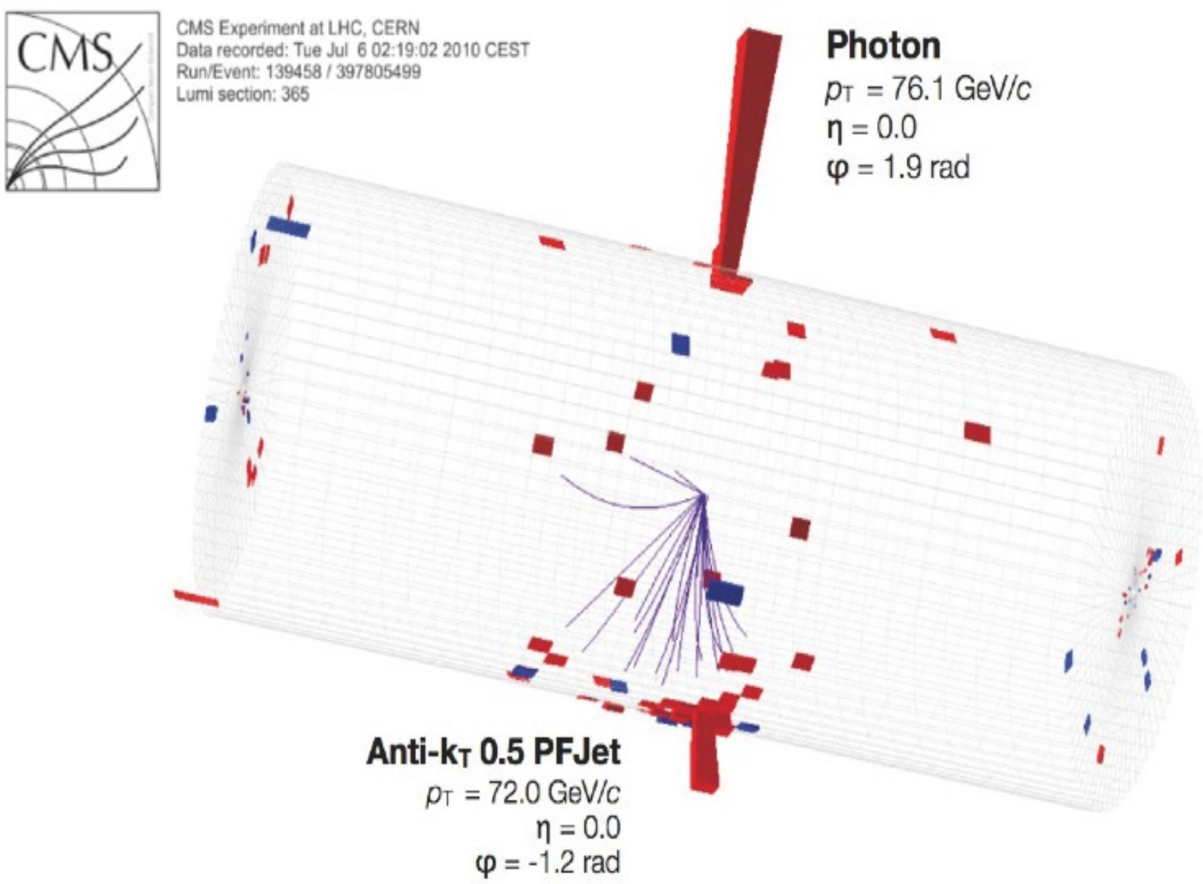
In the anti-kT jet reconstruction algorithm, are all circular

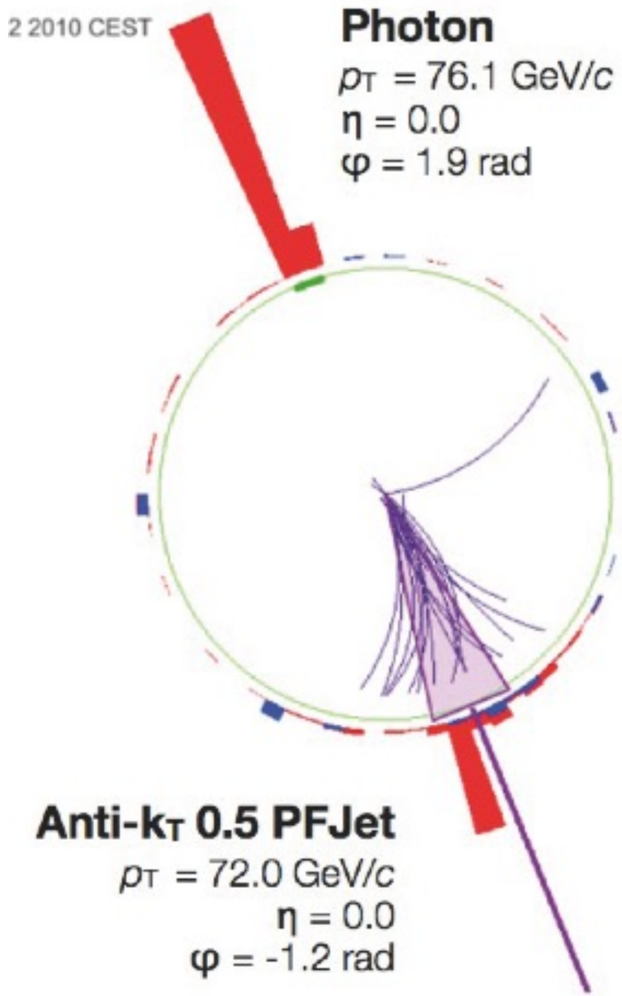
How to Calibrate a Jet?





One CMS Example





Absolute Method Uses p_t balance in back-to-back photon+jet events

Missing Transverse Energy E_T

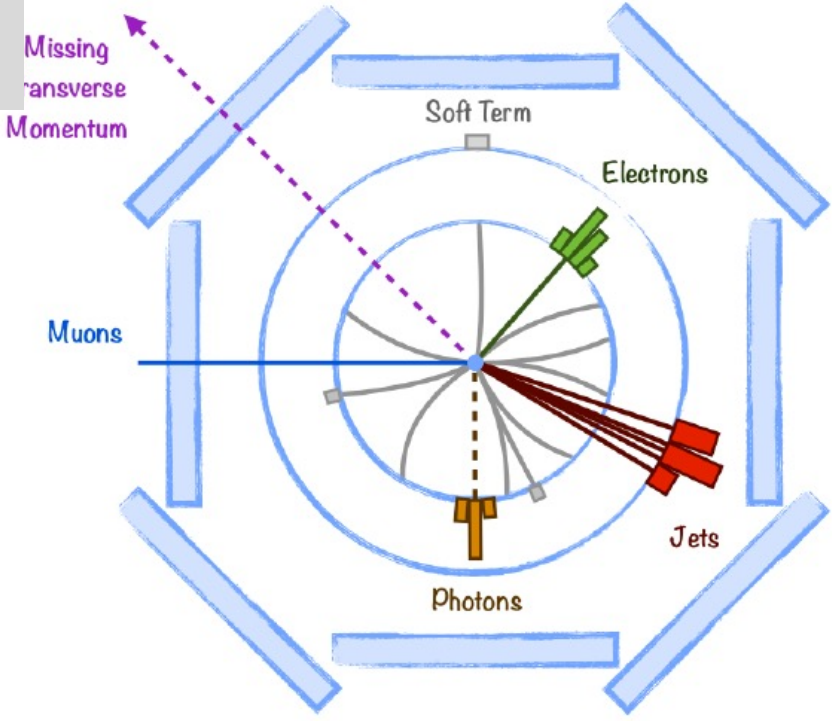
It is ONLY in the transverse plane that p_T is conserved (at hadron colliders)

$\sum_{All\ particles} p_T = 0.$ $\sum_{All\ particles} p_l = ?\ (x_1, x_2\ unknown!)$

$$\vec{E}_T^{miss} = -\Sigma_i \vec{E}_T^i$$

missing transverse energy = minus the vector sum of the transverse energy deposits. It is a proxy of the energy carried away from undetected particles.

→ W bosons, top quark events and supersymmetric particle searches (with neutrinos or neutrinos-like particles in the decay channels).



Another important quantity that is often referred to is the total transverse energy, which is the scalar sum of the transverse energy deposits:

$$\sum E_T = \sum_i E_T^i$$

Missing Transverse Energy (MET)

The missing transverse energy and the total energy measurements are calculated using objects from Particle Flow

ATLAS & CMS in 2 Words

ATLAS: To reconstruct E_T^{miss} , fully calibrated electrons, muons, photons, hadronically decaying τ-leptons, and jets, reconstructed from calorimeter energy deposits, and charged-particle tracks are used. These are combined with the soft hadronic activity measured by reconstructed charged-particle tracks not associated with the hard objects. Possible double counting of contributions from reconstructed charged-particle tracks from the inner detector, energy deposits in the calorimeter, and reconstructed muons from the muon spectrometer is avoided by applying a signal ambiguity resolution procedure which rejects already used signals when combining the various E_T^{miss} contributions

CMS: The optimal response and resolution of E_T^{miss} can be obtained using a global particle-flow reconstruction. The particle-flow technique reconstructs a complete, unique list of particles (PF particles) in each event using an optimized combination of information from all CMS subdetector systems. Reconstructed and identified particles include muons, electrons (with associated bremsstrahlung photons), photons (including conversions in the tracker volume), and charged and neutral hadrons. Particle-flow jets (PF Jets) are constructed from PF particles.

Computing MET

Use:

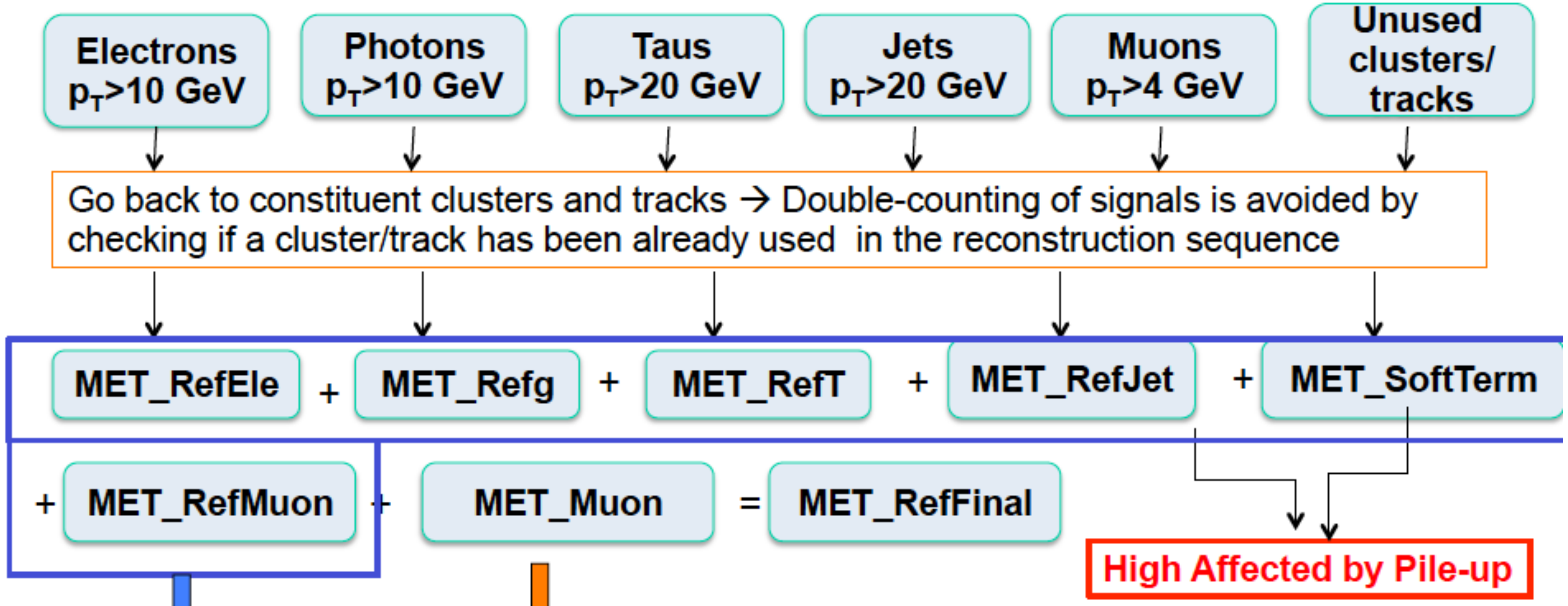
- electrons,
- muons,
- photons,
- hadronically decaying τ-leptons,
- jets, from calorimeters & charged-particles
- soft hadronic activity

Avoid

Double counting!

MET implies

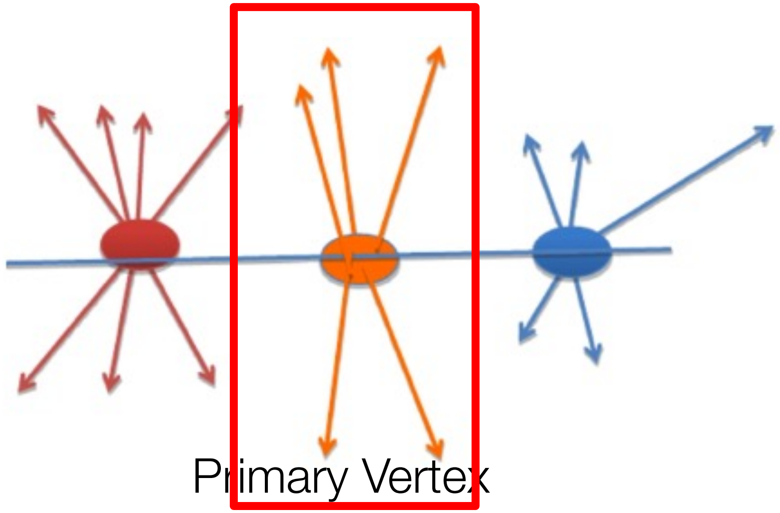
- Different objects are used → many different corrections
- Avoid double counting (→ PF algorithm)



$$\vec{E}_T^{miss,calo} + \vec{E}_T^{miss,muons} = \vec{E}_T^{miss}$$

MET & Pile-Up & Soft Terms

MET is affected by pile-up



- Tracks can be associated to vertices
- Energy depositions in calorimeters cannot be associated to vertices

Compute the ratio Jet Vertex Fraction for each jet:

$$JVF = \sum_{tracks,PV} p_T / \sum_{tracks} p_T$$

How much total momentum of a jet does not come from the PV?

Remove Jets with JVF < cut

Soft Term = un-associated E_{dep}s in calorimeters

Methods developed to remove *Soft term*

E_T^{miss} Resolution in ATLAS & CMS

Study the $(E_{miss})_{x,y}$ distribution for a sample of “minimum bias events” (expected to have no real E_T^{miss}).

Use events with one Z boson or an isolated γ (converting!) is present. These events are produced in collisions

- qg → qγ,
- $q\bar{q}$ → Z,
- qg → qZ, and
- $q\bar{q}$ → γ.

$E_T^{miss} \sim 0.$ is in these events

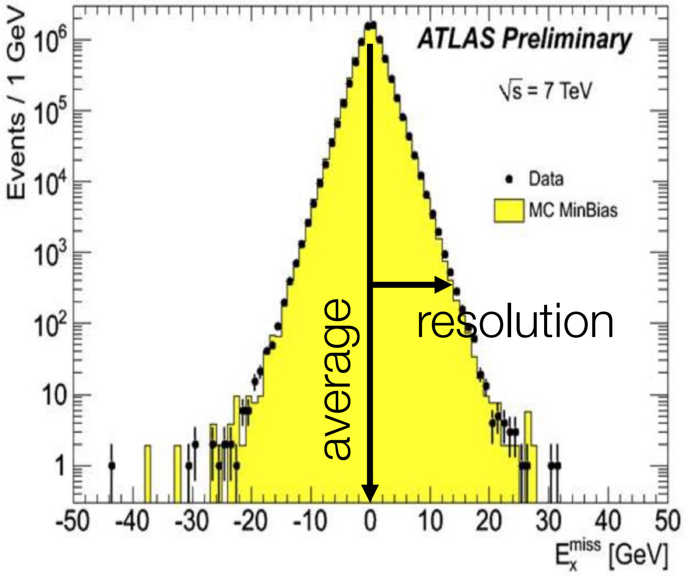
- remove objects from the Z,γ decay/conversion
- $E_T^{miss} \sim E_T^{Z,\gamma}$
- Compare the momenta of the well-measured boson to the E_T^{miss}

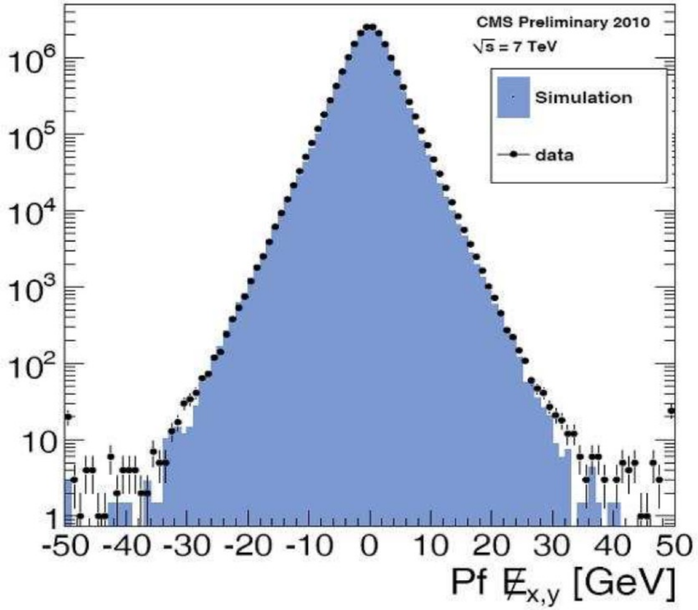
A study of the performance gives:

$\sigma(E_{miss}) = 37\%/\sqrt{\sum E}$ for ATLAS and

$\sigma(E_{miss}) = 45\%/\sqrt{\sum E}$ for CMS.

The two results are ~similar, some of the PFs approaches used in CMS also used in clustering algorithms in ATLAS





Use of Simulation in Data Analysis

The Reason Why we Need Monte Carlo Events

The way to a cross section measurement (real life)

- Identify a measurement you are interested in (call it “signal”), understand its topology and kinematics
- Identify possible “background” processes with similar topology and kinematics (in general $N_b \gg N_s$)
- Identify a possible selection that produces a sample of events rich in signal and poor in background events → Magnify your signal over background
- Apply the selection and count events

$\sigma = \frac{N_{Signal\ Events}}{\mathcal{L}}$	Ideal expression
$\sigma = \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot efficiency}$	More realistic expression
$\sigma = \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot \varepsilon_{trigger} \cdot \varepsilon_{selection} \cdot Acceptance}$	Realistic expression

$$\sigma = \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot \varepsilon_{trigger} \cdot \varepsilon_{selection} \cdot Acceptance}$$

All parameters differ between *Signal* and *Background*

Of Monte Carlo Events in Analysis

This is the ideal case:

$$\sigma^{signal} = \frac{N_{total}^{signal}}{\mathcal{L}} \Longrightarrow \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot \varepsilon_{trigger} \cdot \varepsilon_{selection} \cdot Acceptance}$$

your detector sees everything with perfect resolution, no loss no imperfection

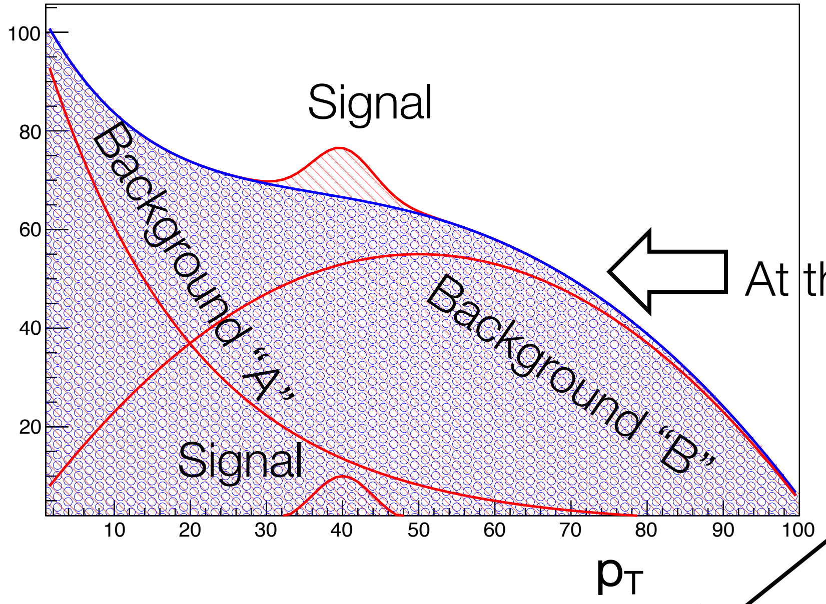
This is the real life:

your detector does NOT see everything has a resolution, has losses, imperfections

- σ^{signal} is the cross section of the interaction you want to study
- $\mathcal{L}$ is the total luminosity you have collected
- N_{total}^{signal} is the number of signal events with cross section σ
- $N_{selected}$ is the number of events at the end of you analysis (signal + background!)
- $N_{background}$ is the number of background events at the end of you analysis. How to evaluate them? Later
- Data have been collected using a trigger. All triggers have inefficiencies → trigger efficiency $\varepsilon_{trigger}$
- To improve the visibility of your signal over background you apply selection cuts → only a fraction of events survive $\varepsilon_{selection}$
- Your detector is NOT really hermetic, there are holes, cracks, non-instrumented zones → only a fraction of events are in the sensitive region of your experiment → $Acceptance$

Of Monte Carlo Events in Analysis

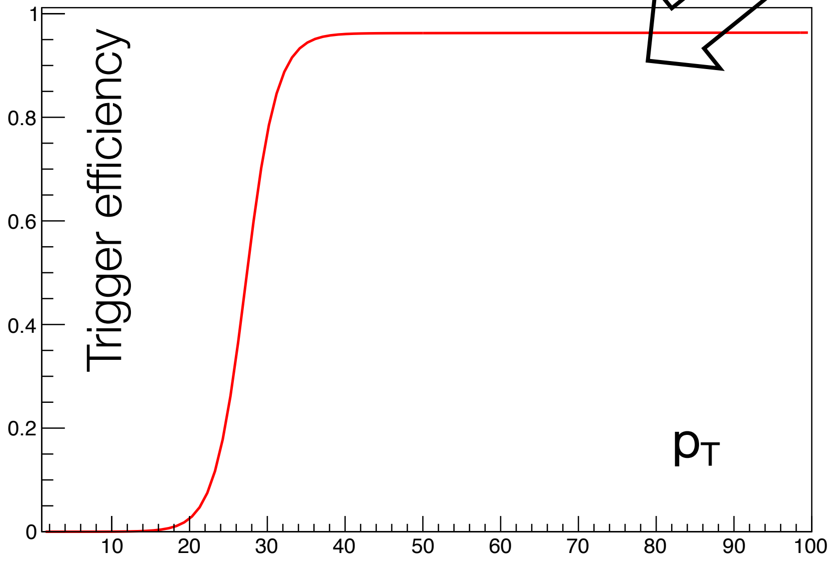
$$\sigma^{signal} = \frac{N^{signal}_{total}}{\mathcal{L}} = \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot \varepsilon_{trigger} \cdot \varepsilon_{selection} \cdot Acceptance}$$

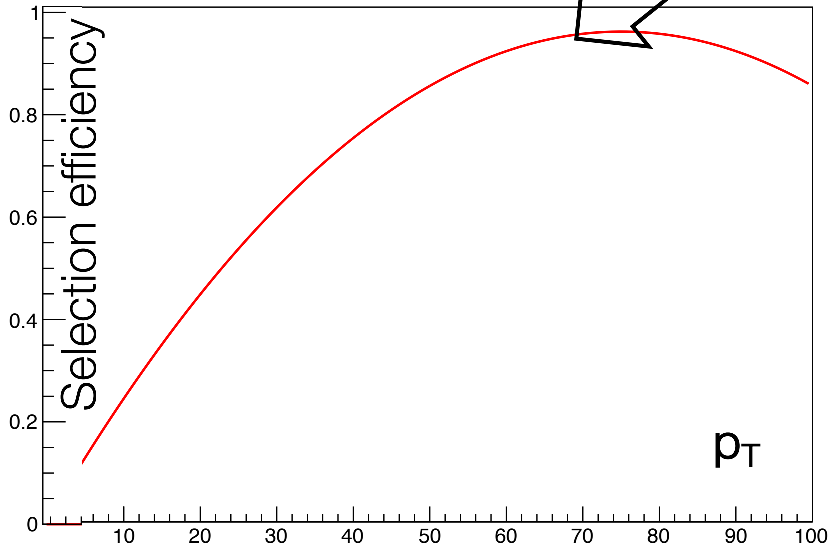


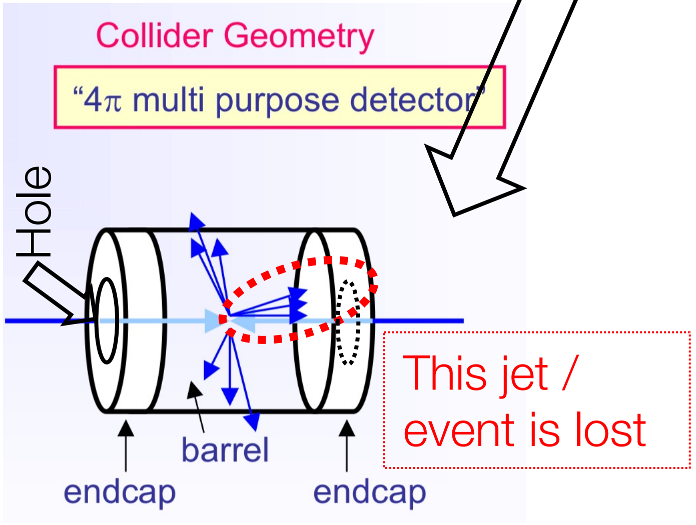
At the start, you have signal events and two types of background events A and B

You collect events using a trigger

you select them to improve S/B

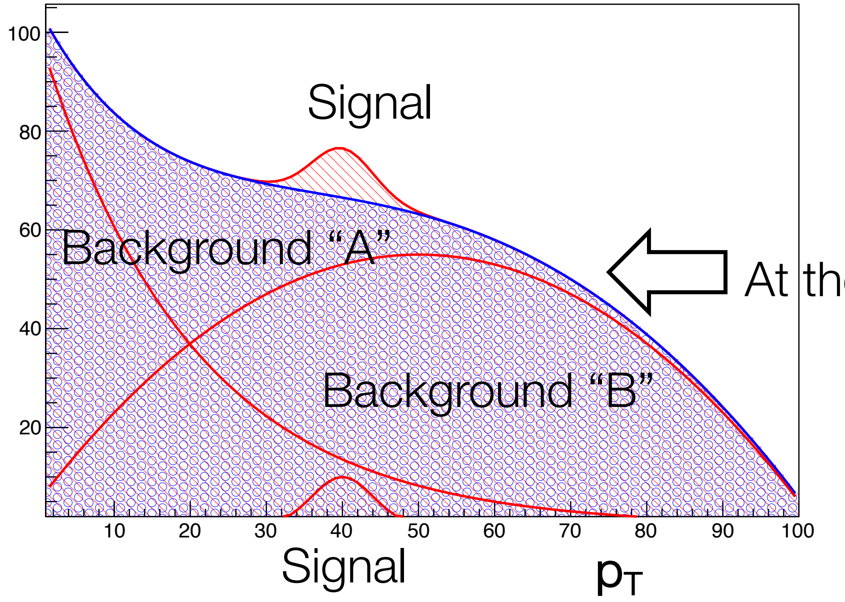






Toni Baroncelli: Detectors

Of Monte Carlo Events in Analysis



$$\sigma^{signal} = \frac{N^{signal}_{total}}{\mathcal{L}} = \frac{N_{selected} - N_{background}}{\mathcal{L} \cdot \varepsilon_{trigger} \cdot \varepsilon_{selection} \cdot Acceptance}$$

At the start, you have signal events and two types of background events A and B

- $N_{selected}$ is counted
- $\mathcal{L}$ is measured
- $\varepsilon_{trigger}$ is ~ measured

Correct 'too good' simulations:

- Use 'standard candles'
- Use Control Regions *(next slide)* and Validation Regions check/calibrate/modify your simulation

- ***$\varepsilon_{selection}$, $Acceptance$, $N_{background}$,*** are estimated using simulated events

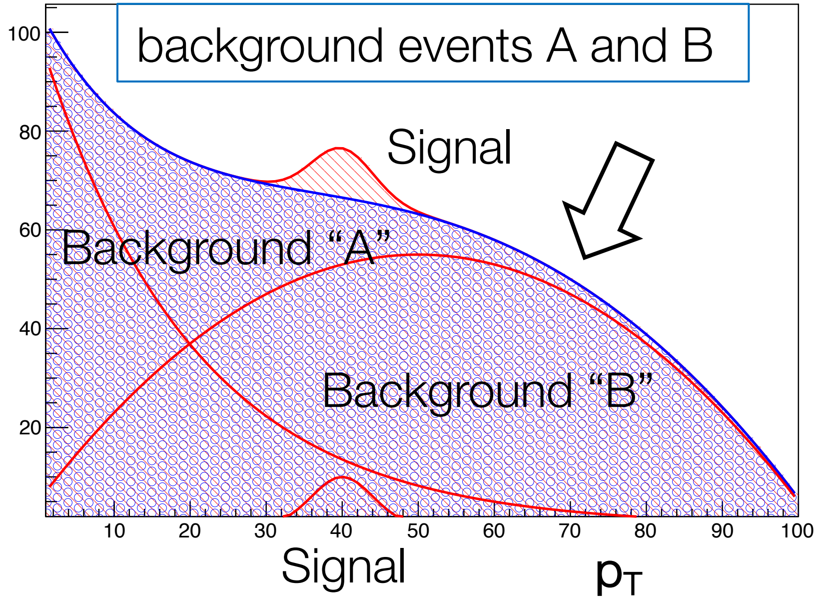
NB: the Monte Carlo is
- *almost* always 'optimistic' → material, resolution, efficiency
- Mitigate 'optimism': add additional smearing: if the resolution is too good add a gaussian random number with appropriate characteristics every measurement

$$p_T^{add.smearing} = p_T + rndm \cdot \sigma_{add.smearing}$$

→worsen resolution

The p_T of a track in your simulated event

Data-driven Background Estimation



Use Simulation and Control Region(s)

ASSUME that

$$N^{A,SR}_{Data}/N^{A,CR}_{Data} = N^{A,SR}_{MC}/N^{A,CR}_{MC}$$

$$N^{B,SR}_{Data}/N^{B,CR}_{Data} = N^{B,SR}_{MC}/N^{B,CR}_{MC}$$

Define Control Regions!

Signal Region: 'optimised' kinematical region that contains your signal (selection cuts)

- Count background events in SRs as predicted by Monte Carlo: $N^{A,SR}_{MC}$, $N^{B,SR}_{MC}$

Control Region (CRs) : kinematical region ORTOGONAL to the signal region that

- Contains the background you want to measure
- Doesn't contain signal events
- Count events in CRs: both Monte Carlo and Data
  - MC simulated events: $N^{A,CR}_{MC}$, $N^{B,CR}_{MC}$
  - Data: $N^{A,CR}_{Data}$, $N^{B,CR}_{Data}$

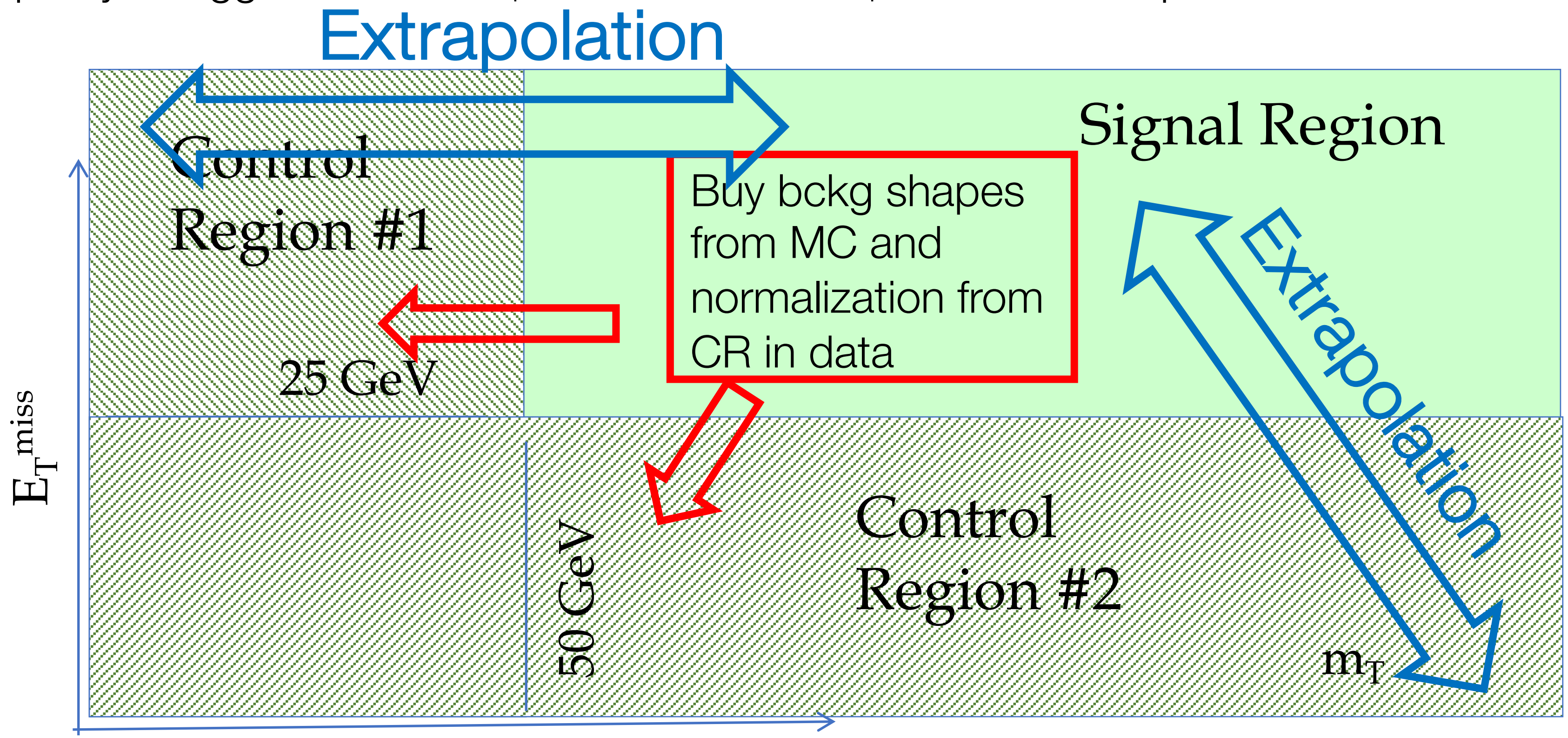
$$N^{B,SR}_{Data} = N^{B,SR}_{MC} * N^{B,CR}_{Data}/N^{B,CR}_{MC}$$

(Integral of distribution)

Normalise MC prediction to Data

Control Regions (2D cartoon)

- Signal Region (SR) contains events we want to select, Control Regions are close to SR but ortogonal. Need to have no correlation between SR&CR. You choose them to be mostly populated by the background you want to control
- SR: Lepton quality & trigger match & $E_T^{miss} > 25$ GeV & $m_T > 50$ GeV & lepton isolation & Overlap Removal (OR)



Background from heavy flavours decays and (for electrons) photon conversions determined using a "data-driven" technique.

Material

CERN School 2017: Rende Steerenberg: Hadron Accelerators-1
CERN School 2017: Rende Steerenberg: Hadron Accelerators-2
The Physics of Particle Detectors
M. Tanabashi et al. (Particle Data Group), Phys. Rev. D 98, 030001 (2018)

Passage of particles through matter, pages 446-460

Particle detectors at accelerators, pages 461-495

Books

1. Sylvie Braibant, Paolo Giacomelli, Maurizio Spurio: Particles and Fundamental Interactions, An Introduction to Particle Physics. Springer
2. DetectorsTokyo.pdf
3. Particle-detectors.pdf
4. Detectors-Full.pdf

End of Detectors

Particle Physics
Toni Baroncelli
Haiping Peng
USTC