

阻性阳极GEM探测器研究进展

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- 探测器基本介绍
- 探测器均匀性研究
- 阻性阳极读出板参数研究
- 总结与计划

探测器基本介绍

阻性阳极二维插值读出方法

- 目的:

- 研究阻性阳极二维插值读出方法
- 用于X射线成像等二维位置灵敏探测器

- 优点:

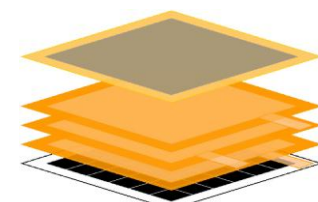
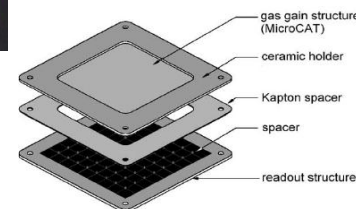
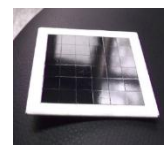
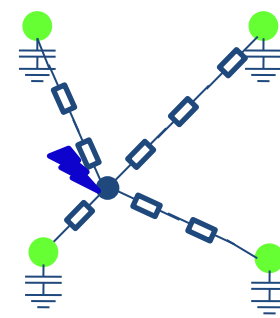
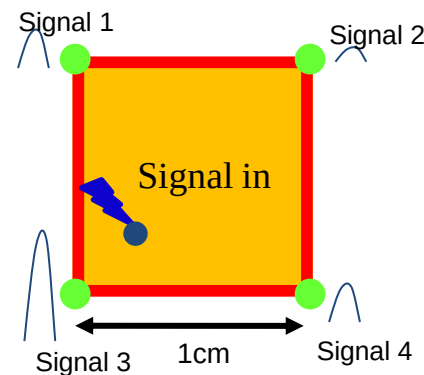
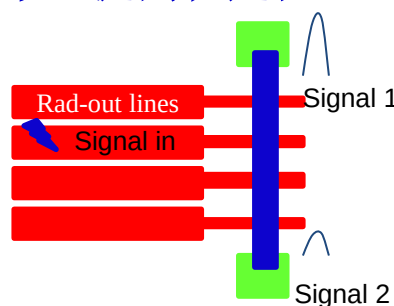
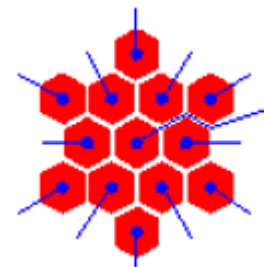
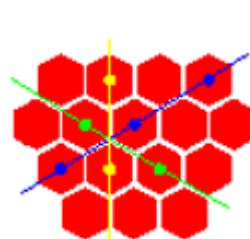
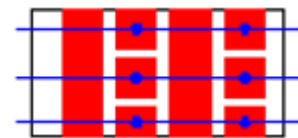
- 有效减少电子学, 降低探测器成本
 - ◆ 相同的位置分辨率, 通道数比像素读出减少**1-2个数量级**
- 降低GEM探测器连续放电几率, 提高稳定性

- 重点:

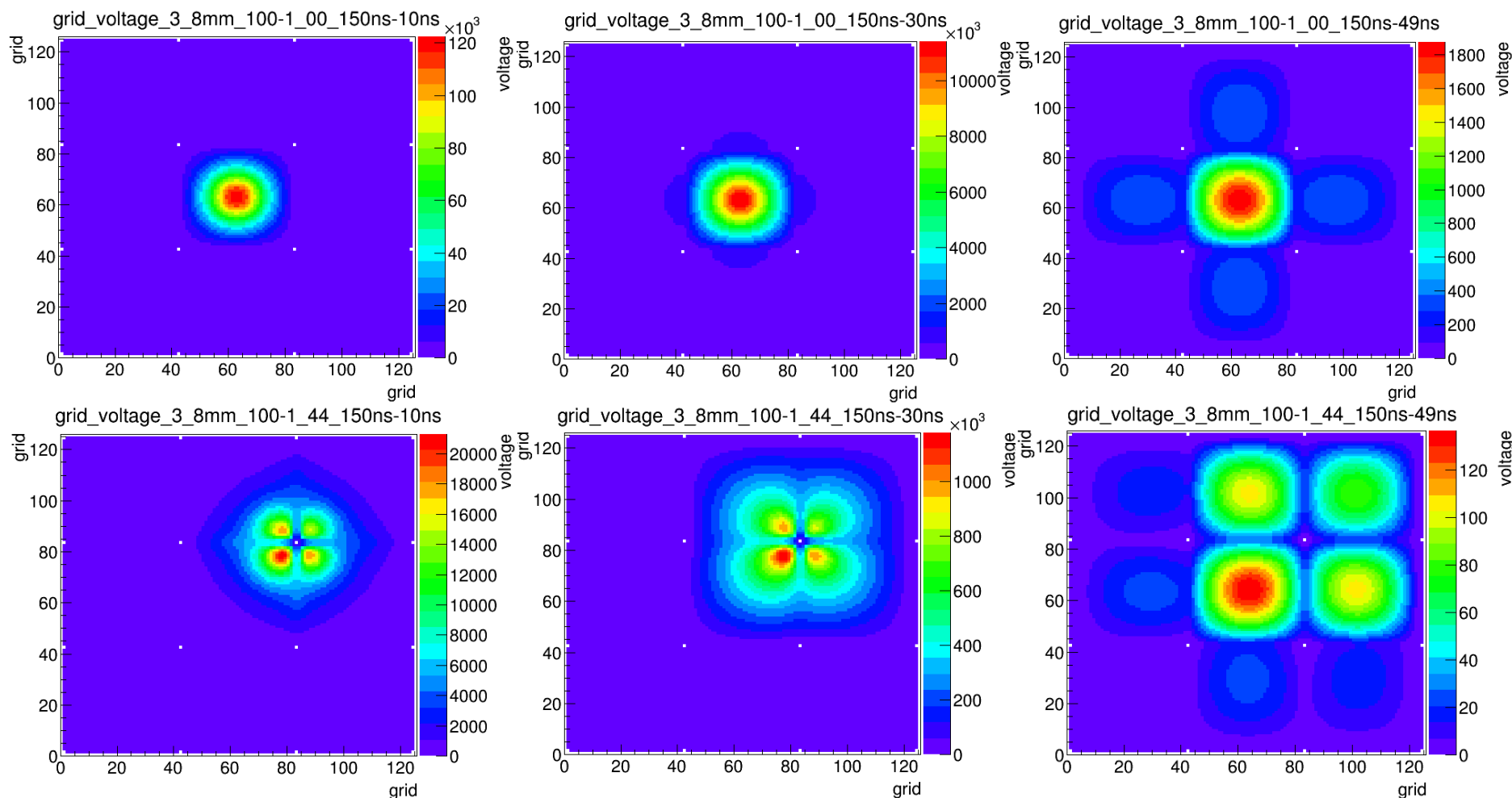
- 阻性阳极读出板
- 二维插值重建算法

- 应用:

- 可用于各种微结构探测器的读出极
- **Resistive Anode Gas Electron Multiplier**



RAGEM读出原理



- 原初电离电子经过三级GEM进行**雪崩放大**
- 雪崩放大后的电子向**阻性阳极平面**漂移，并在阻性阳极平面上**感应出电荷**
- **感应电荷**在**阻性阳极平面**上向周围**扩散**，并最终在收集节点处被收集进入前放

RAGEM重建算法

■ 4节点方法 -靠近中心

$$\begin{aligned} \diamond x_4 &= L \times \frac{(Q_{10}-Q_9)+(Q_6-Q_5)}{Q_5+Q_6+Q_9+Q_{10}} \\ \diamond y_4 &= L \times \frac{(Q_{10}-Q_6)+(Q_9-Q_5)}{Q_5+Q_6+Q_9+Q_{10}} \end{aligned}$$

■ 6节点方法 -靠近低阻条

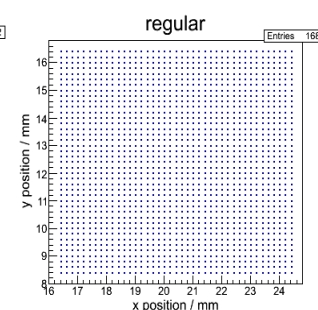
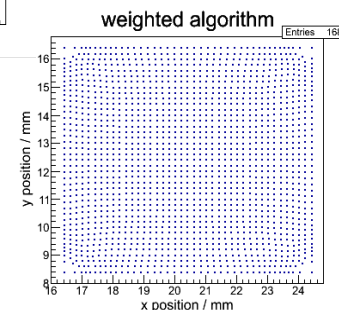
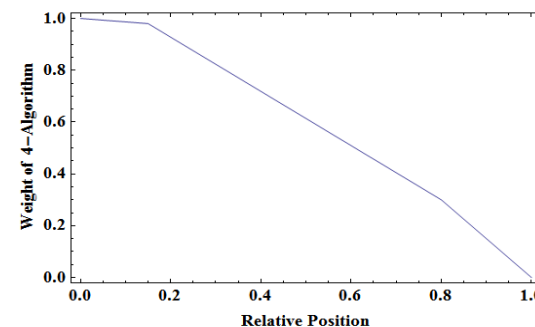
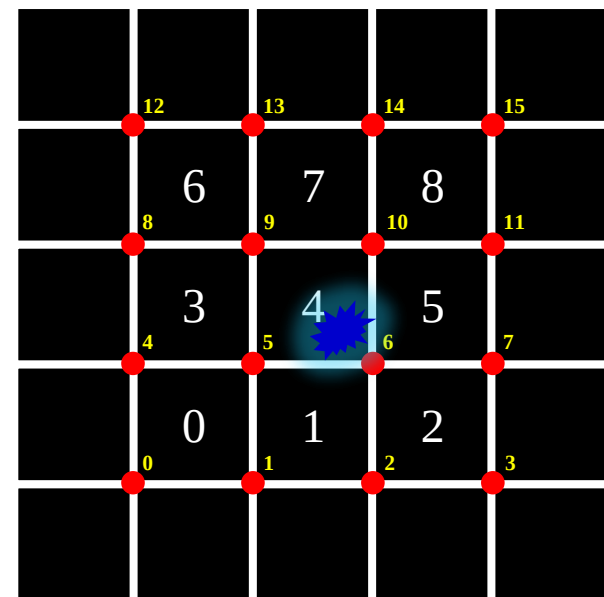
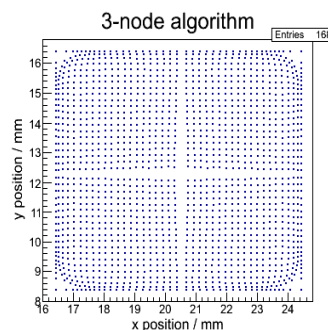
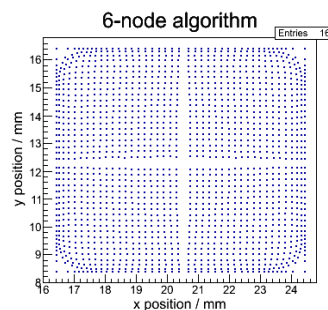
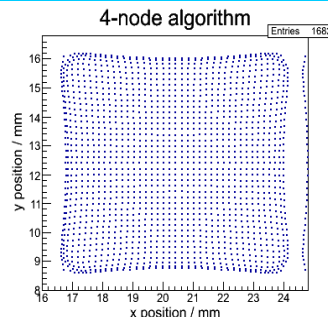
$$\begin{aligned} \diamond x_6 &= L \times \frac{(Q_{11}-Q_9)+(Q_7-Q_5)}{Q_{11}+Q_{10}+Q_9+Q_7+Q_6+Q_5} \\ \diamond y_6 &= L \times \frac{(Q_{10}-Q_2)+(Q_9-Q_1)}{Q_{10}+Q_6+Q_2+Q_9+Q_5+Q_1} \end{aligned}$$

■ 3节点方法 -靠近节点

$$\begin{aligned} \diamond x_3 &= L \times \frac{(Q_7-Q_5)}{Q_7+Q_6+Q_5} \\ \diamond y_3 &= L \times \frac{(Q_{10}-Q_2)}{Q_{10}+Q_6+Q_2} \end{aligned}$$

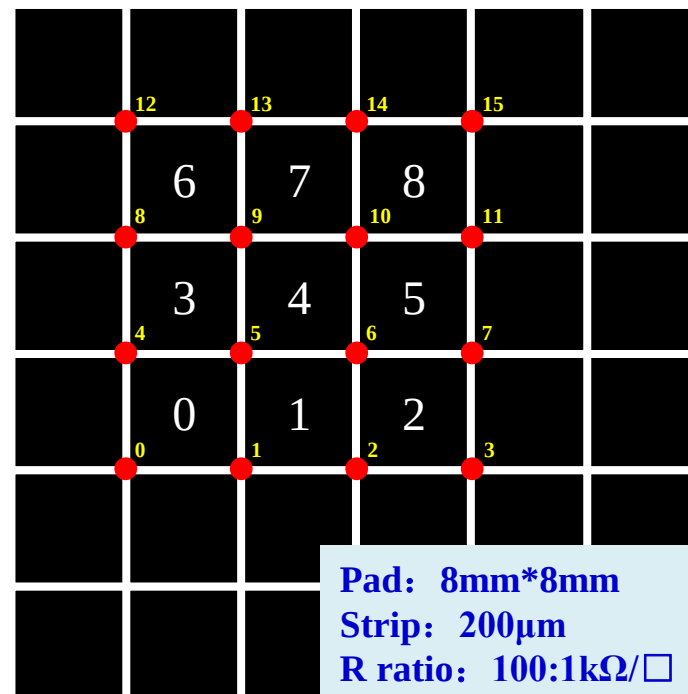
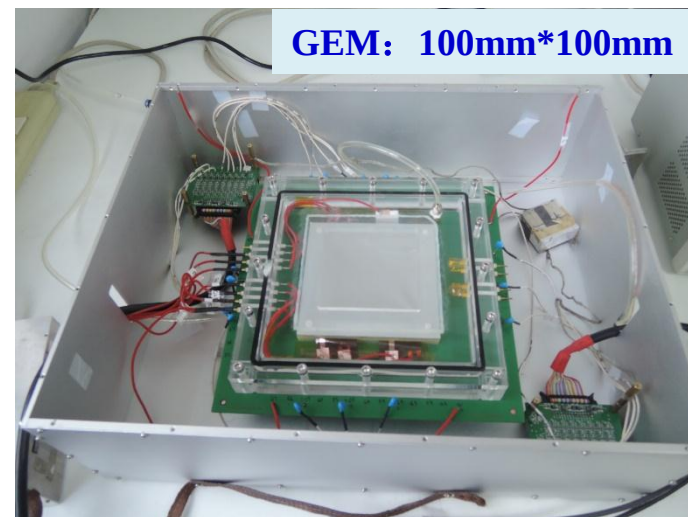
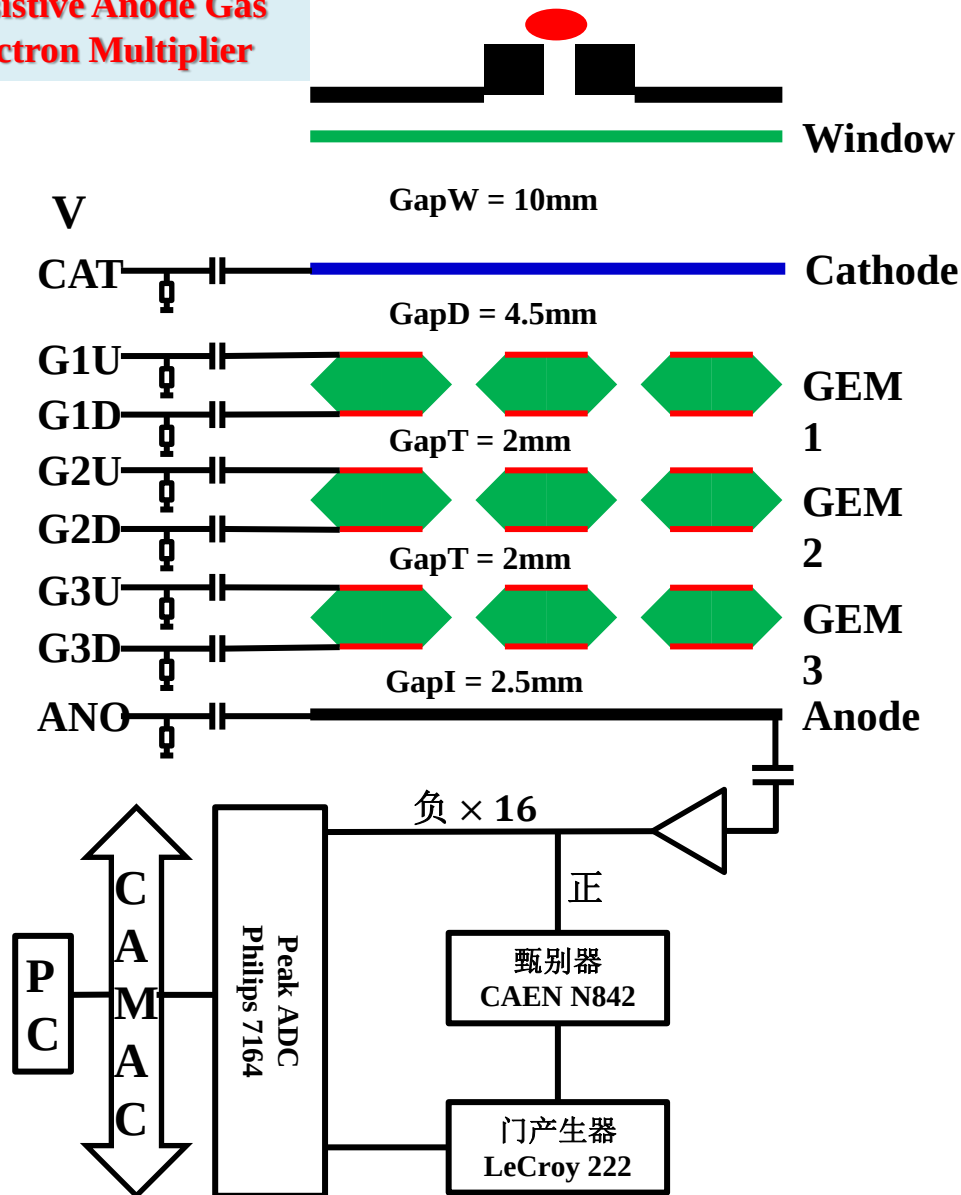
■ 346组合方法 -参数刻度

$$\begin{aligned} \diamond x &= a_x x_4 + (1 - a_x)[b_x x_3 + (1 - b_x)x_6] \\ \diamond y &= a_y y_4 + (1 - a_y)[b_y y_3 + (1 - b_y)y_6] \end{aligned}$$

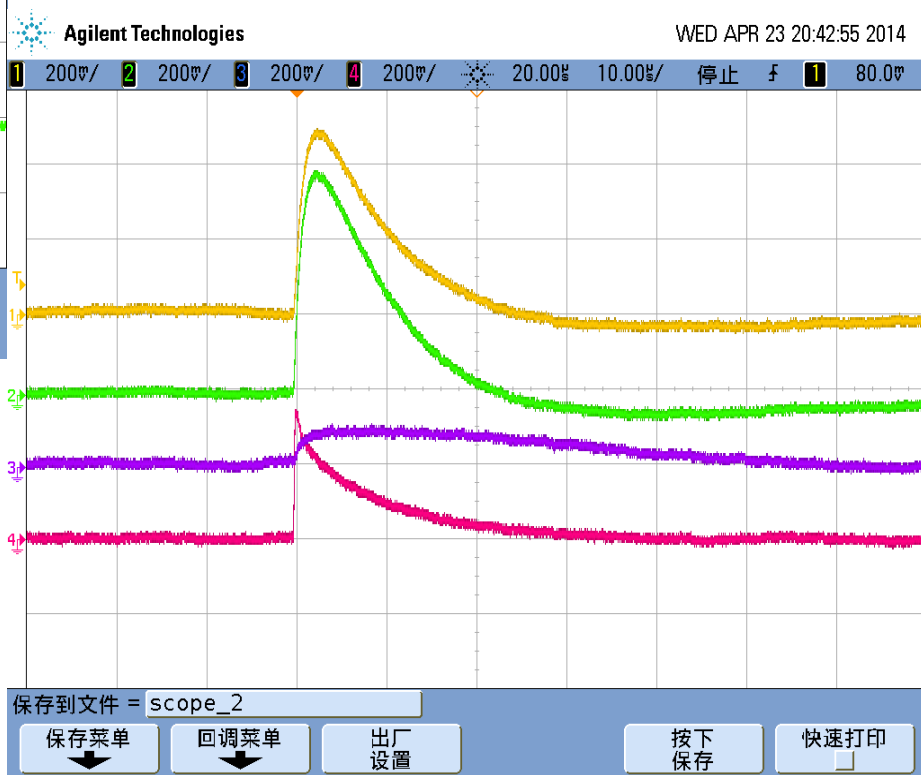
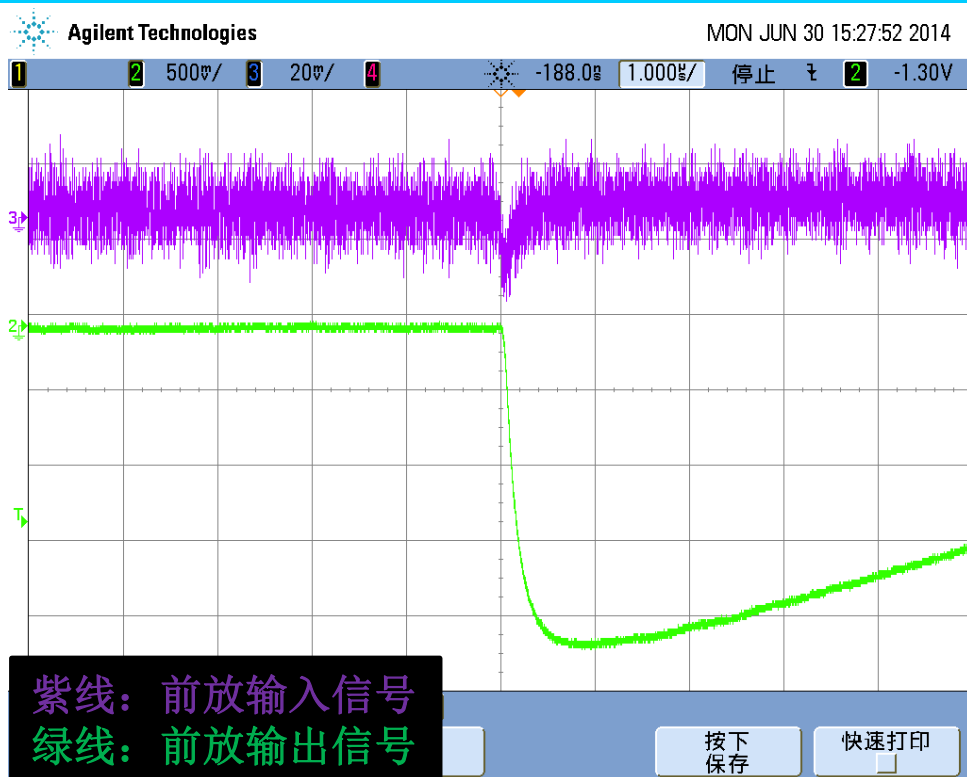


RAGEM原理机

Resistive Anode Gas Electron Multiplier

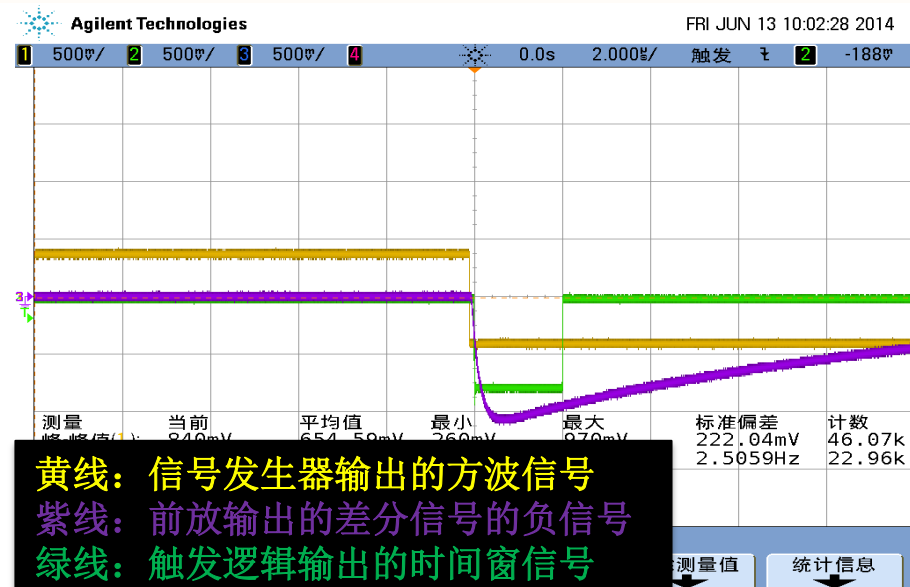
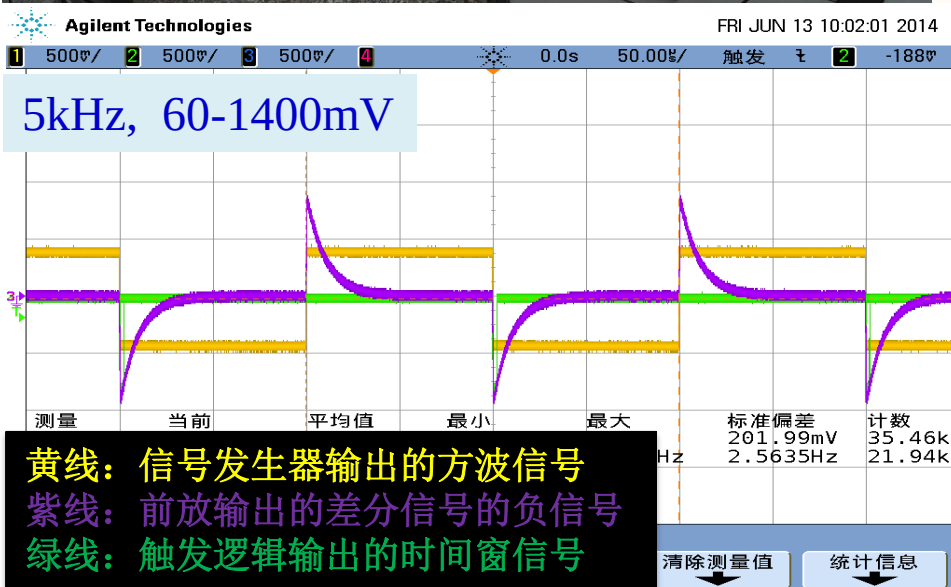
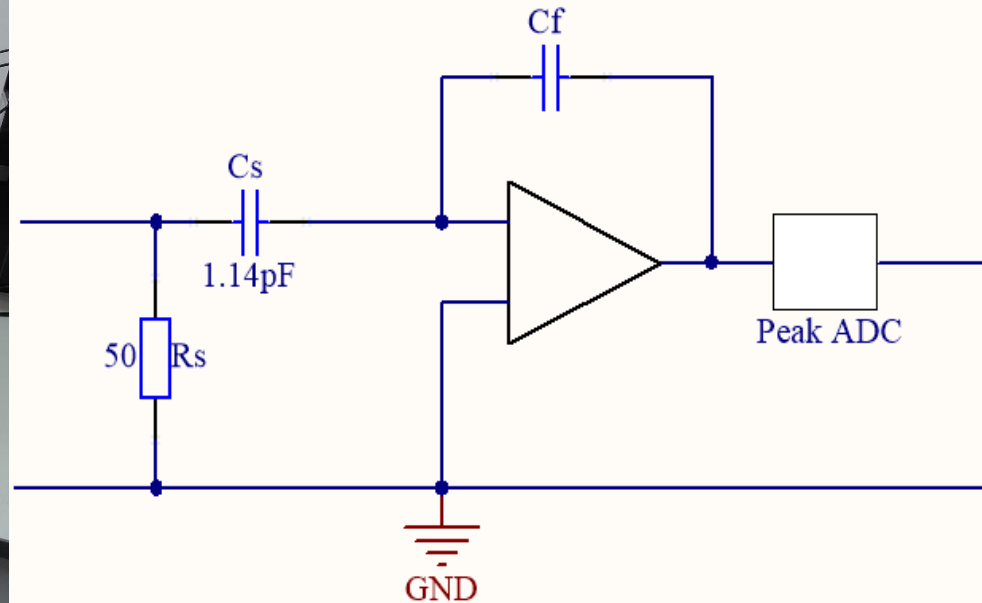


典型的RAGEM信号

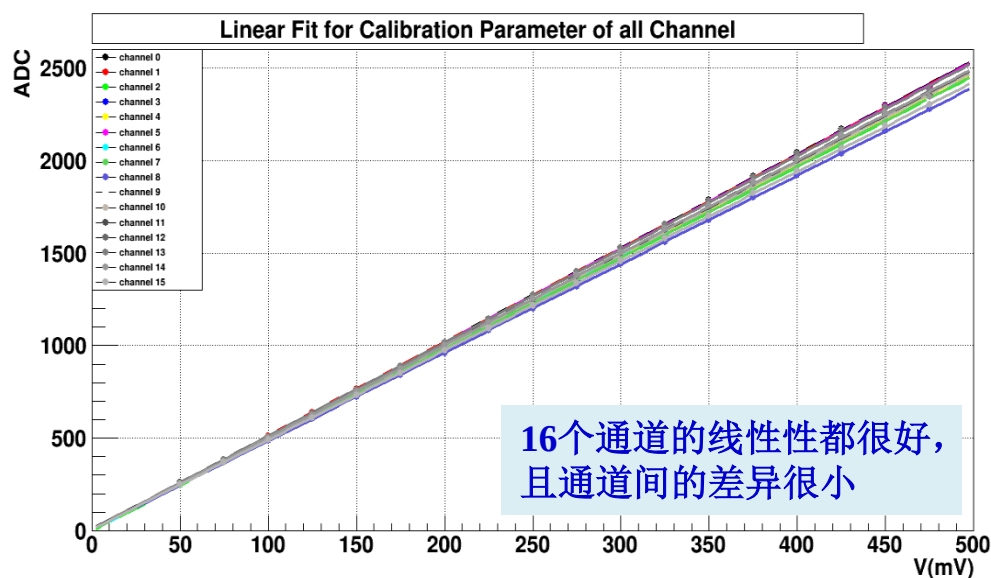
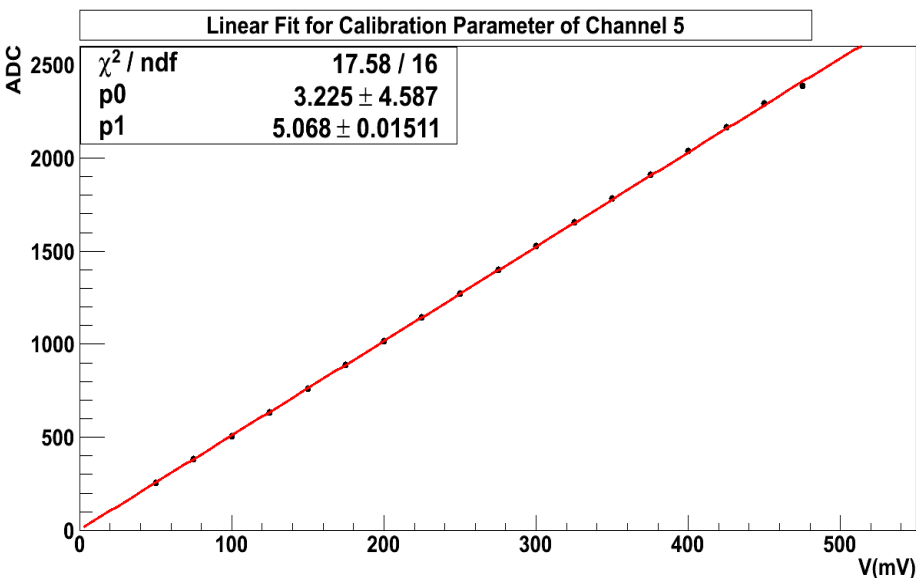
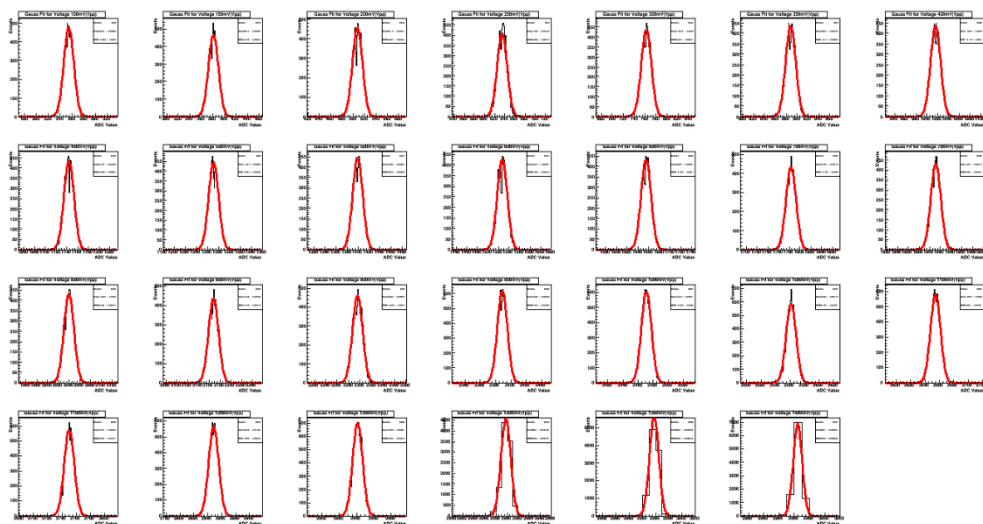
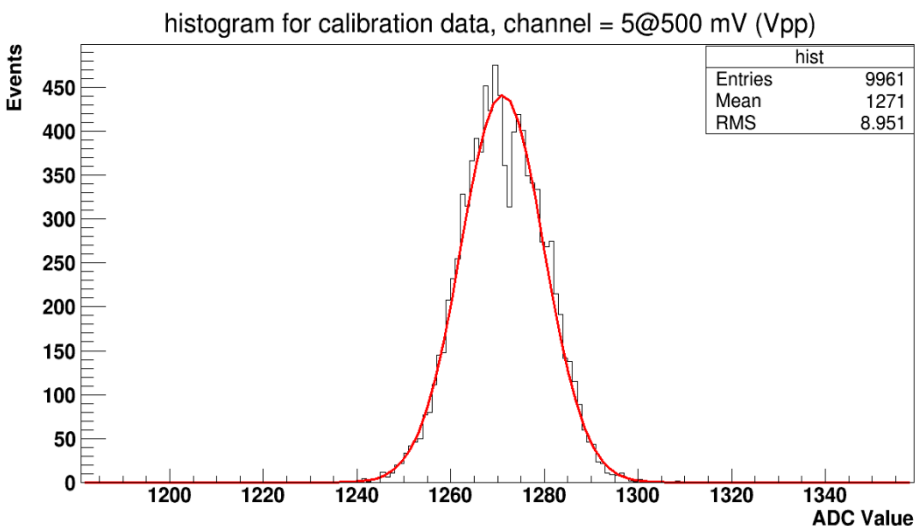


RAGEM均匀性研究

RAGEM电子学刻度

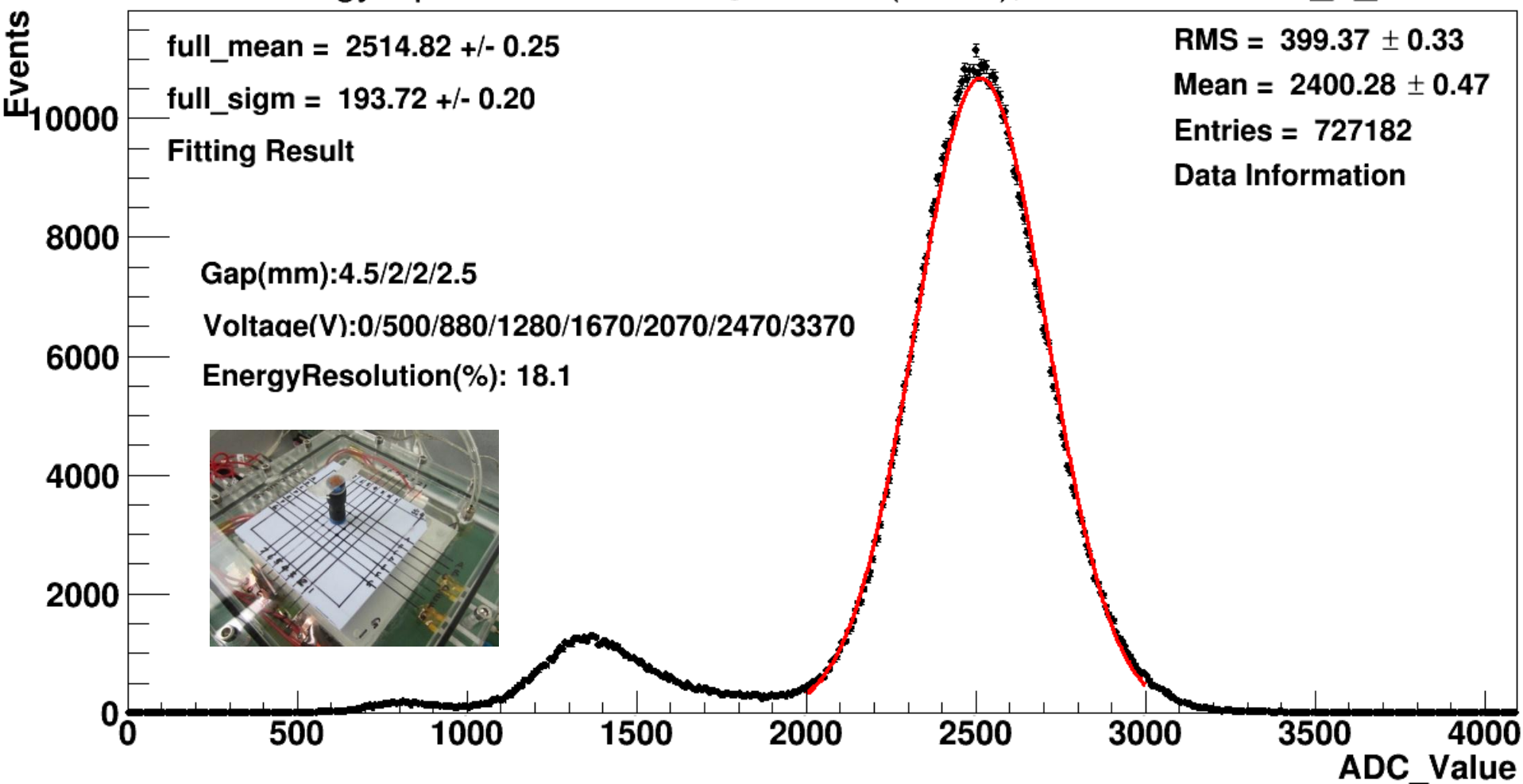


RAGEM电子学刻度

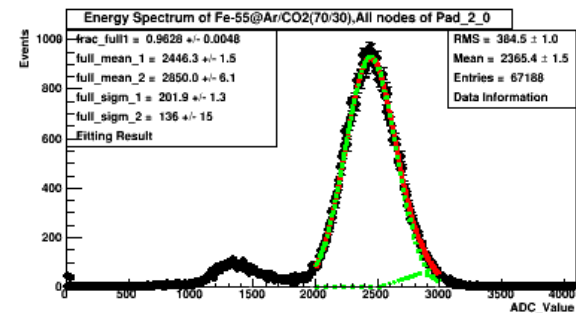
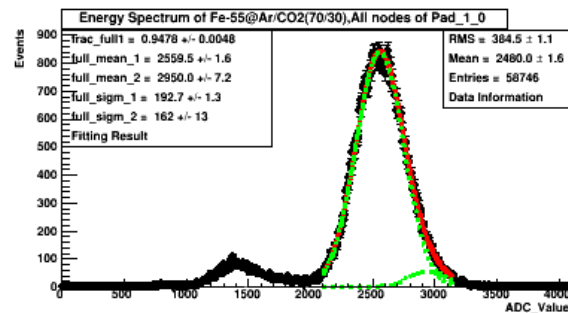
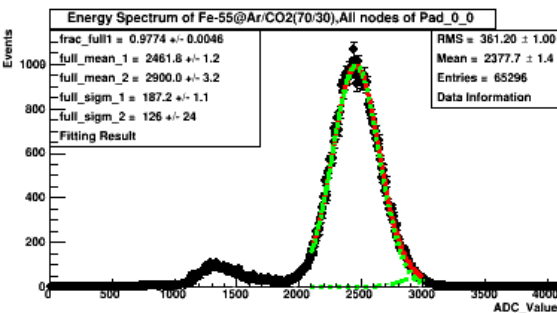
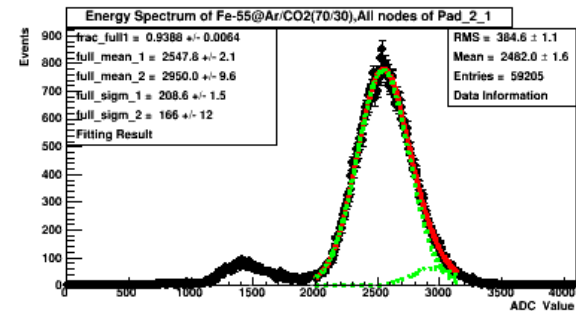
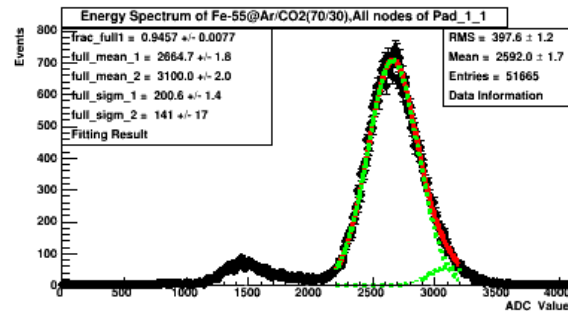
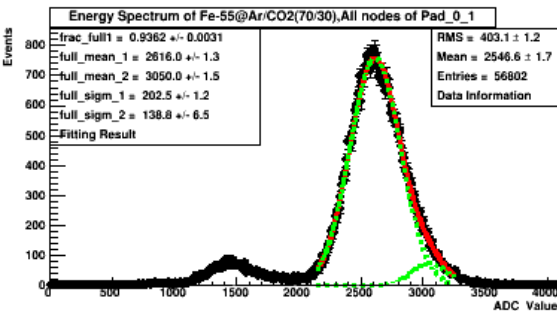
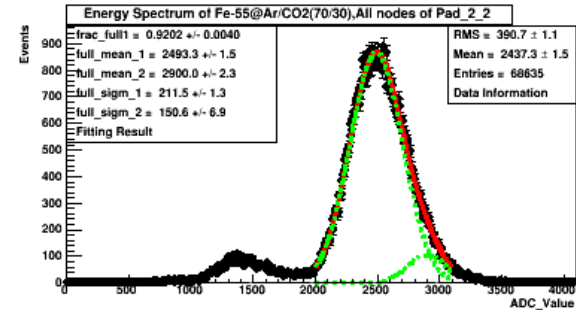
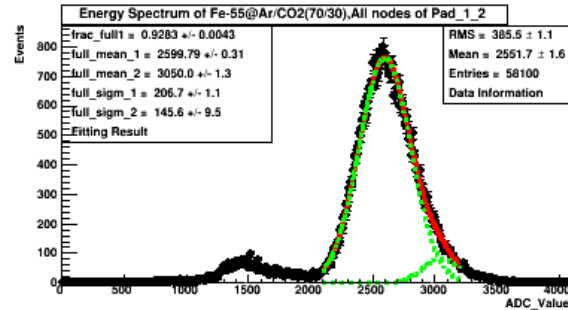
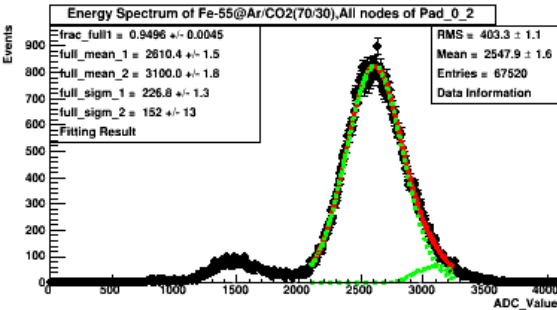


RAGEM能量分辨率

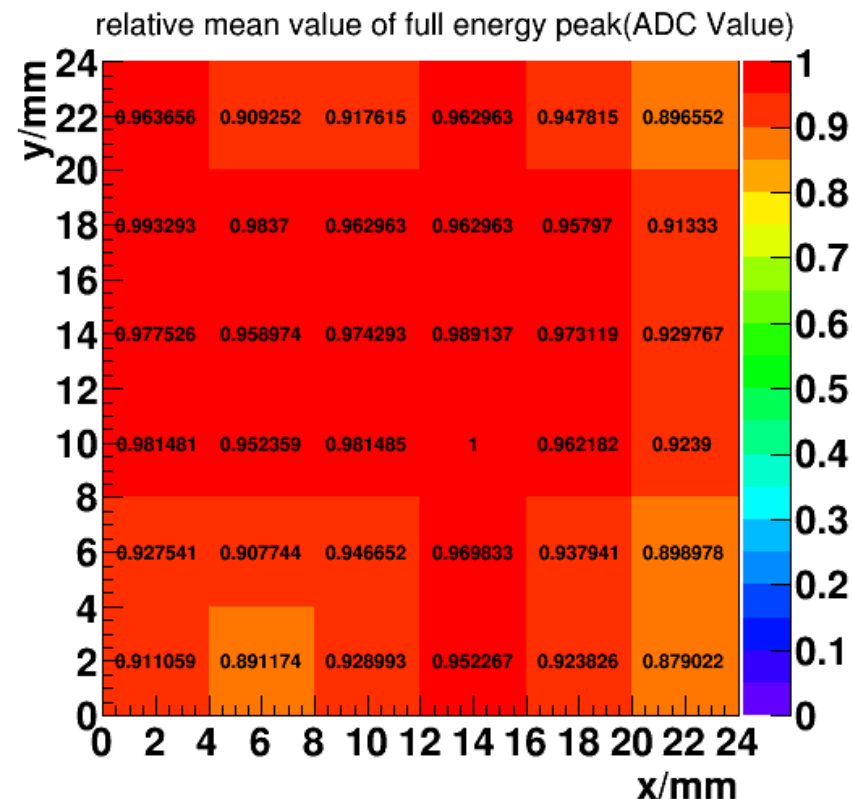
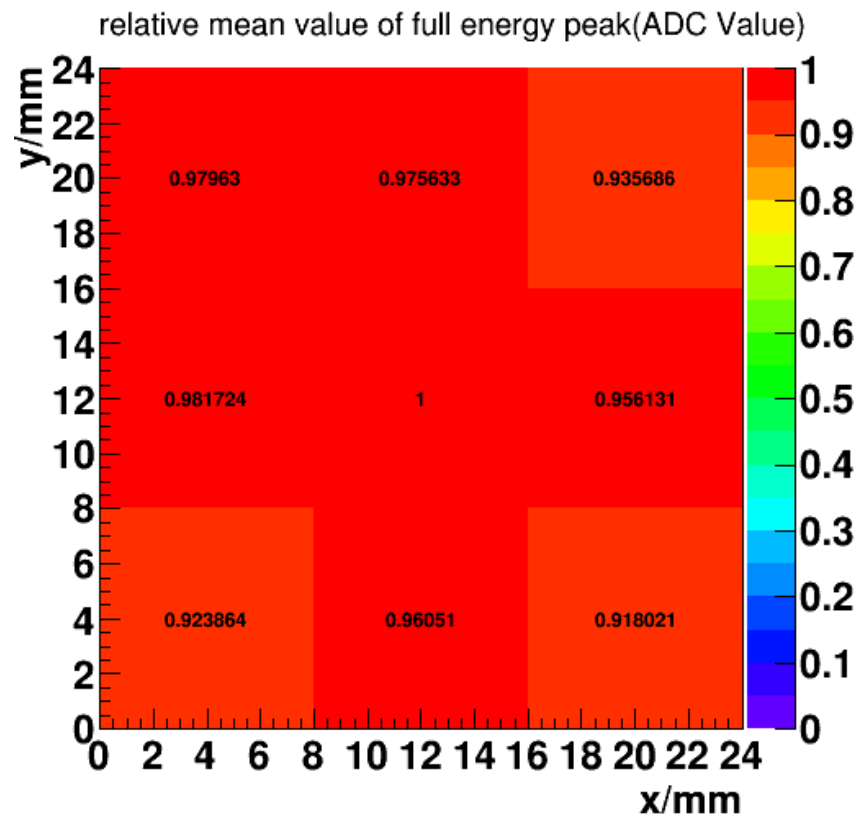
Energy Spectrum of Fe-55@Ar/CO2(70/30), All nodes of Pad_1_1



RAGEM能量分辨率

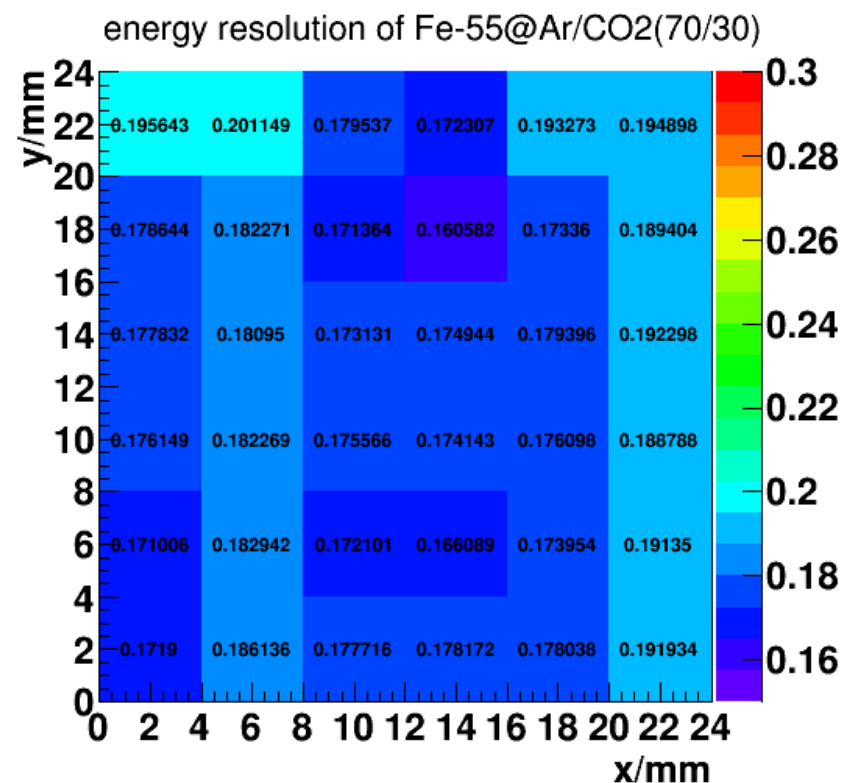
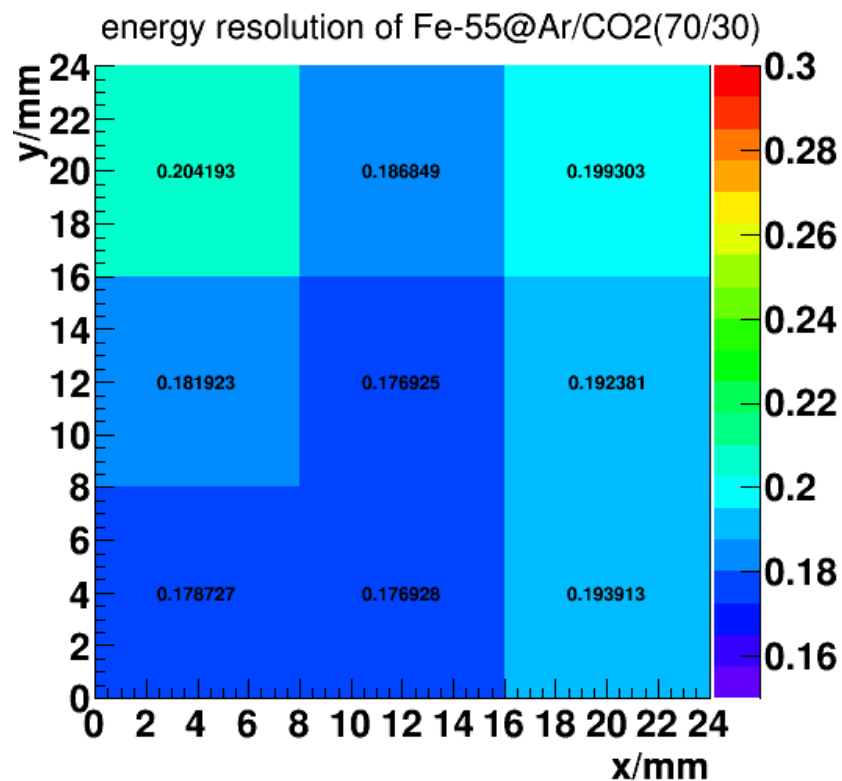


RAGEM增益均匀性



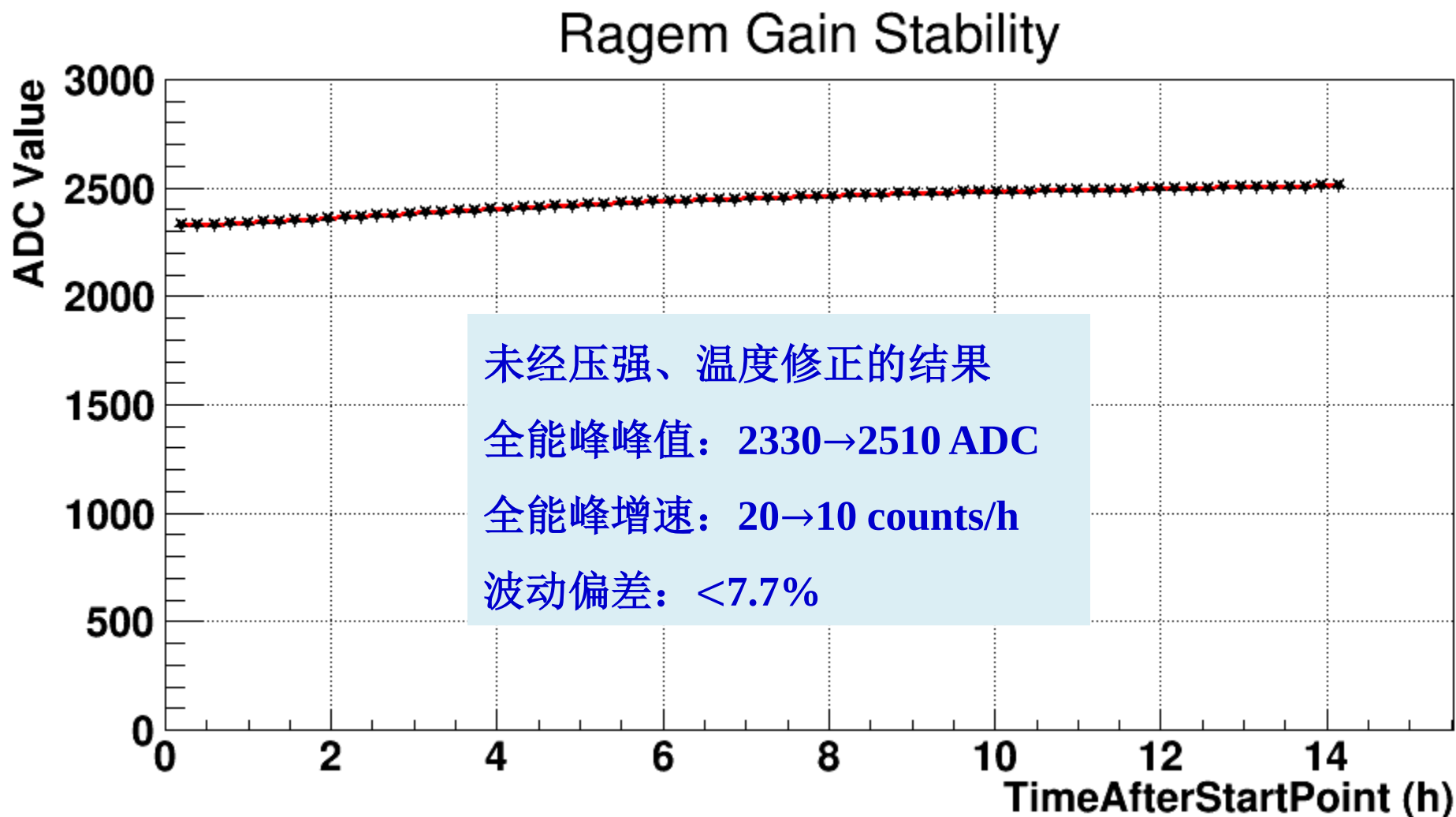
- 增益均匀性 **<8%** (~2500ADC), 中间Pad最大, 周围Pad相对较小
 - ◆ 压强和温度的影响, 探测器长时间工作的稳定性
 - ◆ 阻性阳极Pad本身的不均匀性, 以及探测器入射窗不平等带来的影响
 - ◆ 周围Pad电荷扩散到了临近的没有电子学的Pad

RAGEM能量分辨率均匀性



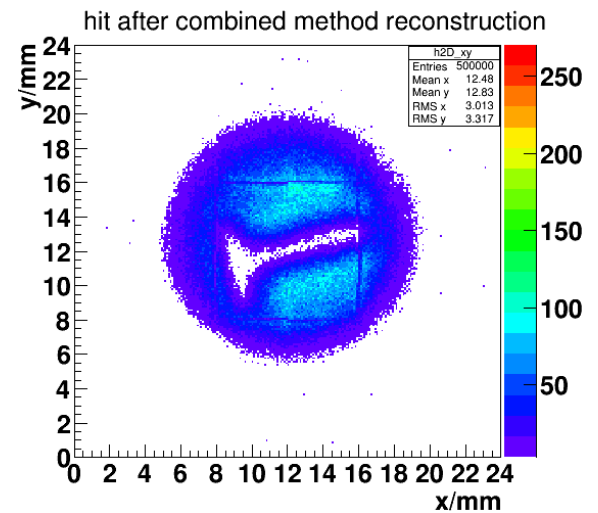
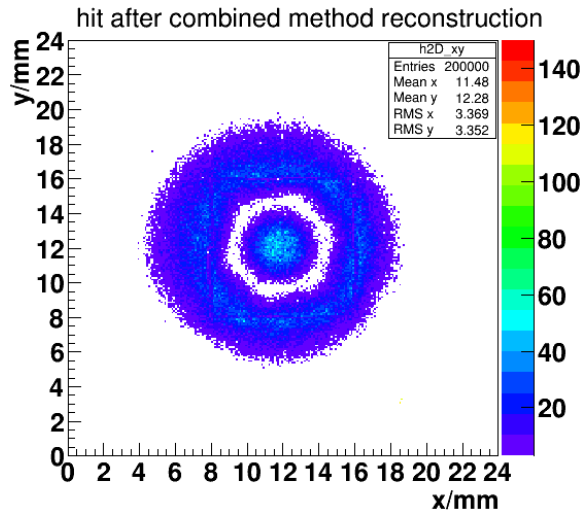
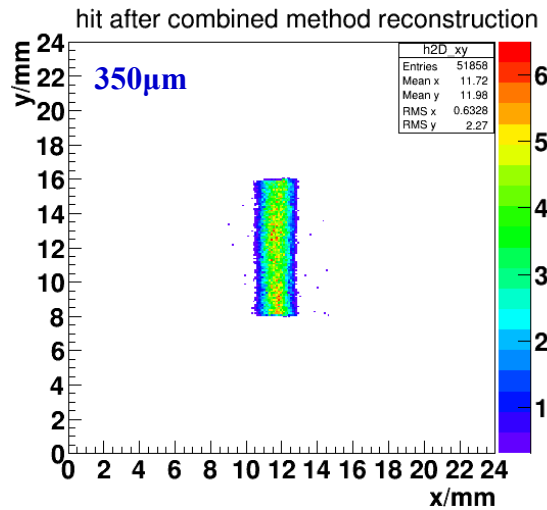
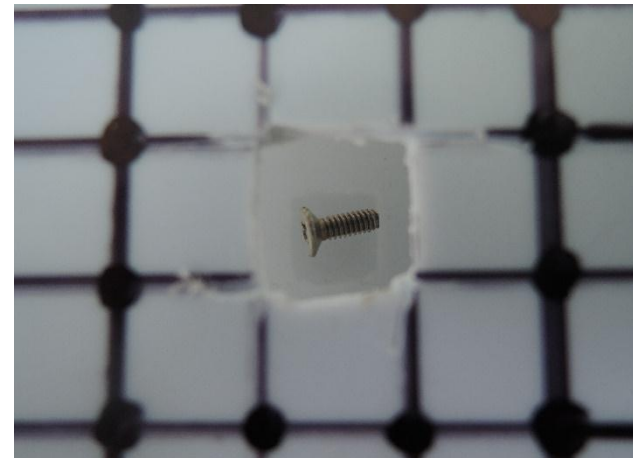
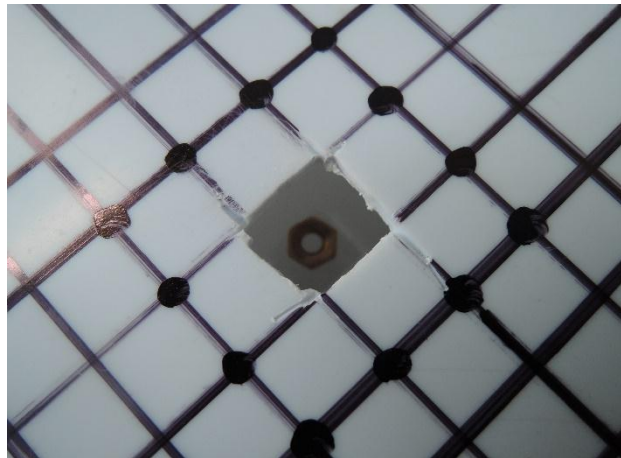
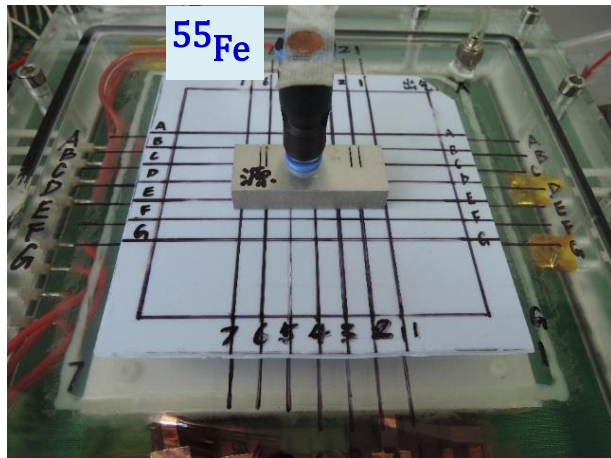
- 能量分辨率在**17%-20%**之间，气体探测器正常范围值

RAGEM增益稳定性



20140709日数据

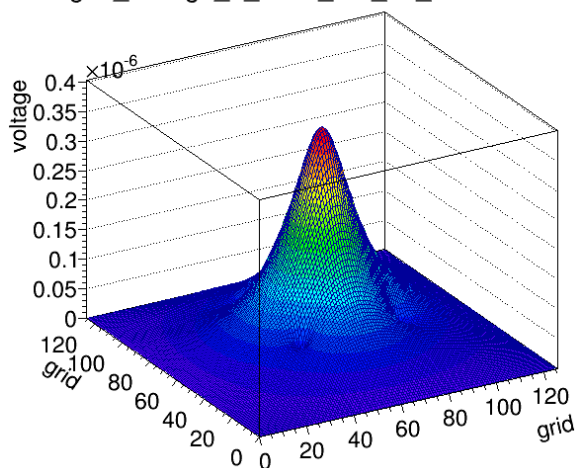
RAGEM初步成像结果



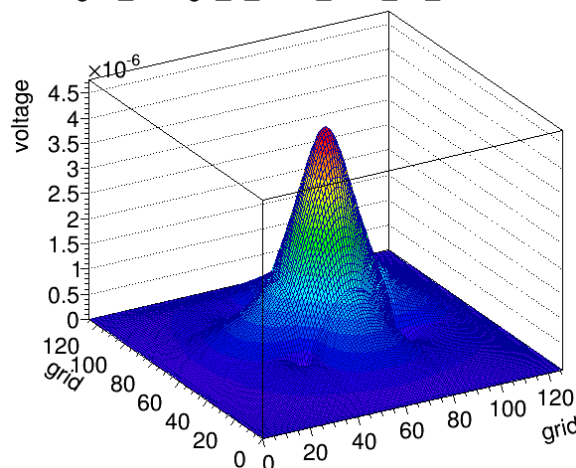
阻性阳极读出板参数研究

不同面电阻比值对电荷收集的影响

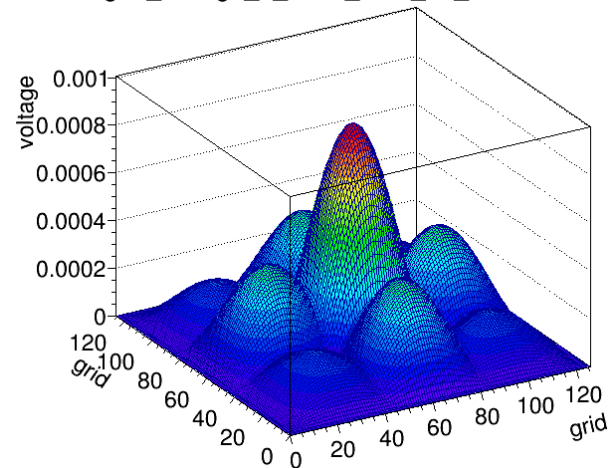
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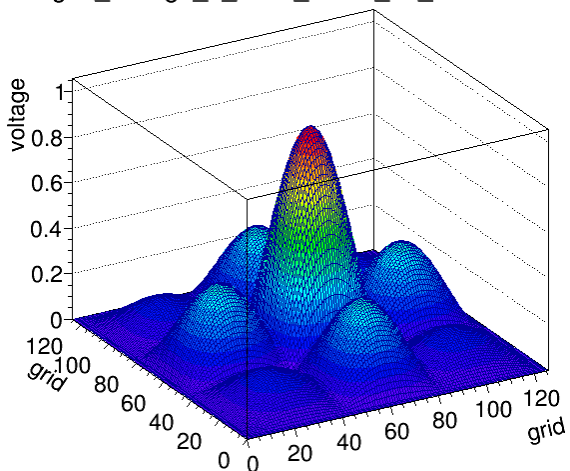
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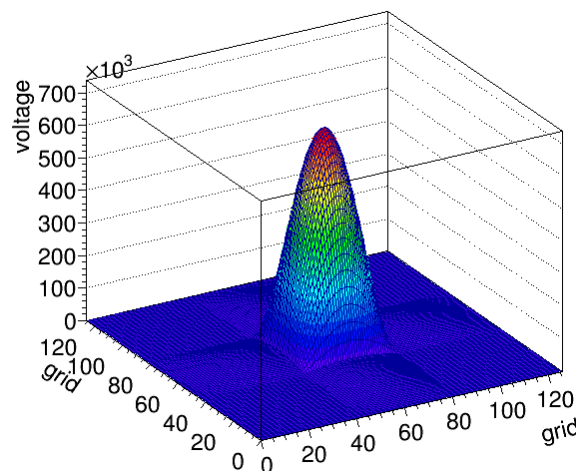
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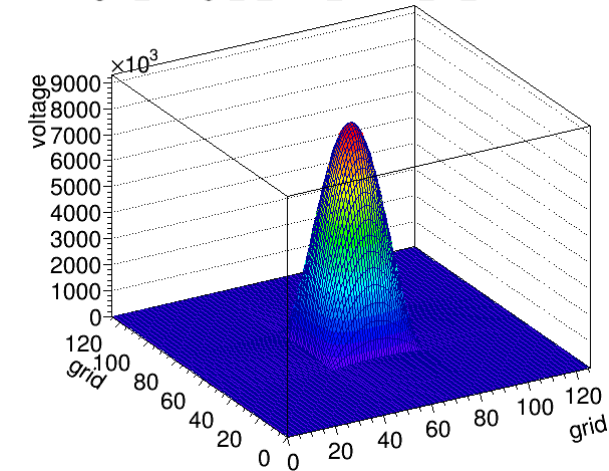
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grid_voltage_3_8mm_500-1_00_150ns-61ns



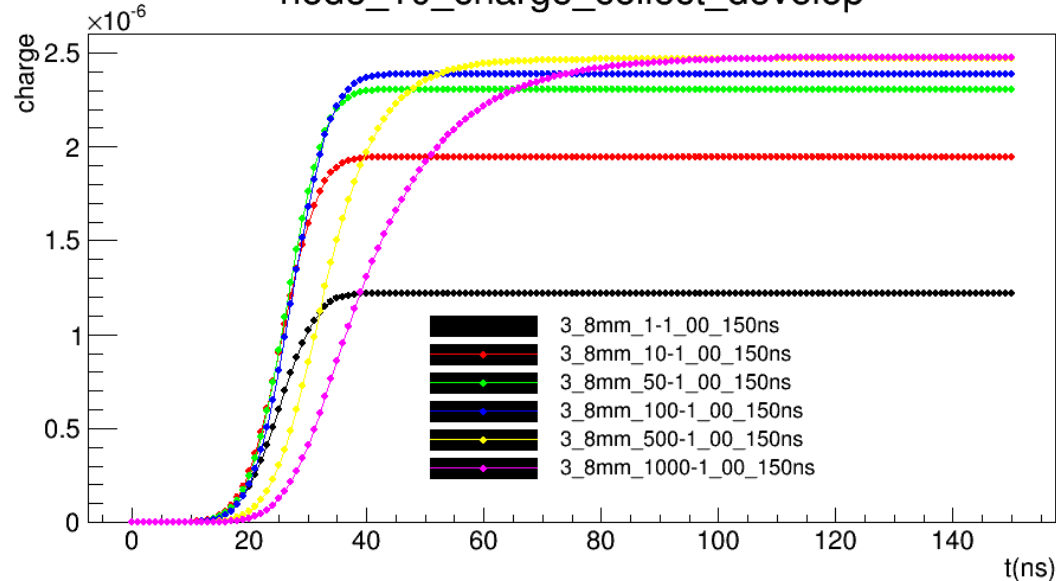
grid_voltage_3_8mm_1000-1_00_150ns-61ns



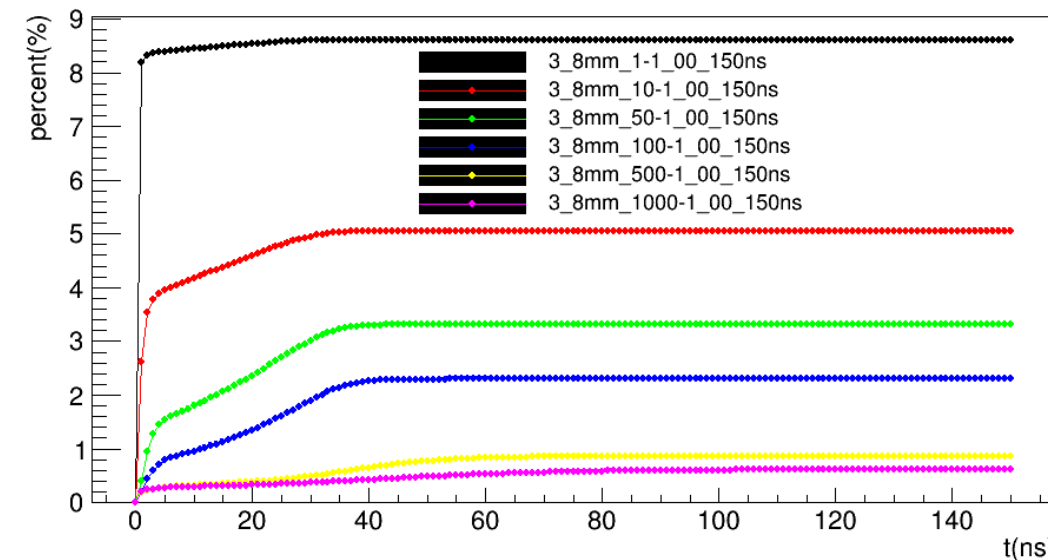
- 不同的面电阻比值，电荷扩散形状不同；且从**形状**上看，面电阻比值**越大**，电荷扩散的**越慢**
- 不同的面电阻比值，电荷收集时间不同；且从**幅值**上看，面电阻比值**越大**，电荷收集的**越慢**

不同面电阻比值对电荷收集的影响

node_10_charge_collect_develop



node_charge_loss_develop



条件:

- 面电阻比值: 不同(1:1–1000:1k Ω /□)
- Pad尺寸: 8mm
- 击中位置: Pad中心

结论:

节点电荷收集时间:

- ◆ 比值越大, 收集越慢
- ◆ 30ns 到 80ns

节点收集到的电荷:

- ◆ 比值越大, 收集越多
- ◆ 相差 2 倍

Pad电荷损失率:

- ◆ 比值越大, 损失率越小
- ◆ 0.5% 到 8.5%

比值太小

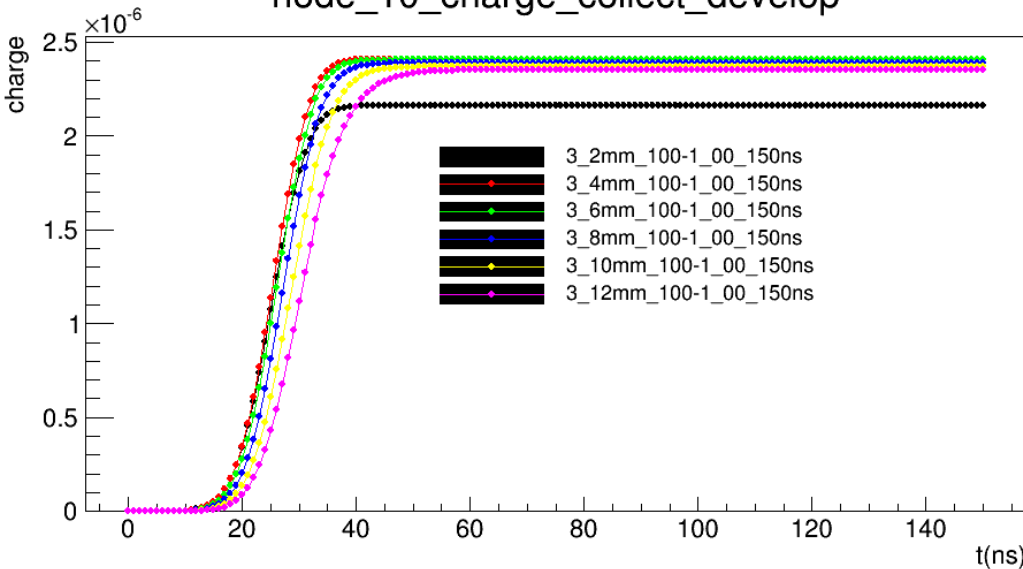
- ◆ 热噪声大, 影响位置分辨

比值太大

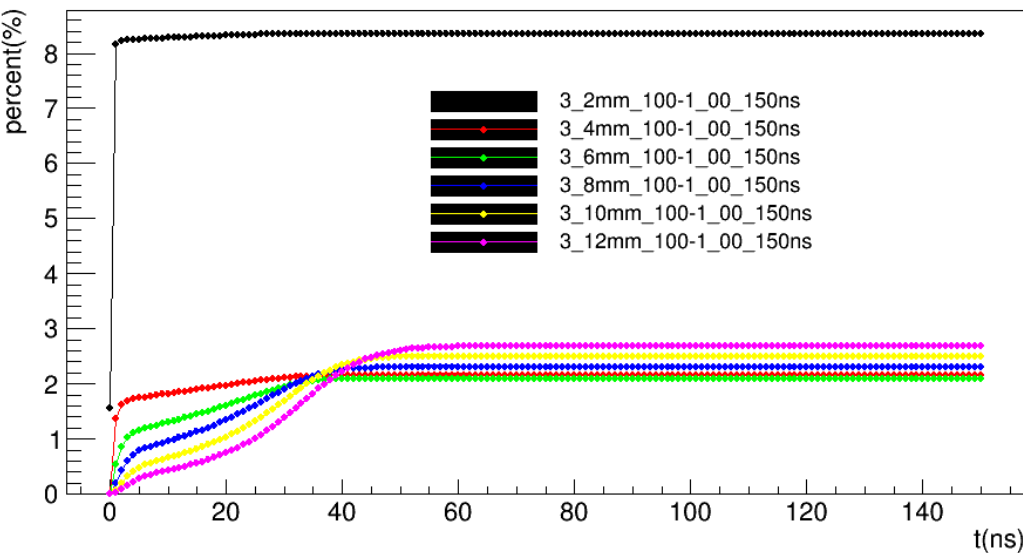
- ◆ 限制收集速率, 影响计数率

不同Pad尺寸对电荷收集的影响

node_10_charge_collect_develop



node_charge_loss_develop



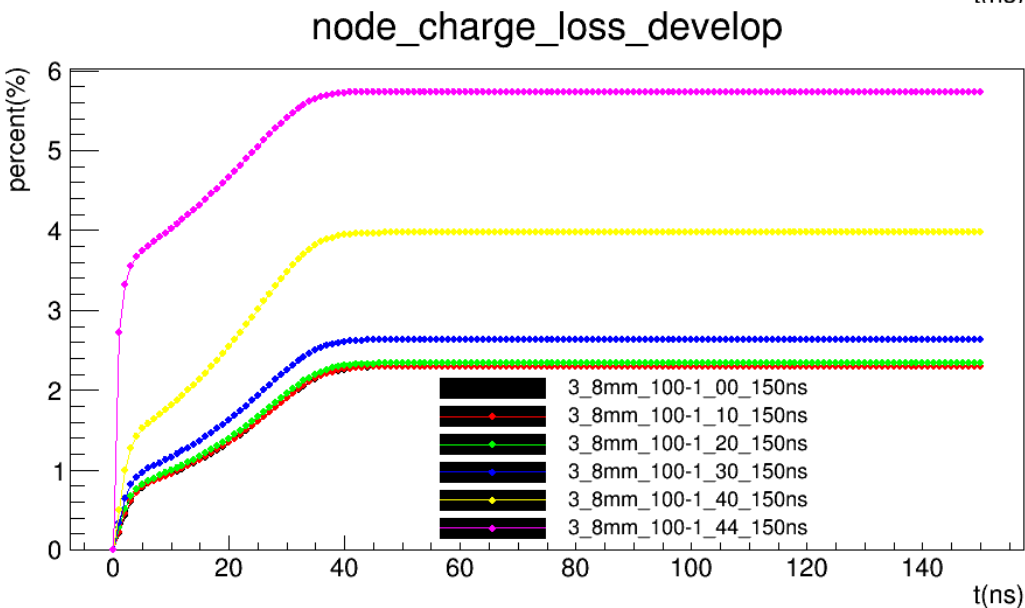
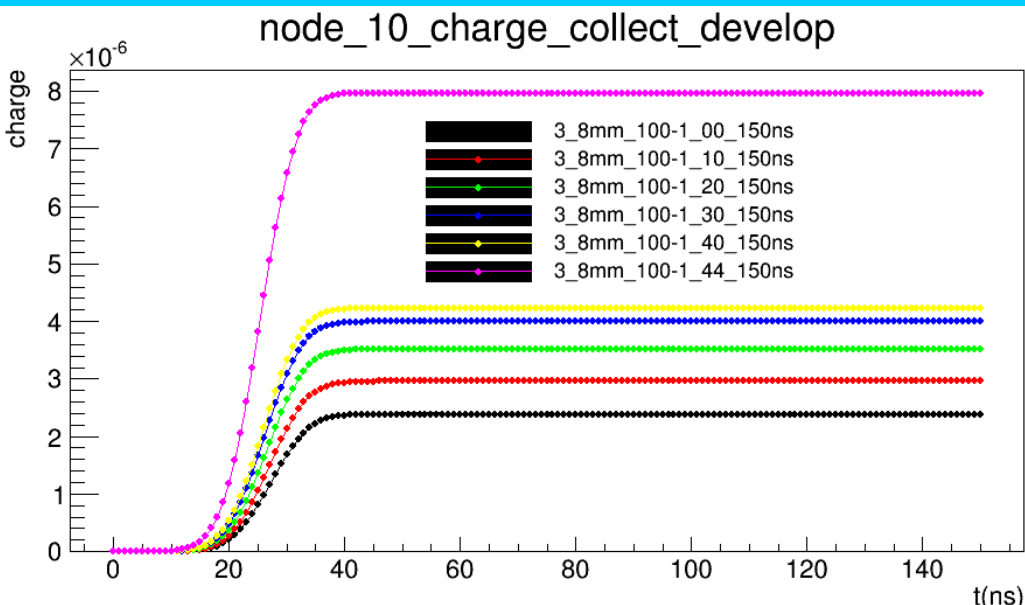
条件:

- 面电阻比值: **100:1k Ω /□**
- Pad尺寸: **不同 (2 - 8mm)**
- 击中位置: **Pad中心**

结论:

- 节点电荷收集时间:
 - ◆ 基本相同, 约为 **35ns**
- 节点收集到的电荷:
 - ◆ Pad越大, 收集越多
 - ◆ 相差 很少
- Pad电荷损失率:
 - ◆ Pad大, 损失少, 有变化
 - ◆ 2.5% 到 8.5%
- Pad尺寸影响位置分辨

不同击中位置对电荷收集的影响



条件:

- 面电阻比值: **100:1k Ω /□**
- Pad尺寸: **8mm**
- 击中位置: 不同(Pad中心到边缘)

结论:

- 节点电荷收集时间:
 - ◆ 基本相同, 约为 **35ns**
- 节点收集到的电荷:
 - ◆ 越靠近节点, 收集越多
 - ◆ 相差显著
- Pad电荷损失率:
 - ◆ 越靠近节点, 损失越多
 - ◆ 2.5% 到 6%
- 影响电荷收集时间的是面电阻比值
- Pad电荷损失并不显著, 即电荷多被所在Pad的节点收集
- 电荷扩散过程对信号总得收集时间的限制很小

总结与计划

总结与计划

● 总结

- 测试了探测器的均匀性，均匀性好于 8%
- 初步进行了成像实验，（需要好的准直器和准直粒子源）
- 计算了阻性阳极读出板的不同参数对电荷收集的影响，为探测器制作提供参考

● 计划

- 新的电子学
 - ◆ 全部电子学通道，约 13*13 道
- 新的原型机制作
 - ◆ 铝制室体
 - ◆ 测试不同参数的阻性阳极板对探测器性能的影响
- 模拟和重建算法的优化和改进
 - ◆ 位置分辨
 - ◆ 大面积，多Seed
 - ◆ 新的刻度方法
- X光机实验
 - ◆ 位置分辨
 - ◆ 成像

谢谢

Theory is when you know everything but nothing works.
Practice is when everything works but no one knows why.
Since I'm an experimenter, I suggest that you talk with a theorist if you really want to know why.